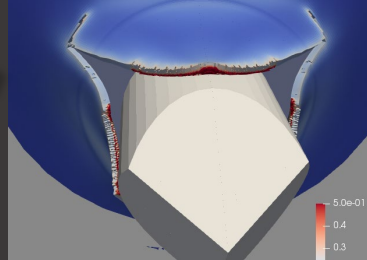
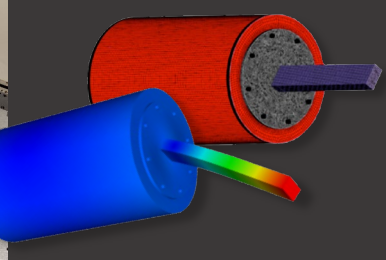
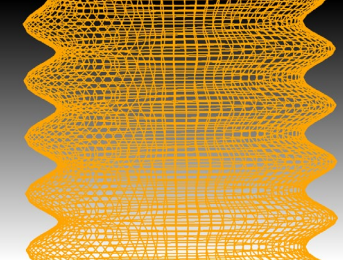


Distortion Compensation for Metal Additive Manufacturing



Collette Gillaspie (TAMU)
Mehmet Sirtalan (UW-Madison)
Theresa Honein (UC-Berkeley)

August 2, 2022

Mentors

Kyle Johnson
Carl Herriott
Michael Stender
Ellen Wagman
Richard Deering (KCNSC)



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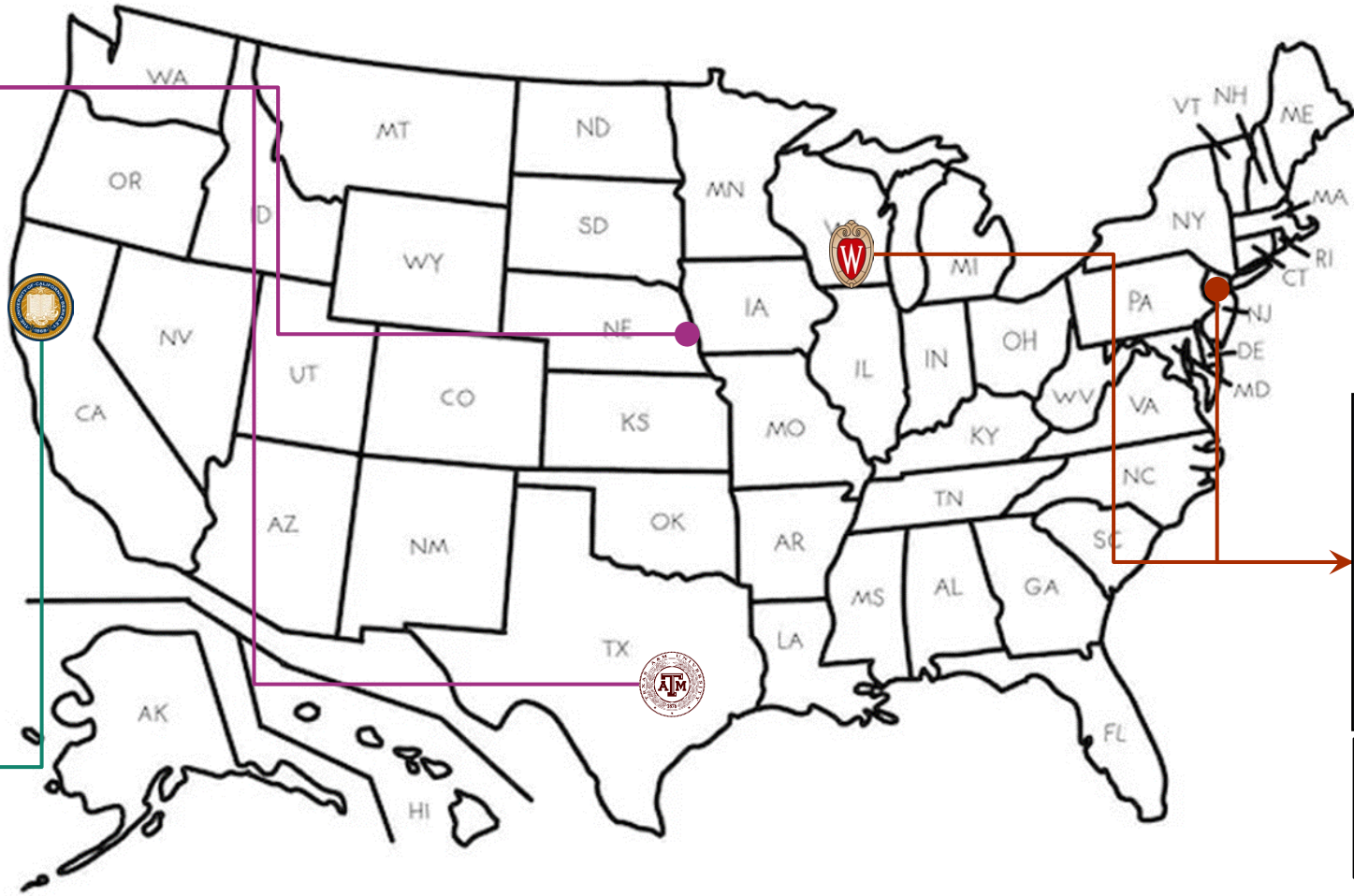
SAND2022-10345 PE



