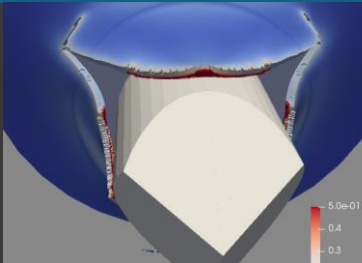
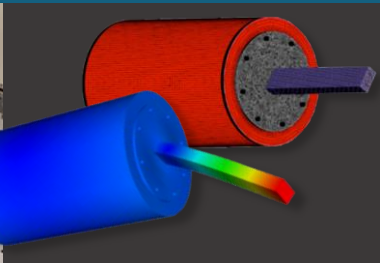
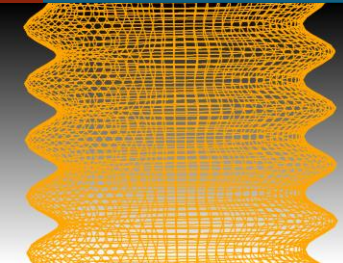


Parameterized Friction Modeling With Optimized User Constructs



Robert Duong, Andrew Slezak, Chris Jawetz

August 8, 2023

Our Team



Robert Duong



Andrew Slezak



Chris Jawetz

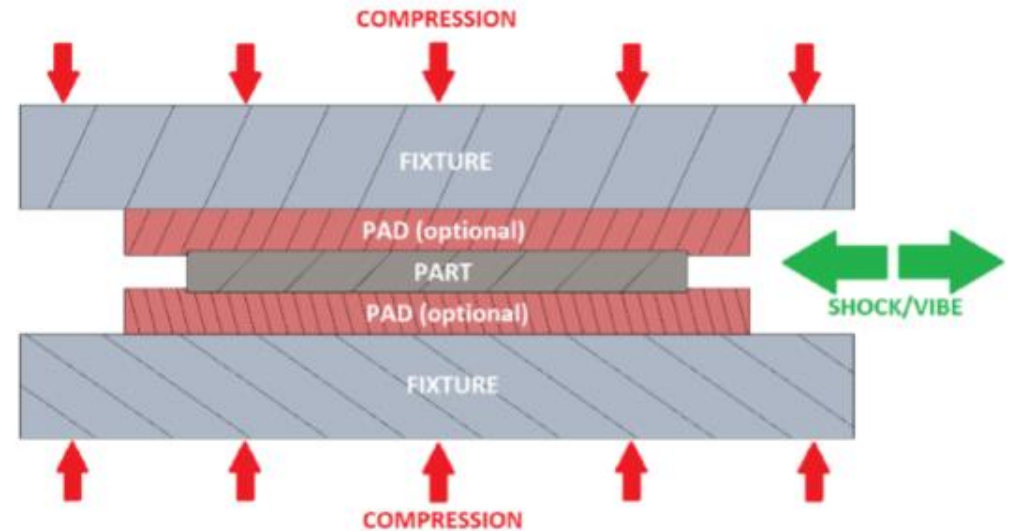


TEXAS TECH
UNIVERSITY.



Problem

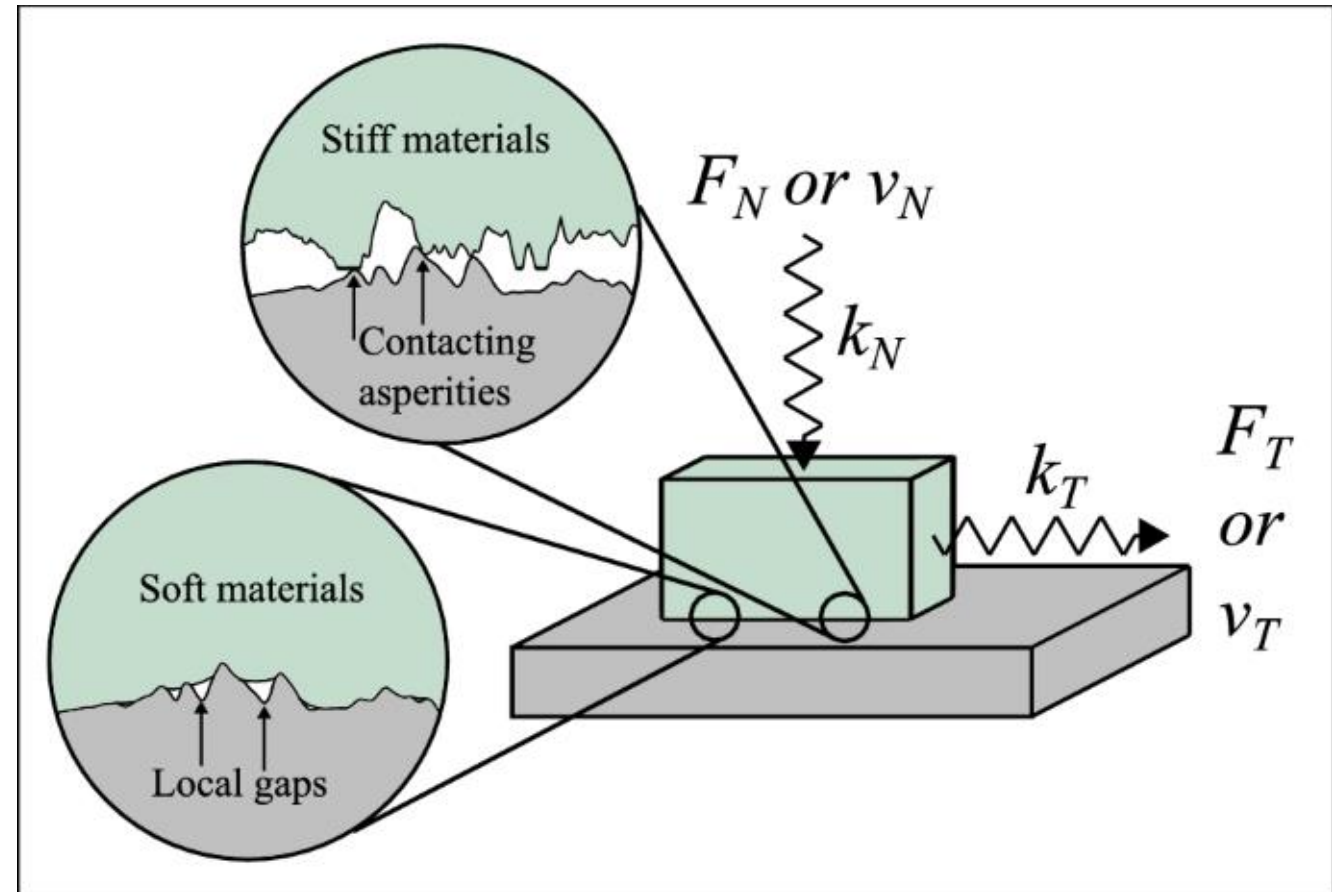
- Many systems hold components in place through clamping
- Friction is notoriously difficult to model
- Determining required clamping often takes many cycles of destructive testing



Compliant Friction Modeling



- Micro scale surface features change friction coefficients
- True surface area increases as compression increases
- Compliant materials deform and “fill” voids from surface features
- FEA required for simulation



[1]

Our Project



Model

- Build a 3D model in SolidWorks
- Mesh using CUBIT
- Simulate in SIERRA under different conditions

Build design advisor

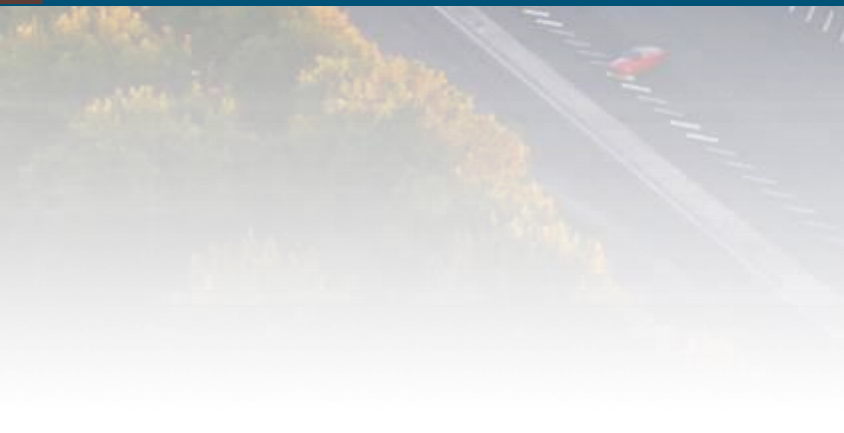
- Import user conditions
- Determine successes and failures
- Find regions of success, failure and uncertainty

