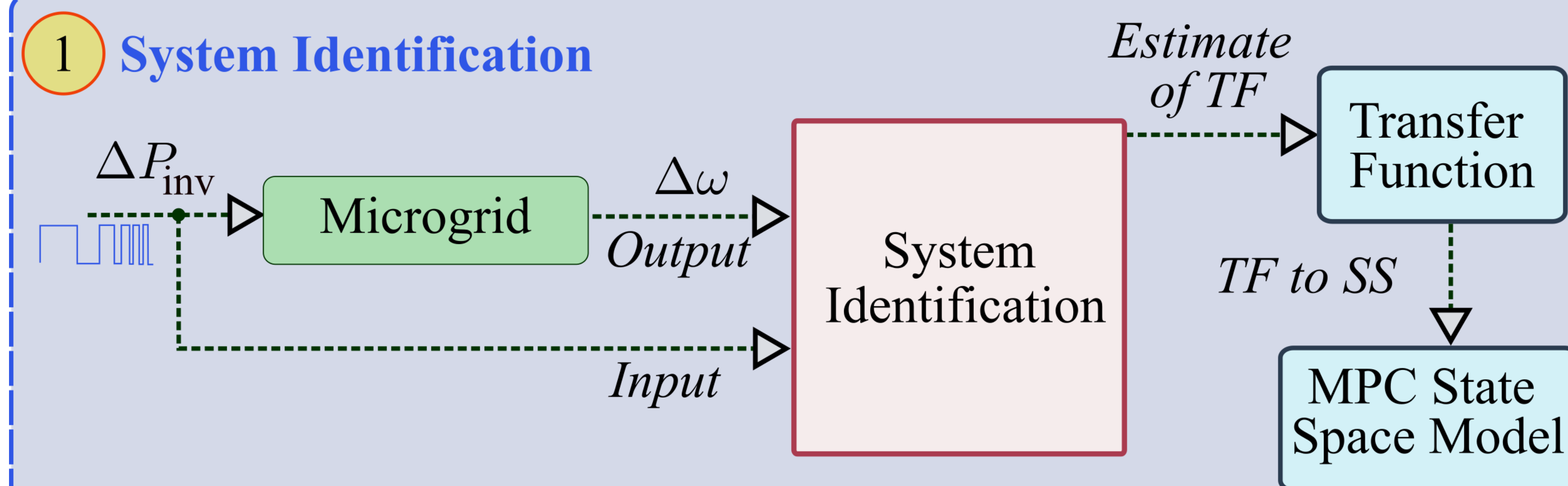


## Motivation and Objectives

- Model predictive control (MPC) based approach to achieve fast frequency response in ESS
  - Handles operational constraints and cost and flexible to adjust performance
  - Challenges: How to obtain accurate prediction model?
- Data-driven model : Builds mathematical model based on observed data
  - Without prior assumption of power system dynamics
- Contribution:
  - Design of data-driven modeling of a microgrid system
  - Implementation of data-driven MPC for fast-frequency support
  - Comparison with standard MPC (analytic model)