Collette Gillaspie



Theresa Honein



Mehmet Sirtalan



- Background information: Distortion in metal additive manufacturing
 - Why distortion happens?
 - How do we quantify it?
- Distortion compensation optimization algorithm
- Results validation: It works!

BACKGROUND & MOTIVATION



Fig. 1 Video on metal additive manufacturing. <https://www.youtube.com/watch?v=yiUUZxp7bLQ>

Metal Additive
Manufacturing

Problem
Formulation

Deformation Prediction

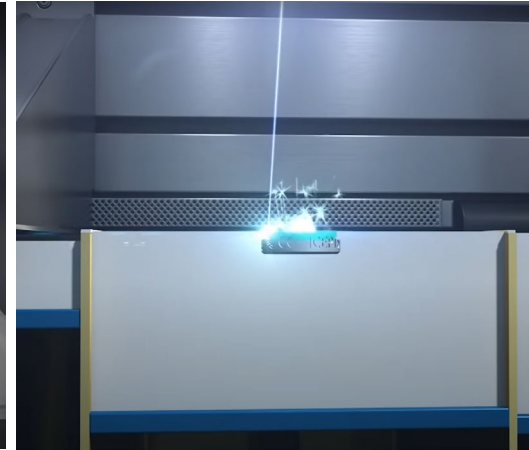
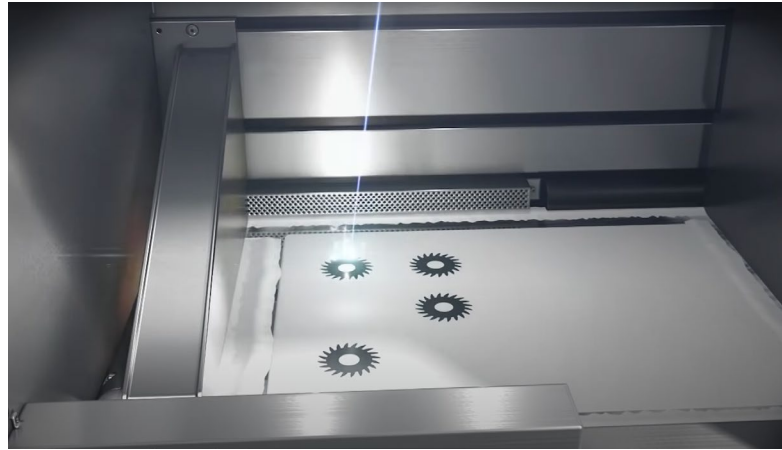
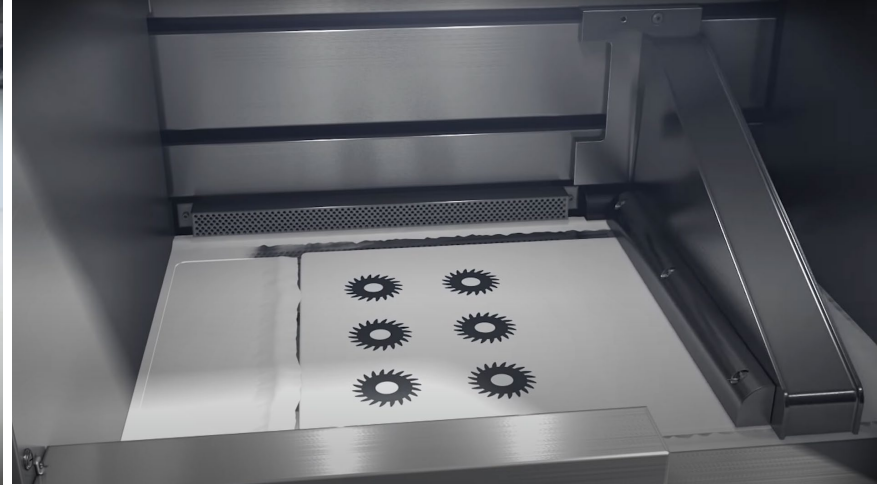
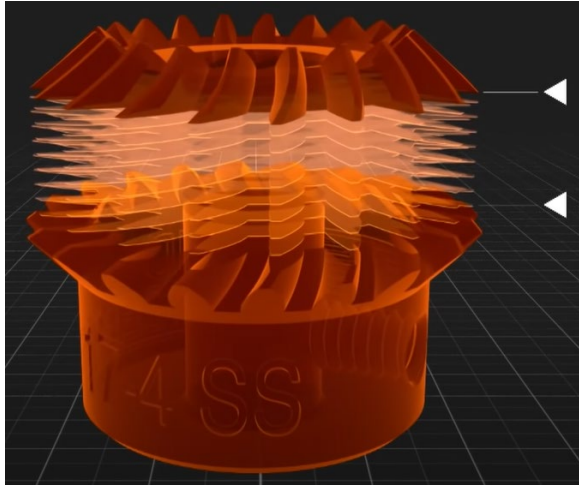