Test and verify

- Test at simulated points
- Test at high preloads based on prediction function
- Input test data into design advisor for comparison



Simulation & Modeling



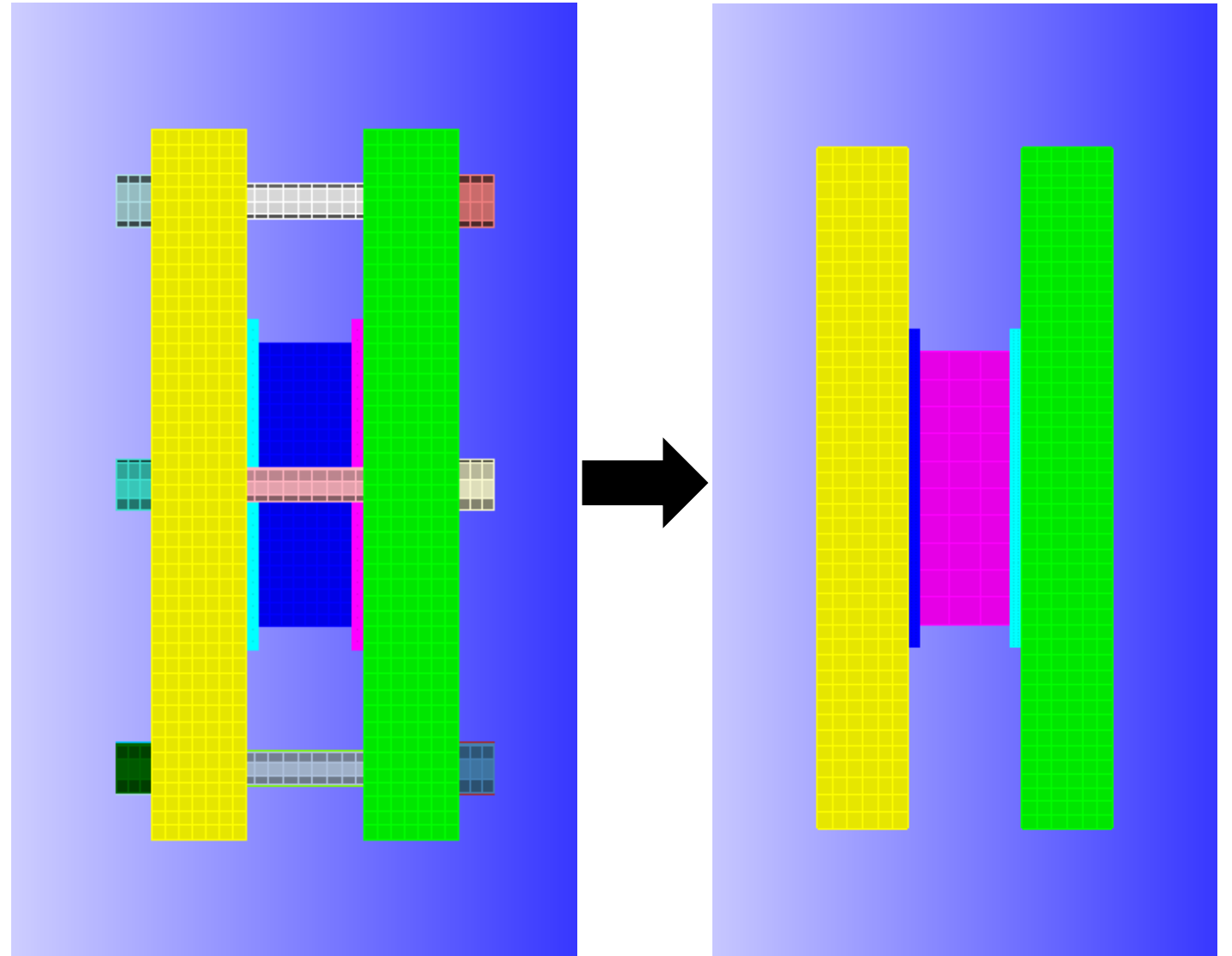
Simulation Parameters



- Efficiency of simulations were paramount
- Pad deformation is critical to the validity of the simulations
- Hundreds of simulations required
 - Sweep over geometries, pad materials, and compressions
 - Automated through Python scripts

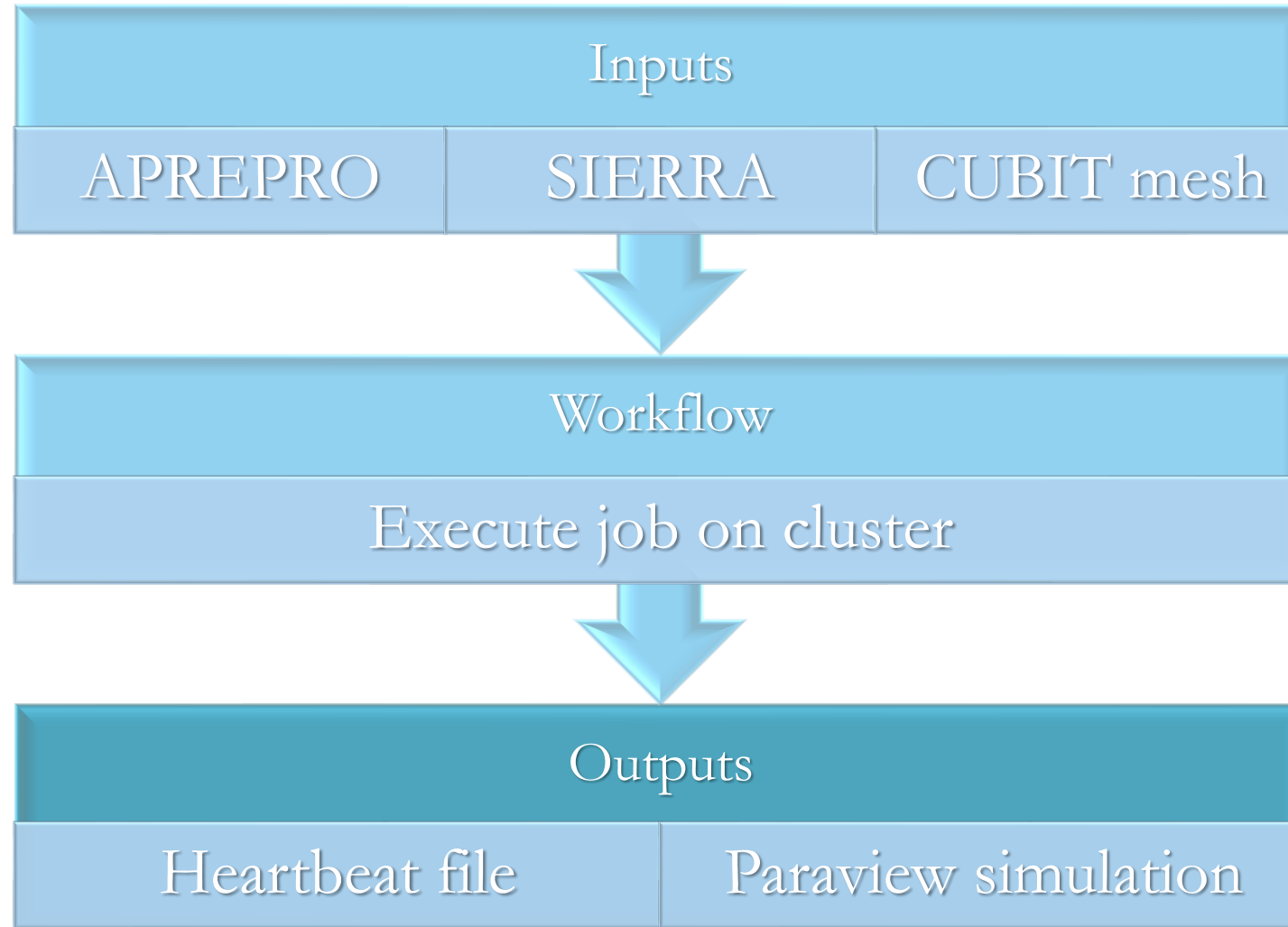
Simplified Geometry

- Model on right was used for bulk simulations
- Verified against the exact model for stress distribution
- Allowed for 3x timestep size