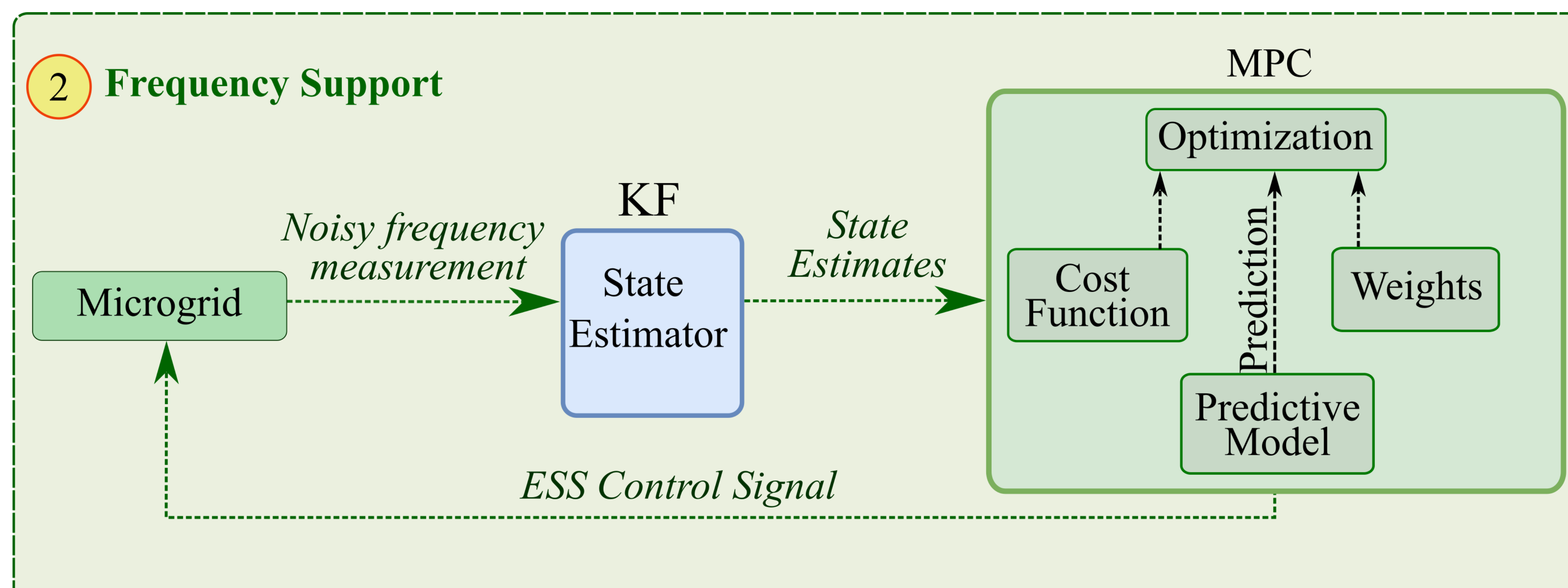
## Proposed Framework

### 1 System Identification



- Data-driven system identification on Cordova benchmark<sup>[1]</sup>
- Square log chirp signal to perturb the system
  - Amplitude: 0.05 p.u., Frequency range: 0.02Hz-3Hz, Time period = 250s
- Collect input and output data, estimate transfer function(TF)
- Change into state-space model and use the estimated model for MPC

### 2 Frequency Support



- Use Kalman filter (KF) to estimate states
- Use MPC to generate control signal for ESS
- Comparison of two predictive models for frequency support
  - KF tuned to perform similar results
- At  $t=70s$ , step-change of load from 0.5 p.u. to 0.7 p.u.

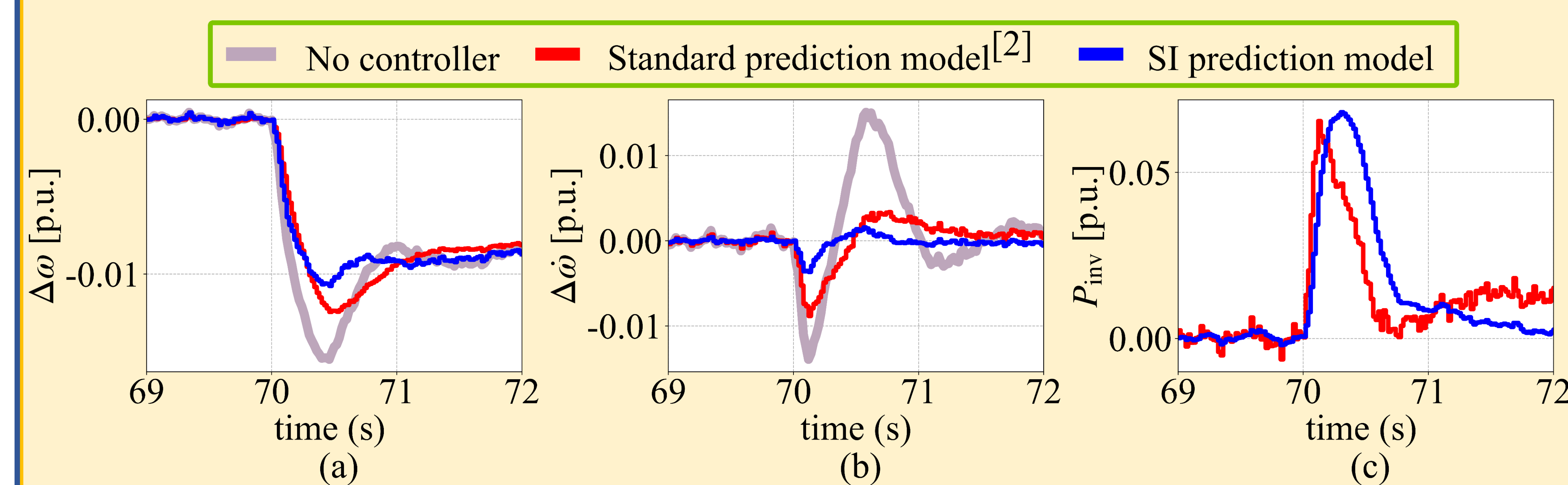
## System Identification(SI) MPC

SI estimates predictive model for MPC

## Standard MPC

State space model with known system parameters

## Simulation Result and Analysis



- The model training percent fit 87% with the true data
- Validated with test data (square wave)
- SI-based MPC provides a lower frequency deviation and rate of change of frequency (ROCOF)
- Fig. c shows inverter power → peak difference insignificant
  - SI-based MPC uses more inverter power
- SI-based model utilizes slightly more power to reduce the frequency deviation and ROCOF

## Conclusion and Future Work

- Implemented SI in MATLAB/Simulink to predict the model of a microgrid
- Result showed that the SI-based MPC → suitable model
  - Lower frequency deviation and ROCOF
- Limited bandwidth of PLL limits the frequency range of input signal
- SI conducted offline
- Potential for online SI
  - Collect data in real time and estimate on slower time scale
- Generalize SI methodology for different test systems and conditions
- Perform state-of health of microgrid

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## References

- [1] U. Tamrakar, D. A. Copp, T. Nguyen, T. M. Hansen and R. Tonkoski, "Optimization-Based Fast-Frequency Estimation and Control of Low-Inertia Microgrids," in *IEEE Transactions on Energy Conversion*, vol. 36, no. 2, pp. 1459-1468, June 2021, doi: 10.1109/TEC.2020.3040107.
- [2] A. Rai, N. Bhujel, T. M. Hansen, R. Tonkoski, and U. Tamrakar, "Implementation of model predictive control for frequency support in a real-time digital simulator," in *IEEE Electrical Energy Storage Application and Technologies Conference (EESAT)*, 2022, pp. 1-5.