Fig. 2 Images of metal additive manufacturing.

Metal Additive
Manufacturing

Problem
Formulation

Deformation Prediction

7 **Problem: Distortion**

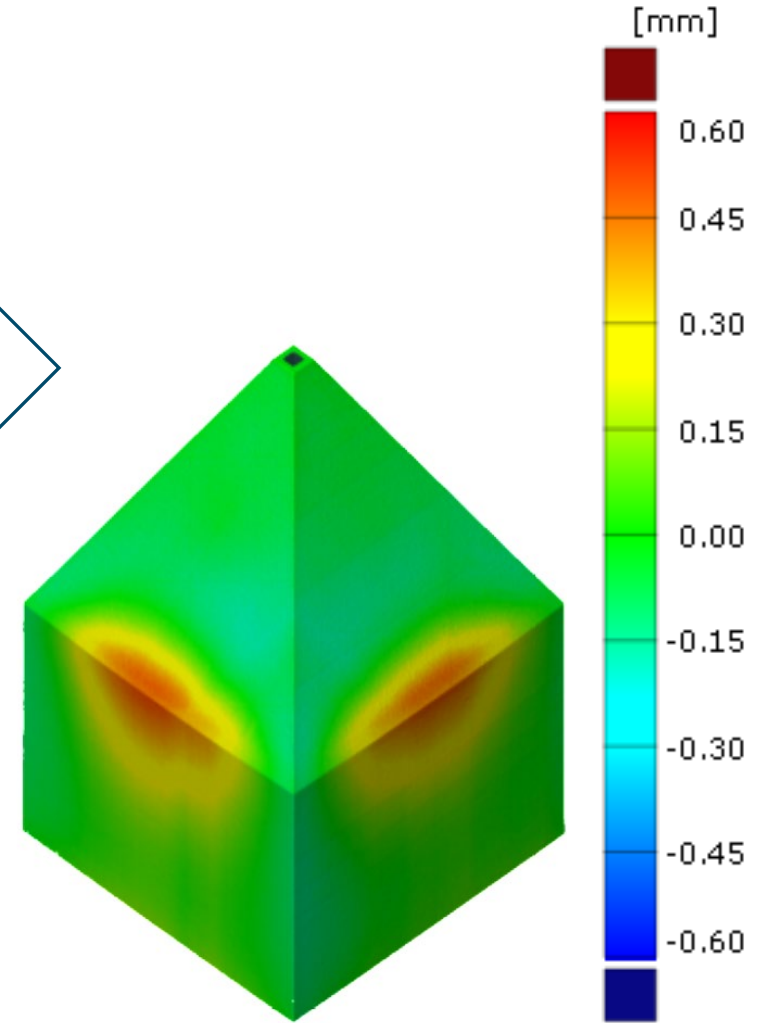