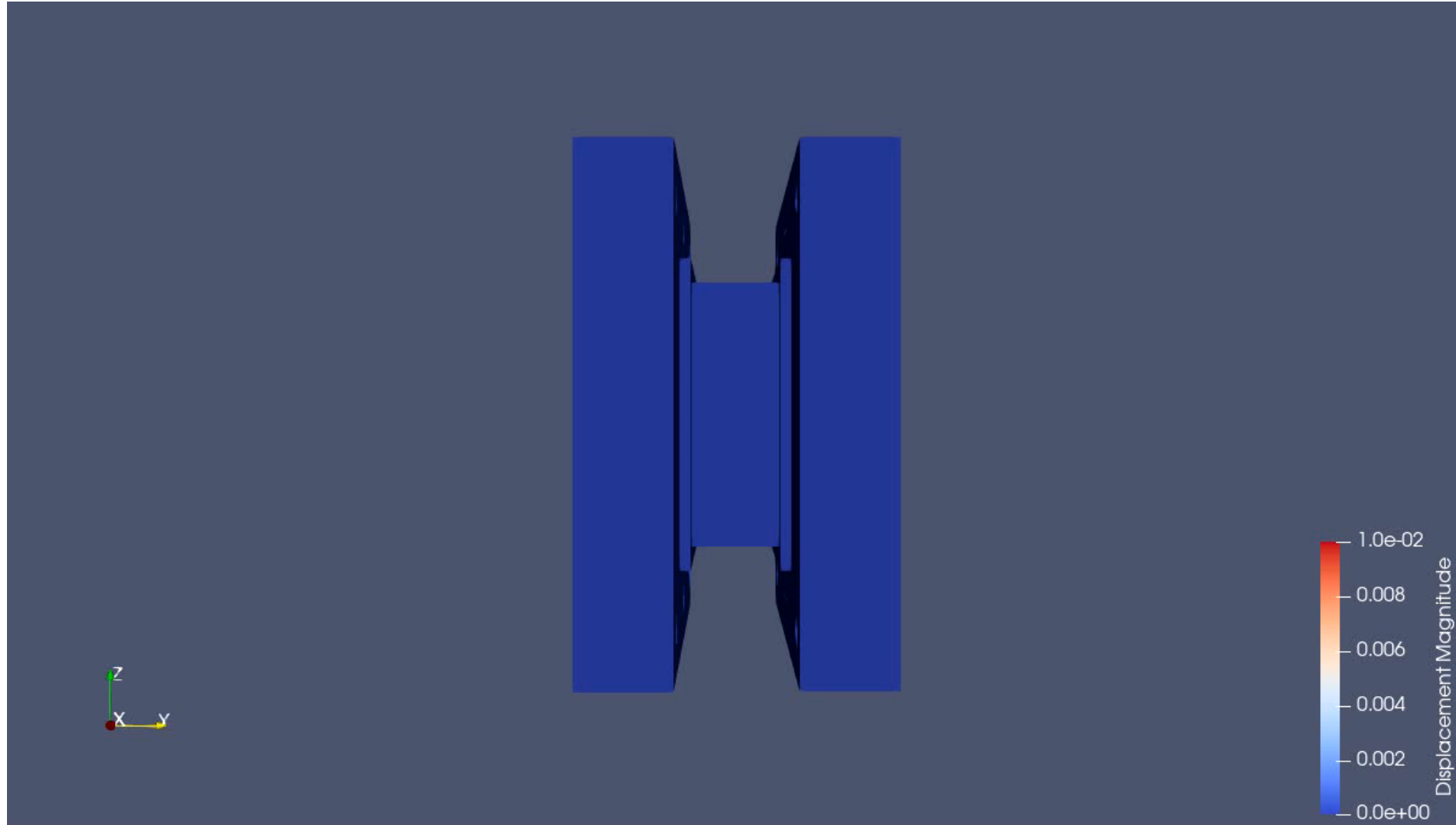




Simulation Workflow

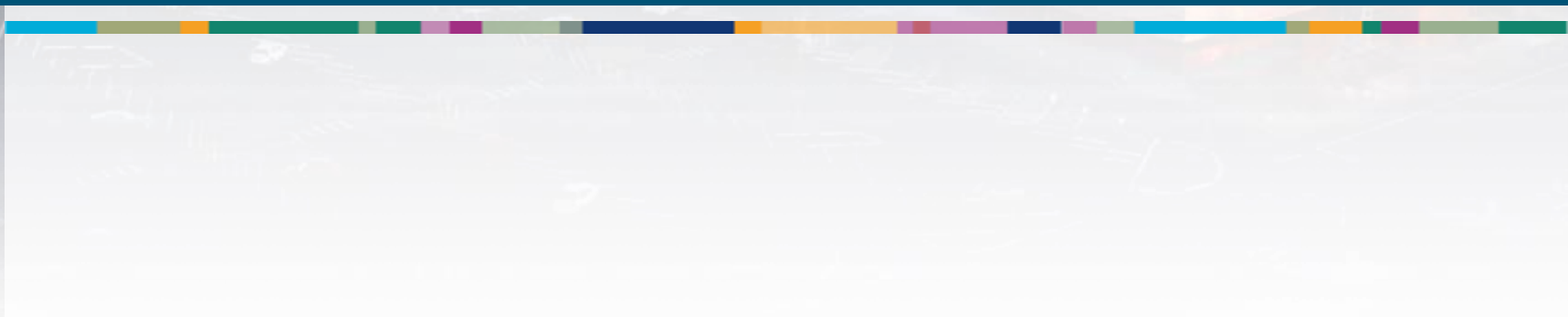


Simulation Results





Design Advisor



Design Advisor Simplified Overview



Inputs

- Simulated data
- User input data
- User fail criteria
- Requested output graphs

Data processing

- Import principal simulation data
- Determine maximal successes & minimal fails from failure criteria

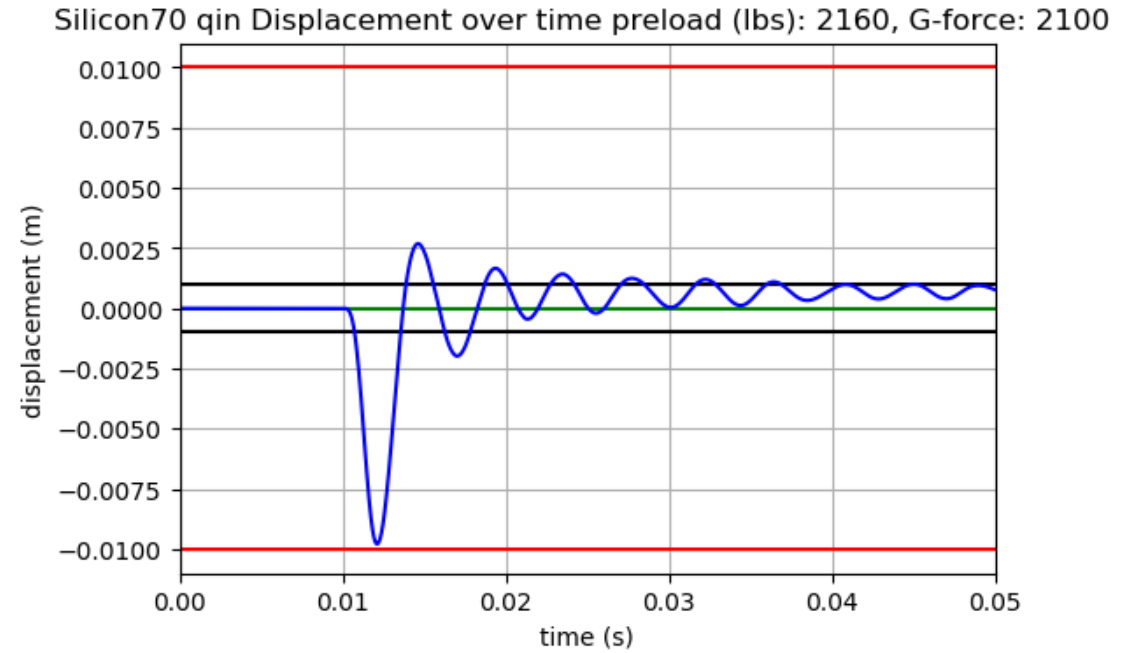
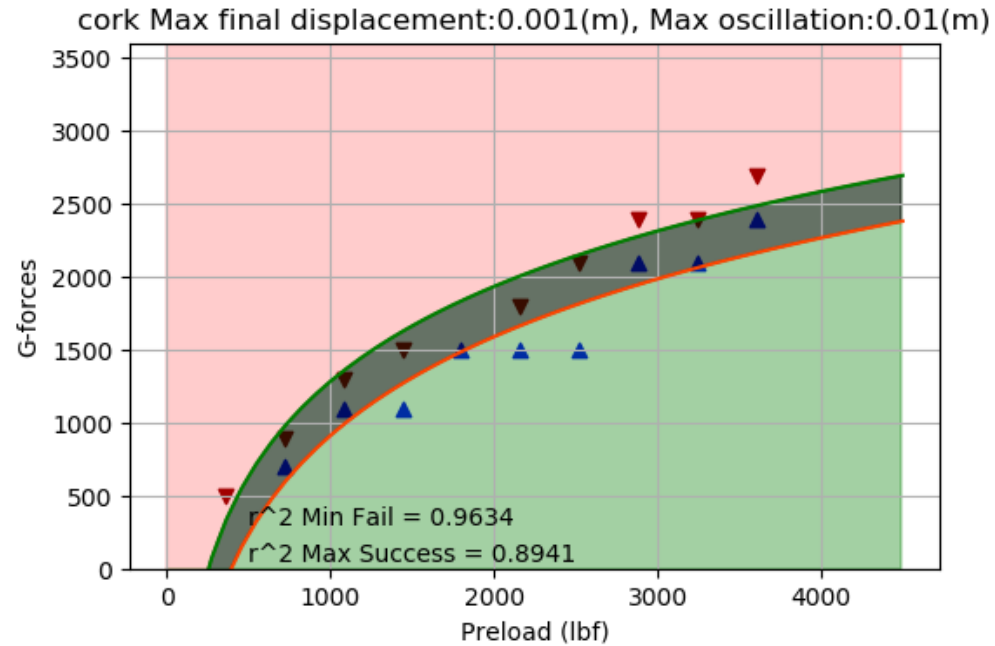
Optional data processing