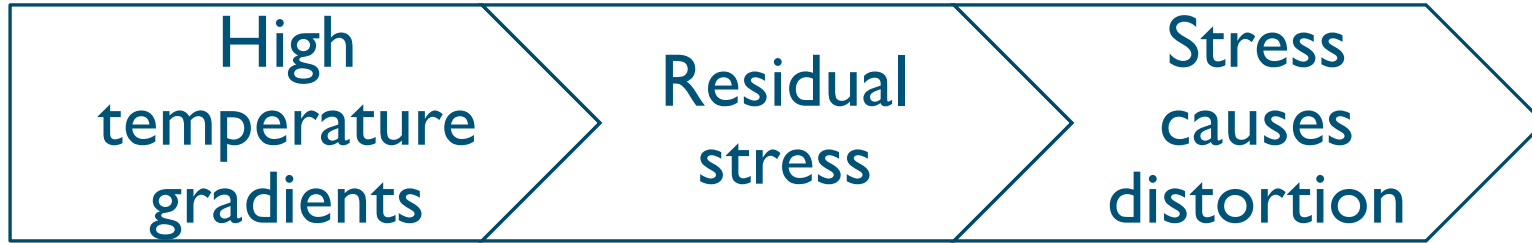
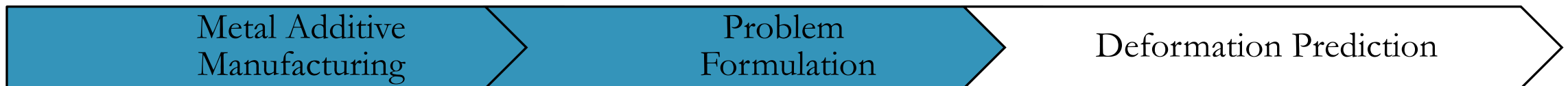
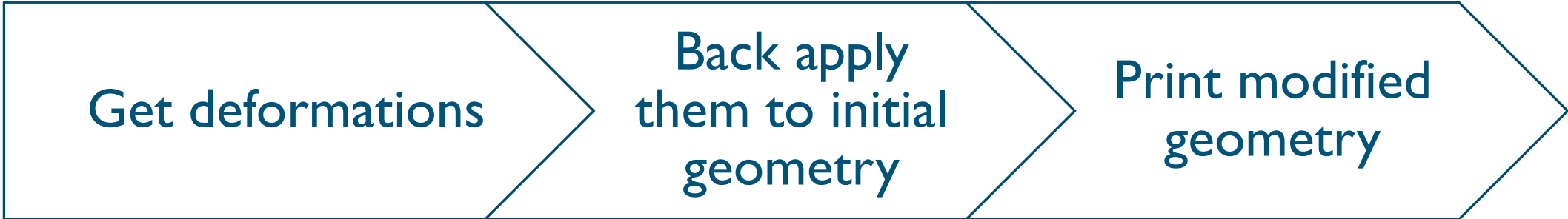


Fig. 3 Distortion of uncompensated printed part relative to CAD geometry.

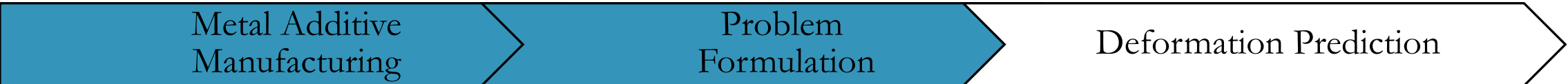




Solution: Distortion Compensation



Goal: Printed Geometry Distorts Into Desired Geometry



9 Deformation Prediction



- Modeling Approaches
 - Thermomechanical simulations
 - Inherent strain method: mechanical simulations
 - Modified inherent strain methods

- Optical approaches

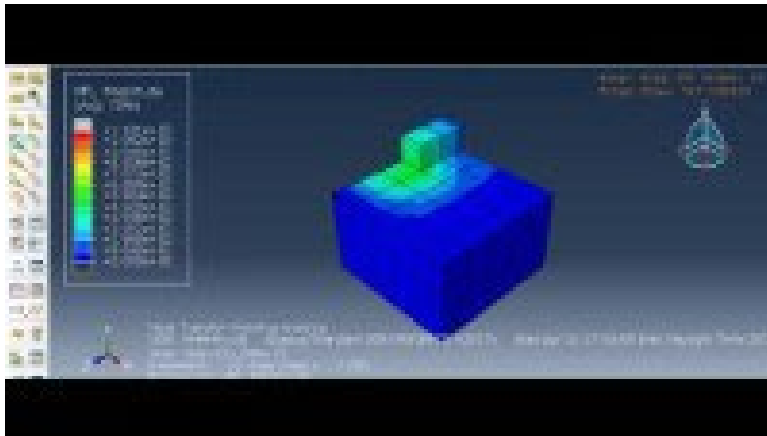


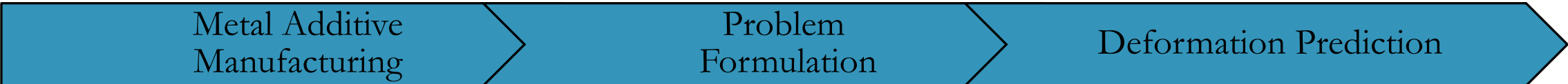
Fig. 4 Element birth simulation using Abaqus.

<https://www.youtube.com/watch?v=FqE3kj9ESVc>



Fig. 5 ATOS Compact Scan: Blue Light 3D Scanner.

<https://www.youtube.com/watch?v=T-RkQioXHYg>



Deformation Prediction

- Modeling Approaches
 - Thermomechanical simulations
 - Inherent strain method: mechanical simulations
 - Modified inherent strain methods

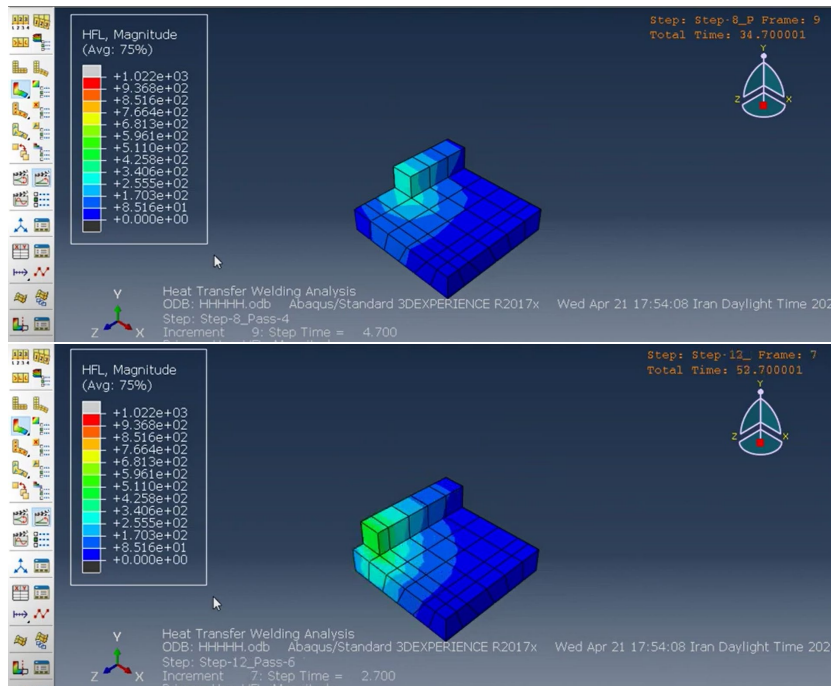


Fig. 6 Element birth simulation using Abaqus. <https://www.youtube.com/watch?v=FqE3kj9ESVc>