- Check additional requested graphs
- Import secondary simulation data
- Apply failure criteria

Outputs

- Plot best fit success & failure functions
- Plot failure criteria against displacement
- Save all figures to host computer

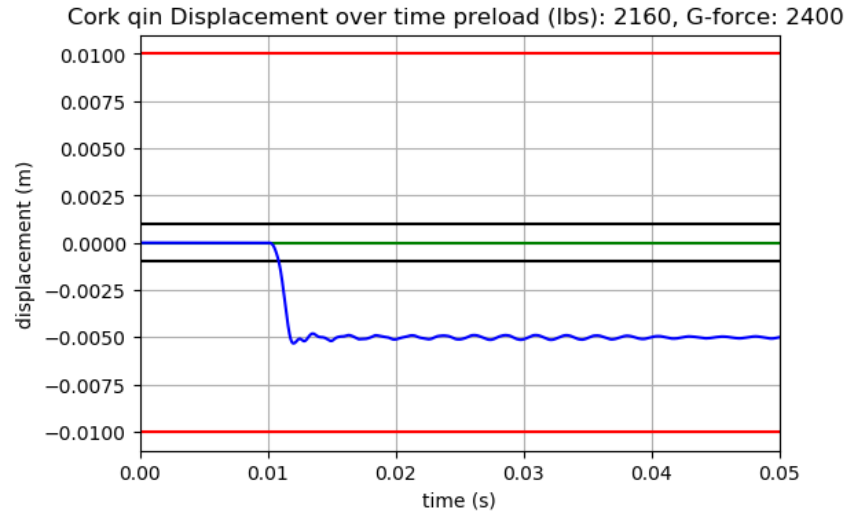
Design Advisor Outputs



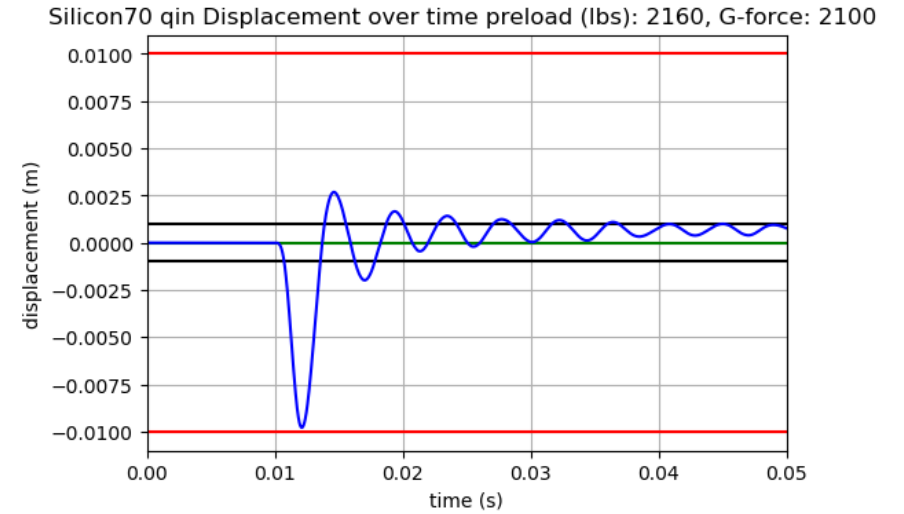
Displacement Over Time



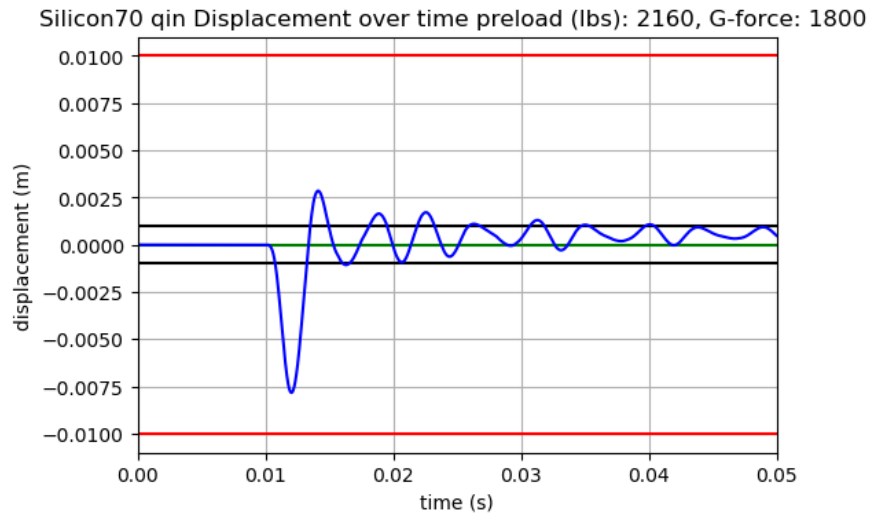
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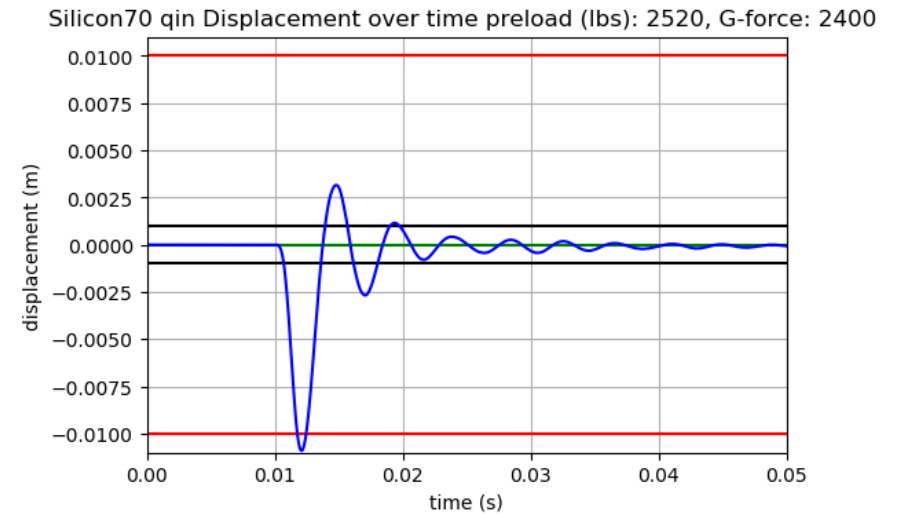
58