- Optical approaches



Fig. 7 ATOS Compact Scan – Blue Light 3D Scanner. <https://www.youtube.com/watch?v=T-RkQioXHYg>

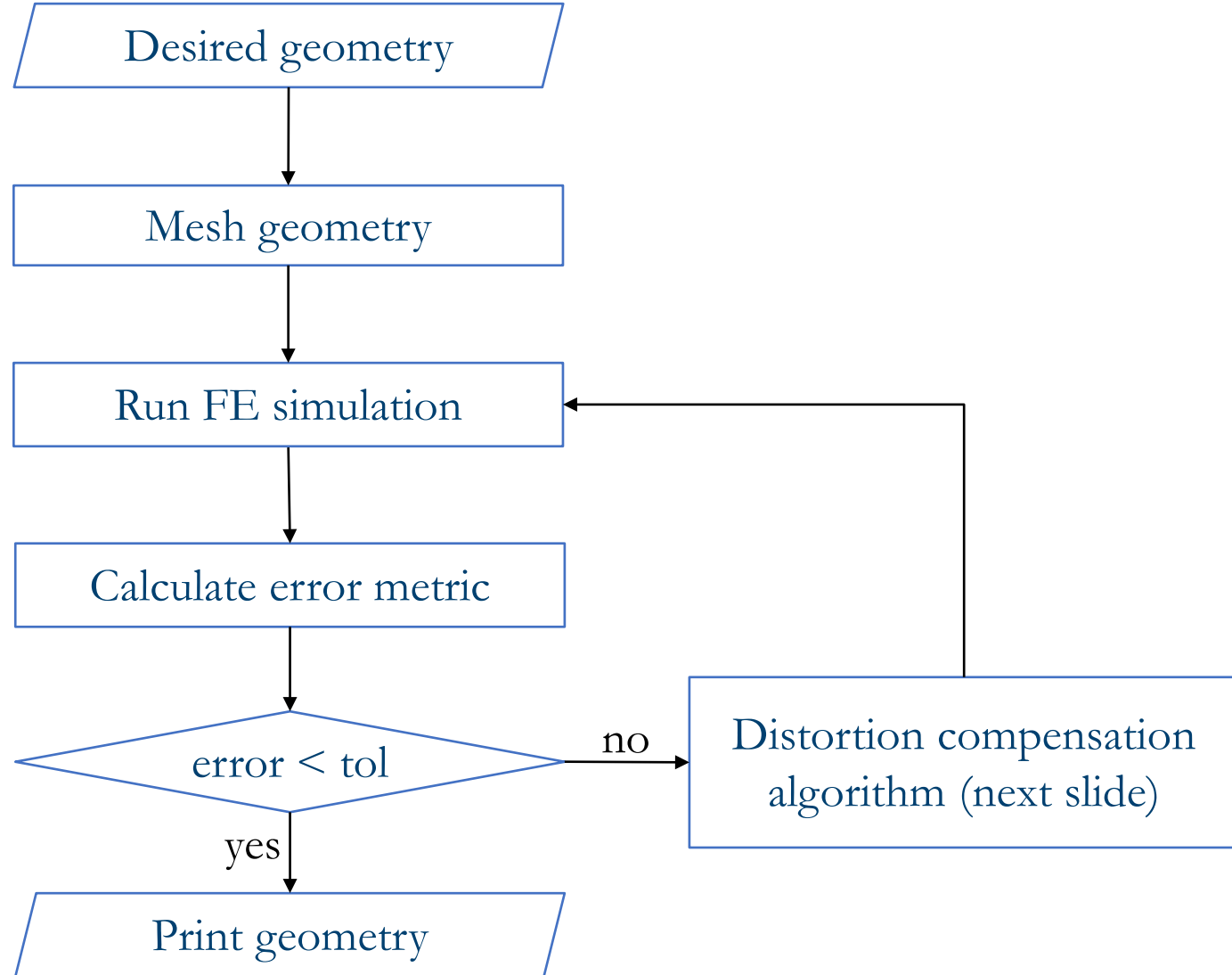
Metal Additive
Manufacturing

Problem
Formulation