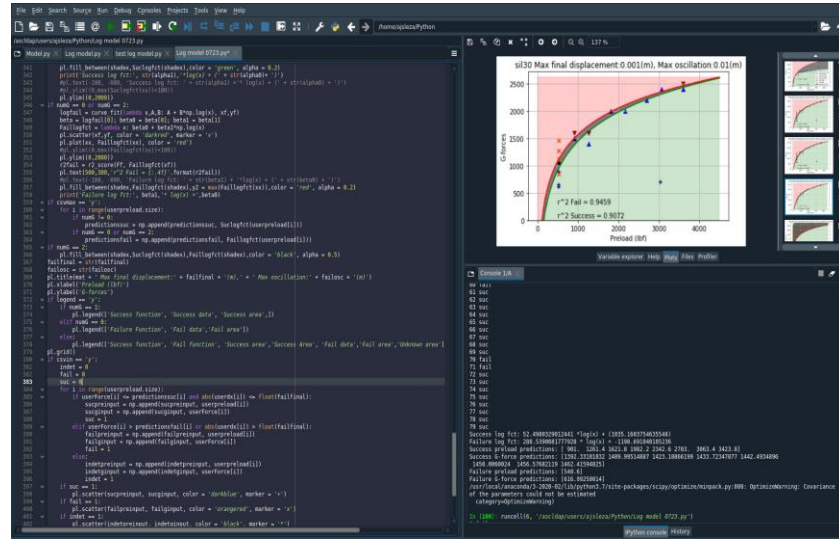
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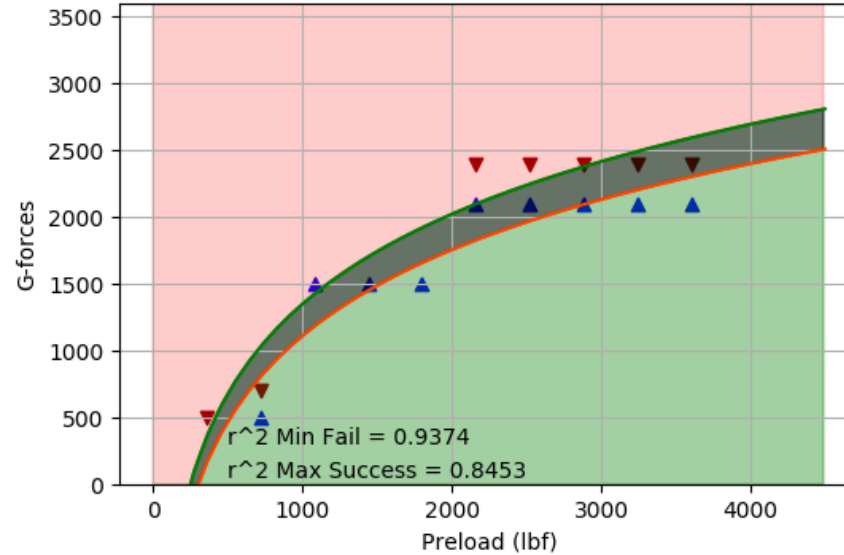
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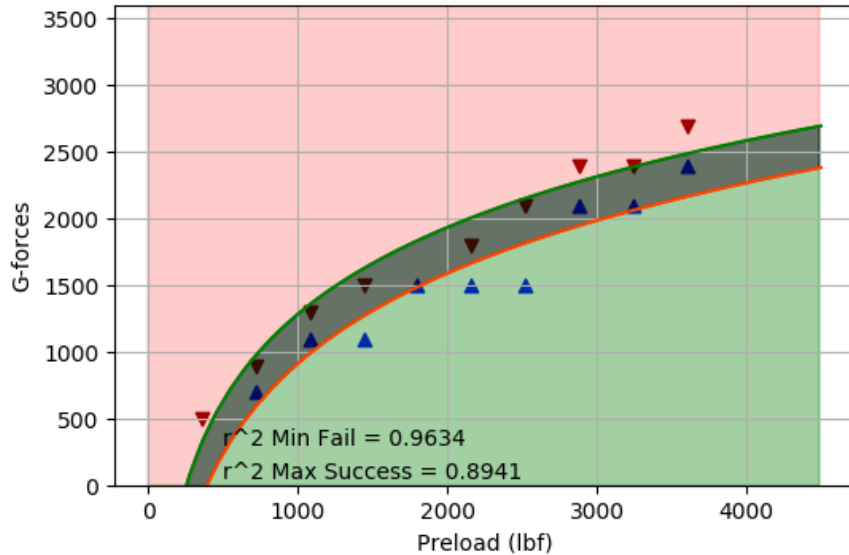
Design Advisor



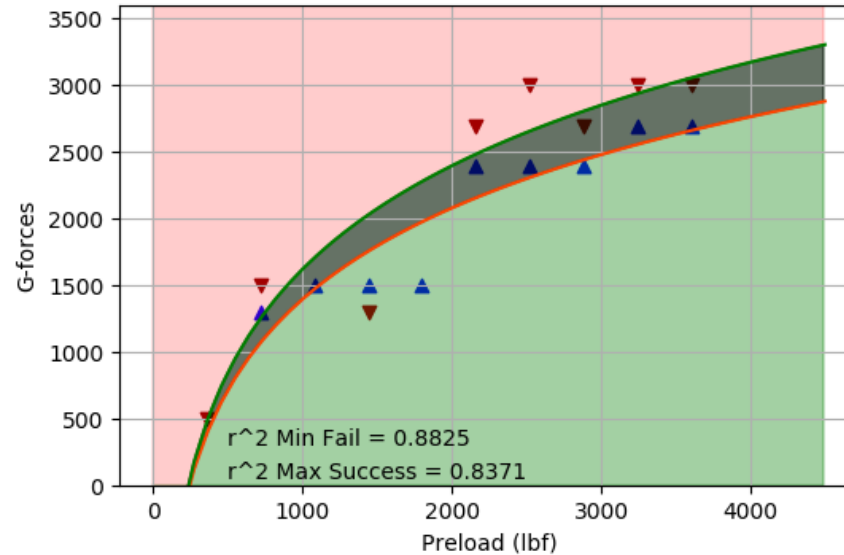
silicon70 Max final displacement:0.001(m), Max oscillation:0.01(m)



cork Max final displacement:0.001(m), Max oscillation:0.01(m)

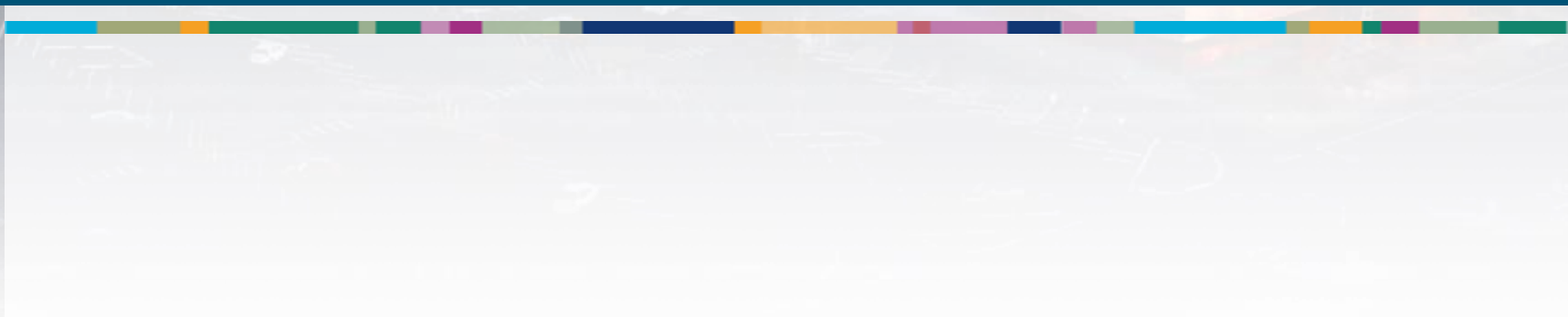


silicon30 Max final displacement:0.001(m), Max oscillation:0.01(m)

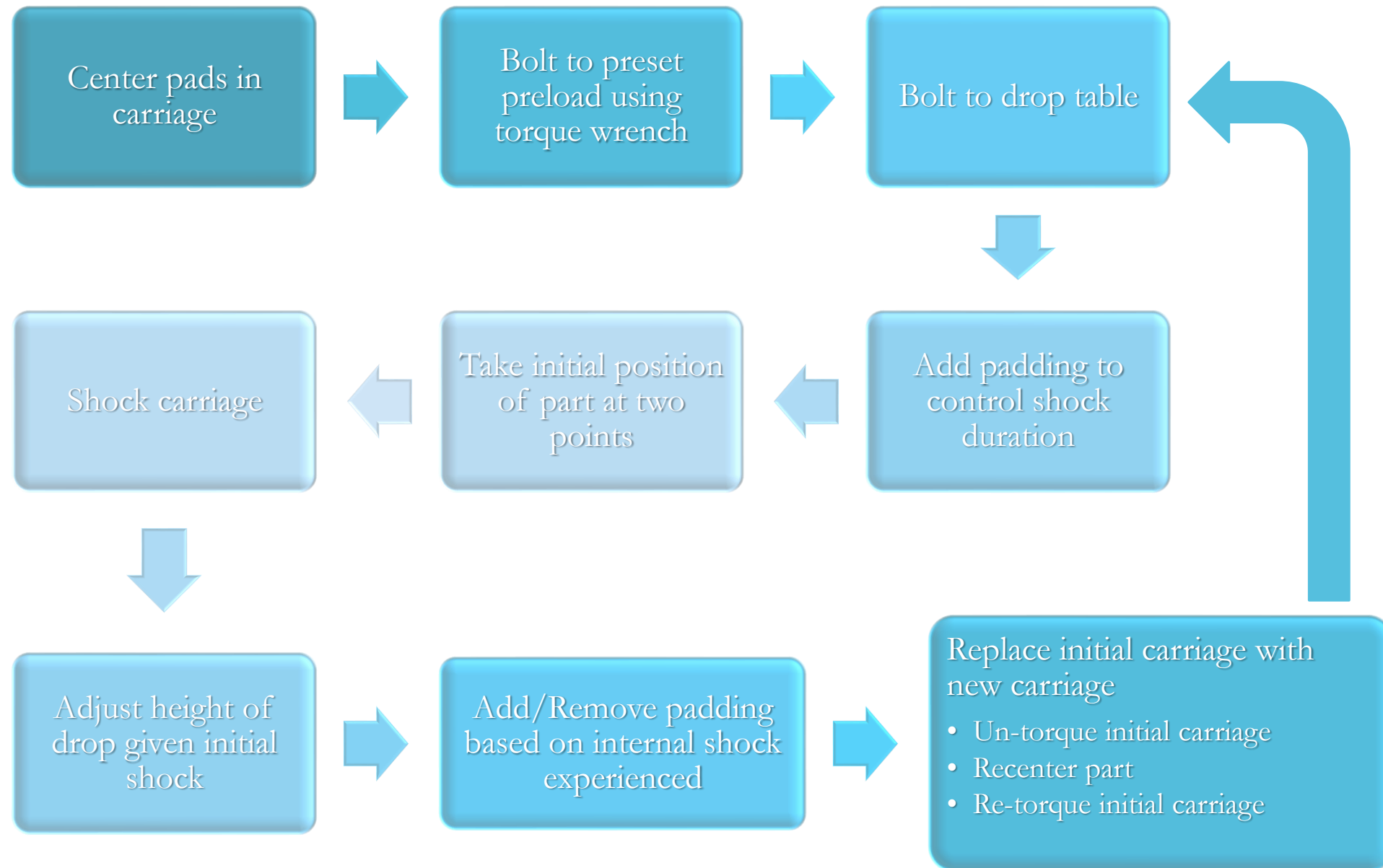




Verification & Testing



Test Methodology



Data Collection

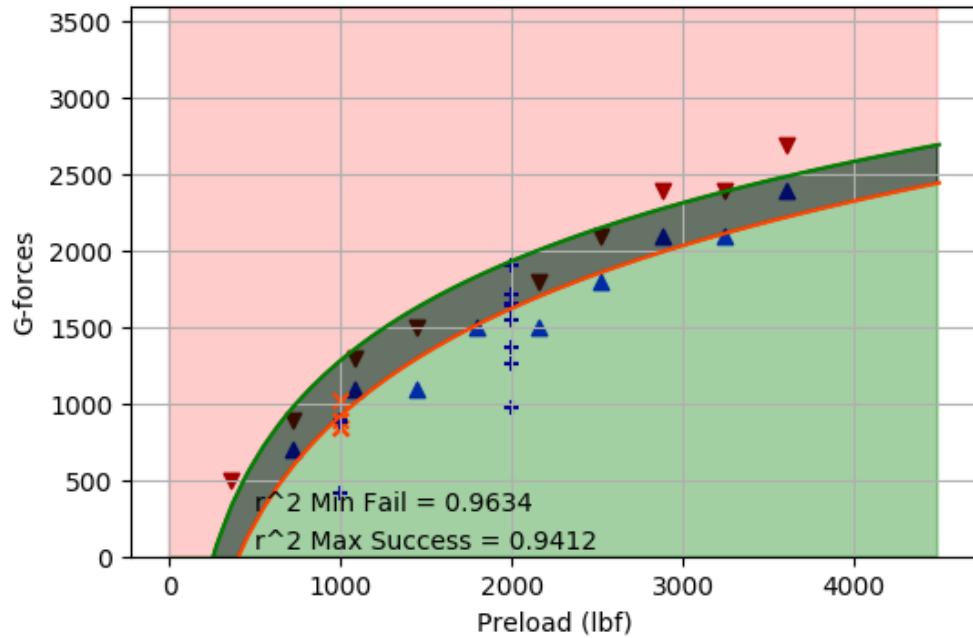


- High speed video
 - Displacement over time
 - Pad deformation and slip
- Accelerometers
 - Part kinematics
 - Time dependent, quantitative data
- Digital Calipers
 - Precise final displacement

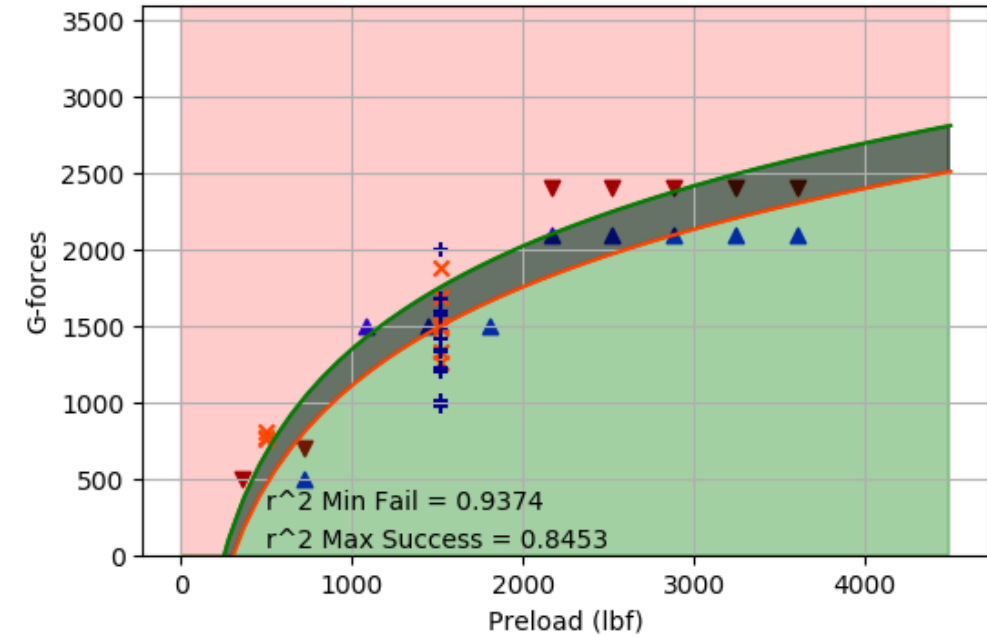


Test Results

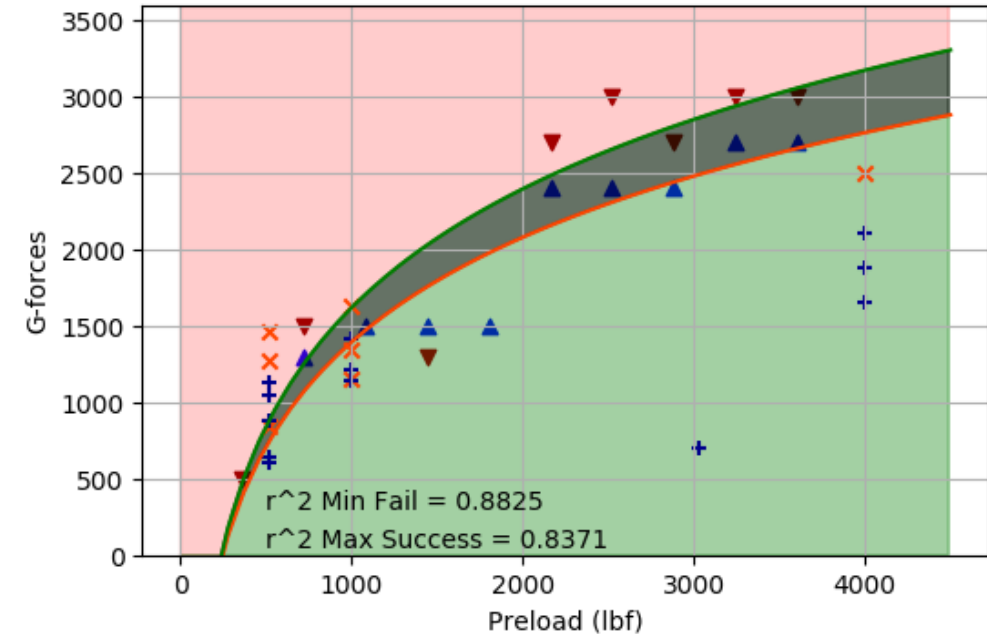
Cork qin max final displacement: 1 (mm), max oscillation: 10 (mm)



Silicon70 qin max final displacement: 1 (mm), max oscillation: 10 (mm)

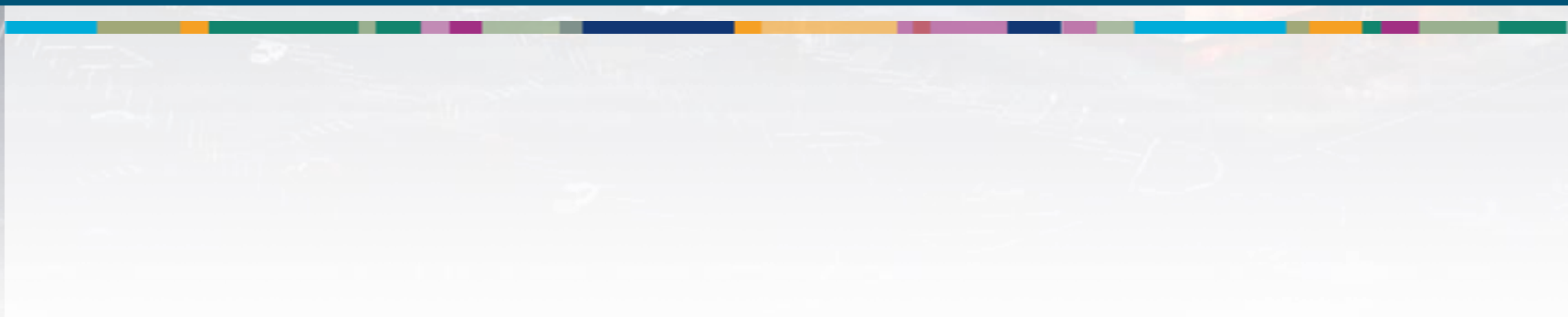


Silicon30 qin max final displacement: 1 (mm), max oscillation: 10 (mm)





Limitations & Future Research



Limitations



Simulation Limitations

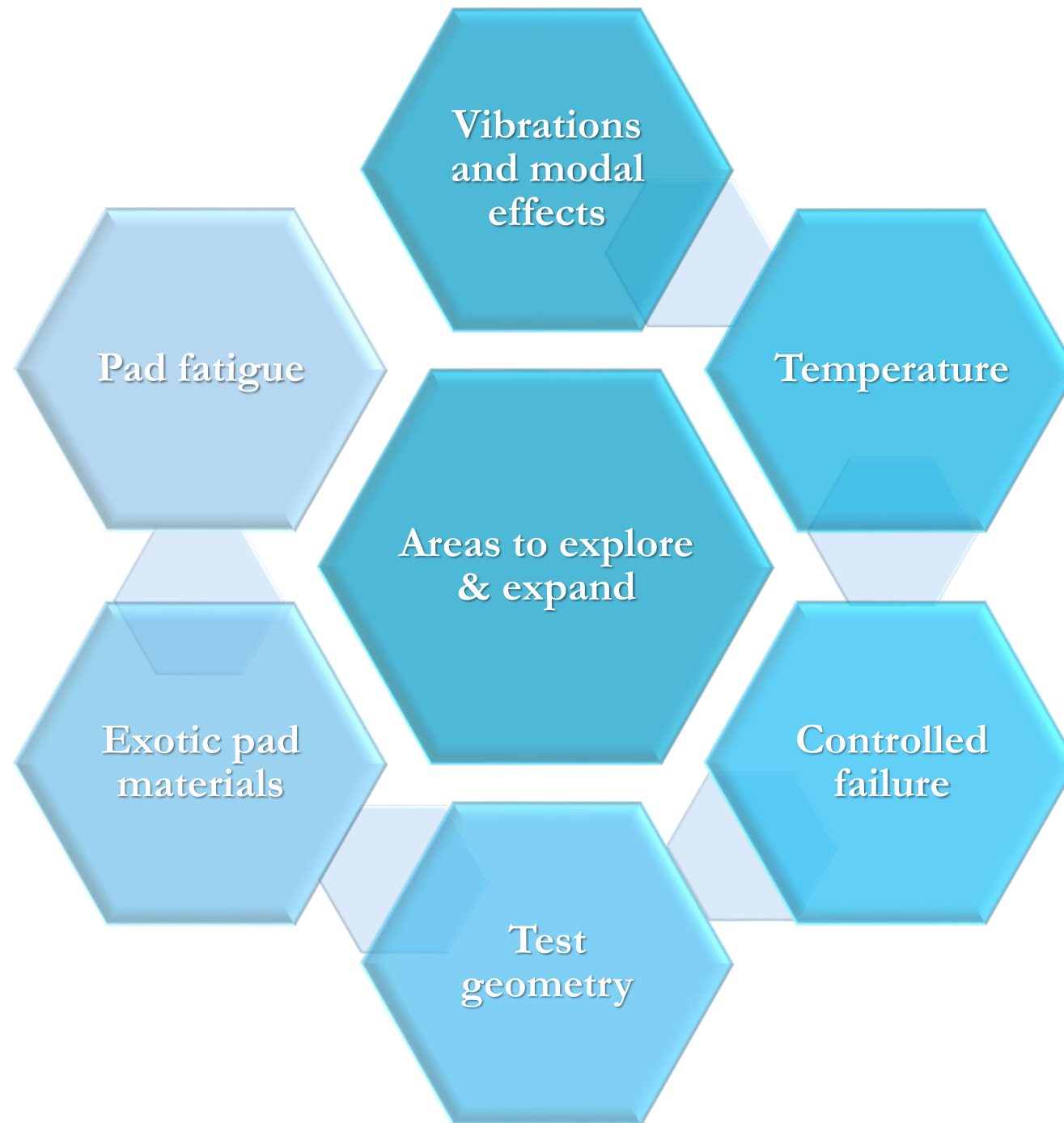
- More rotation in plates than observed in testing
- μ_s changes based on compression
- Deterministic simulation of stochastic process

Advisor Limitations

- Maximum success point dependent on range swept
- Oscillations do not always terminate in time
- Cannot predict specific displacements

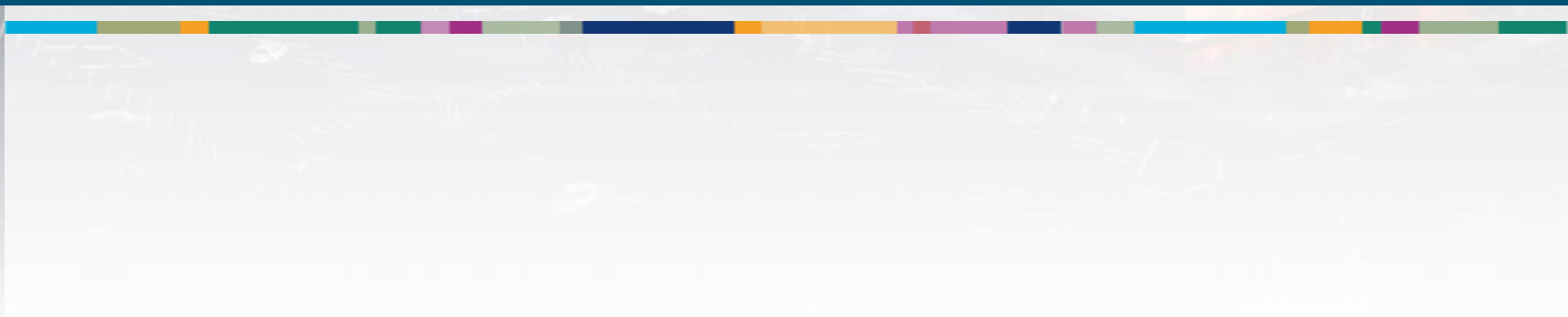
Test Limitations

- Pulsed shock duration is inconsistent
- Bolts lose compression after shock
- Shock amplitude is inconsistent and infeasible to predict a priori





Q&A



Acknowledgments



- NOMAD team
 - Debby Fowler
 - Brooke Allensworth
 - Jesse Powers
- Mentors
 - Greg Neugebauer
 - Wesley Greenwood
 - Neal Hubbard
 - Ramon Reyes
- Special thanks to John Mersch for his help with Dakota

References



[1] Weber, B., Scheibert, J., de Boer, M.P. *et al.* Experimental insights into adhesion and friction between nominally dry rough surfaces. *MRS Bulletin* **47**, 1237–1246 (2022).

<https://doi.org/10.1557/s43577-022-00464-6>

[2] Kogut, L., and Etsion, I. (January 13, 2004). "A Static Friction Model for Elastic-Plastic Contacting Rough Surfaces ." ASME. *J. Tribol.* January 2004; 126(1): 34–40.

<https://doi.org/10.1115/1.1609488>

[3] Yang, J., and Komvopoulos, K. (April 7, 2005). "A Mechanics Approach to Static Friction of Elastic–Plastic Fractal Surfaces ." ASME. *J. Tribol.* April 2005; 127(2): 315–324.

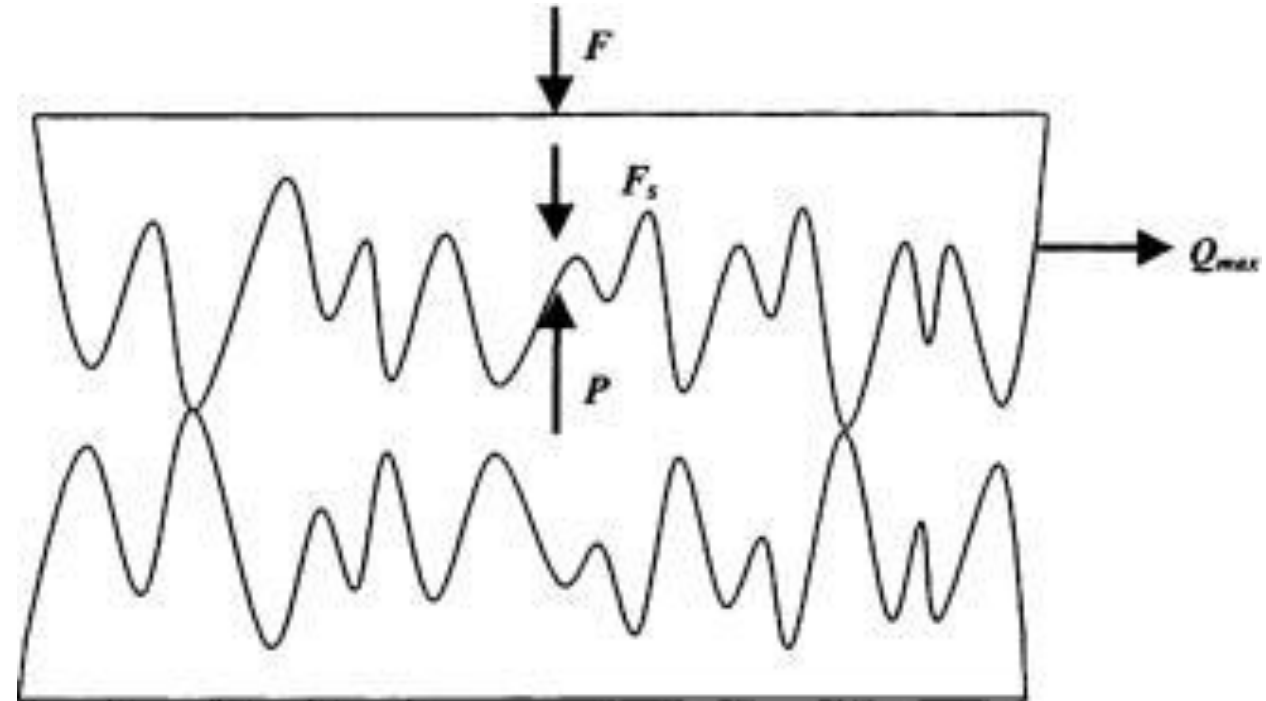
<https://doi.org/10.1115/1.1828080>

[4] Risch, Brian & Fallahmohammadi, Ehsan & Anderson, Nick. (2018). Structurally and Environmentally Robust Flexible Ribbon for High Fiber Density Cables Compatible with Mass Fusion Splicing.

Friction Modeling With Rigid Materials



- Dependent on micro and nano scale surface features
- True surface area changes friction coefficient
- Compression independent
- FEA often required for simulation

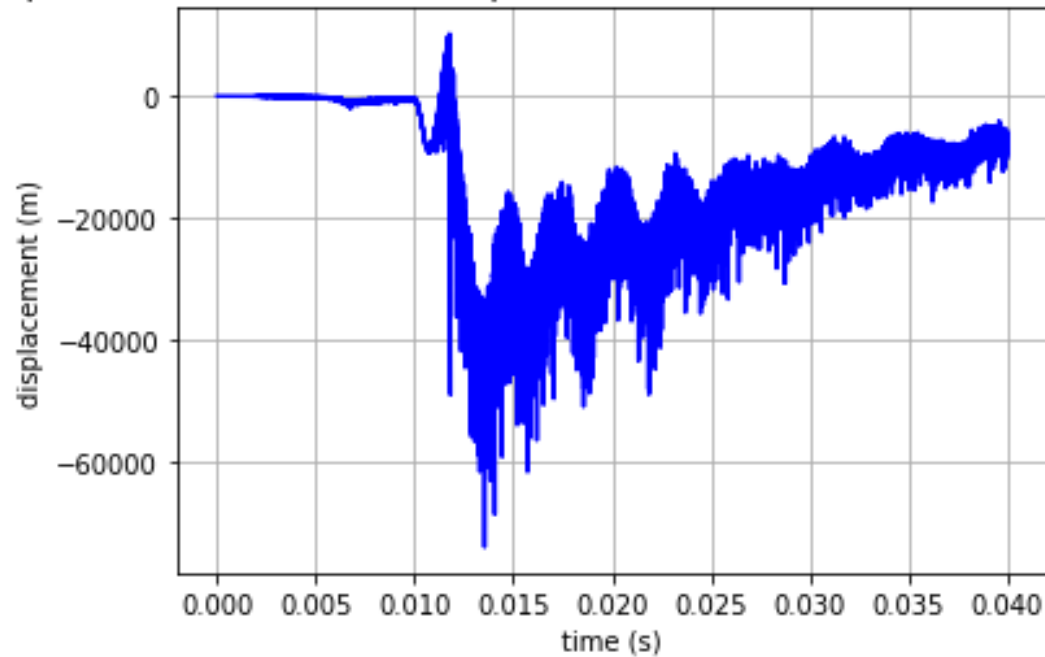


[2]

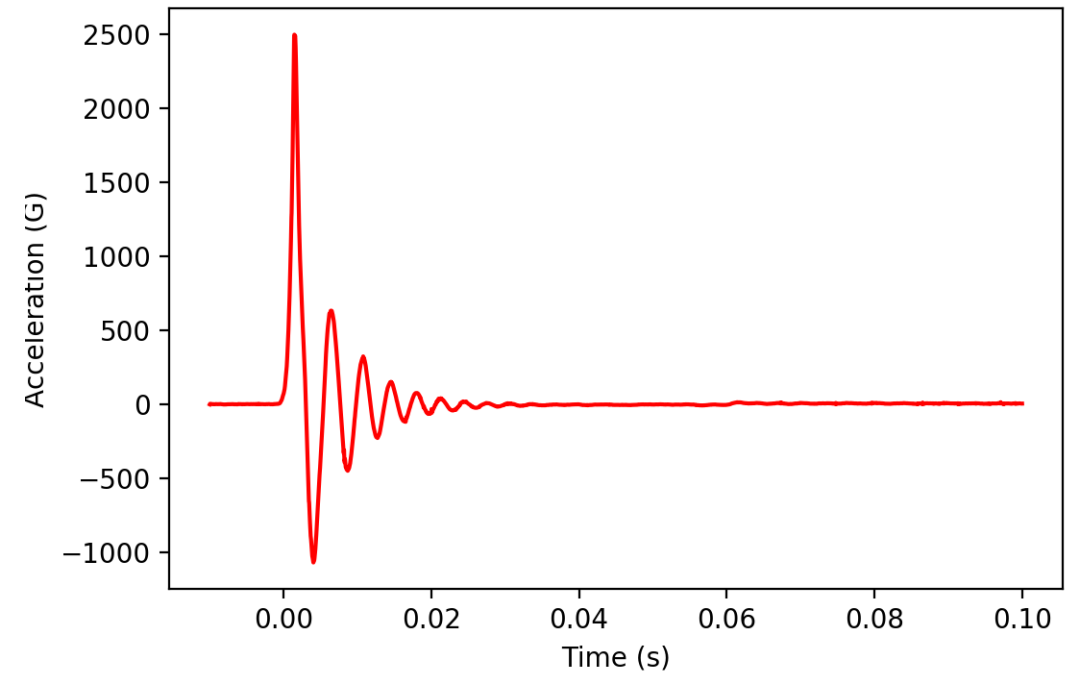
Simulation Acceleration VS Test Acceleration



sil30qin8th Acceleration over time preload (lbs): 1440.000000, G-force: 1500



Test 50 Acceleration over time



Design Considerations & Central Questions



- Will a shock displace a compressed part?
- What are the failure conditions?
- How much compression is there?
- How large is the shock?
- How long is the shock?
- What is the pad material?
- What is the pad geometry?