Deformation Prediction

PROJECT WORKFLOW

Distortion Compensation Optimization Workflow

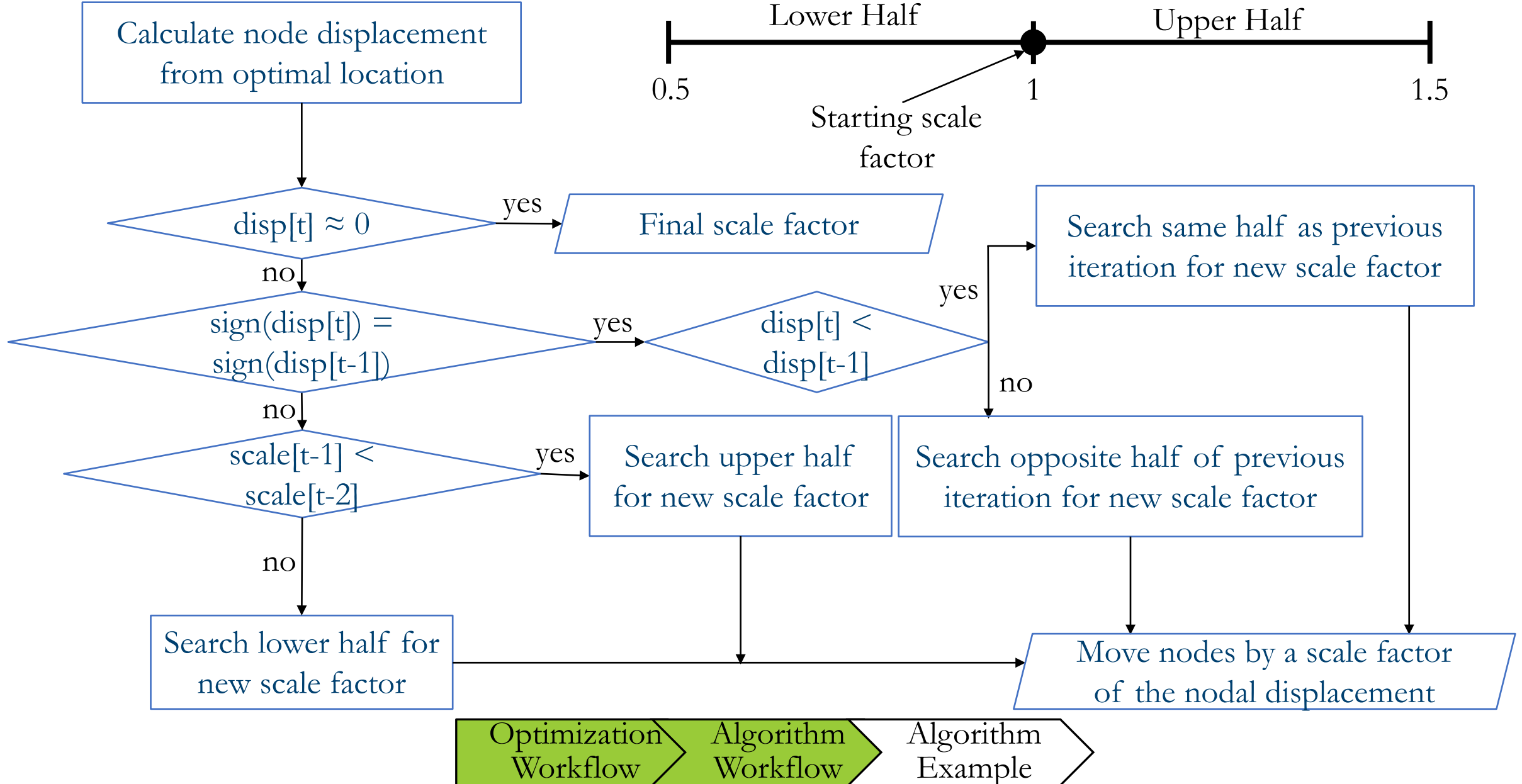


Optimization
Workflow

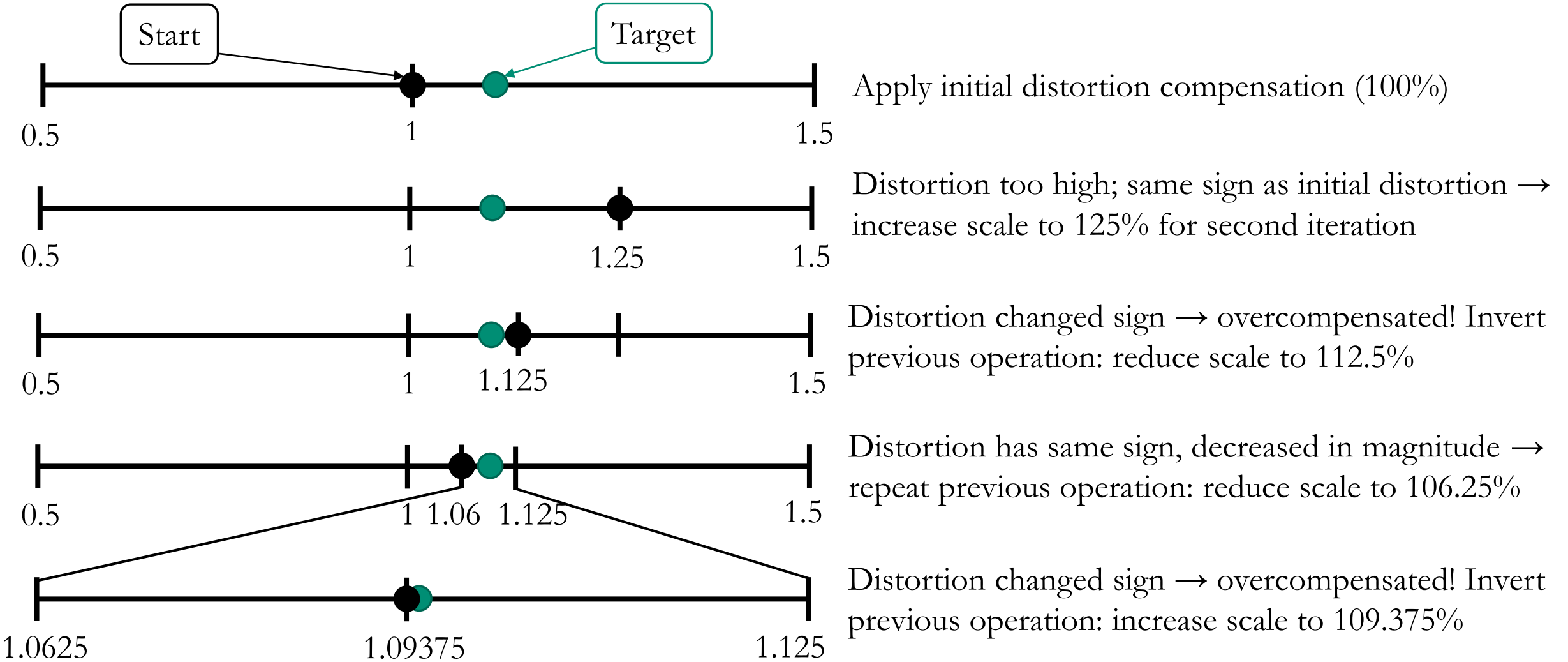
Algorithm
Workflow

Algorithm
Example

Distortion Compensation Algorithm Workflow



Distortion Compensation Algorithm Example



Distortion within tolerance after final iteration, print corresponding geometry.

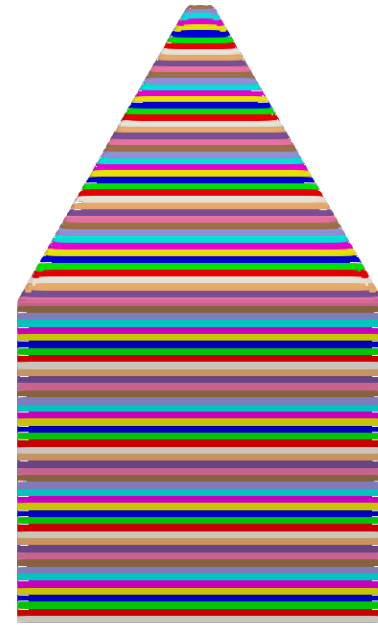
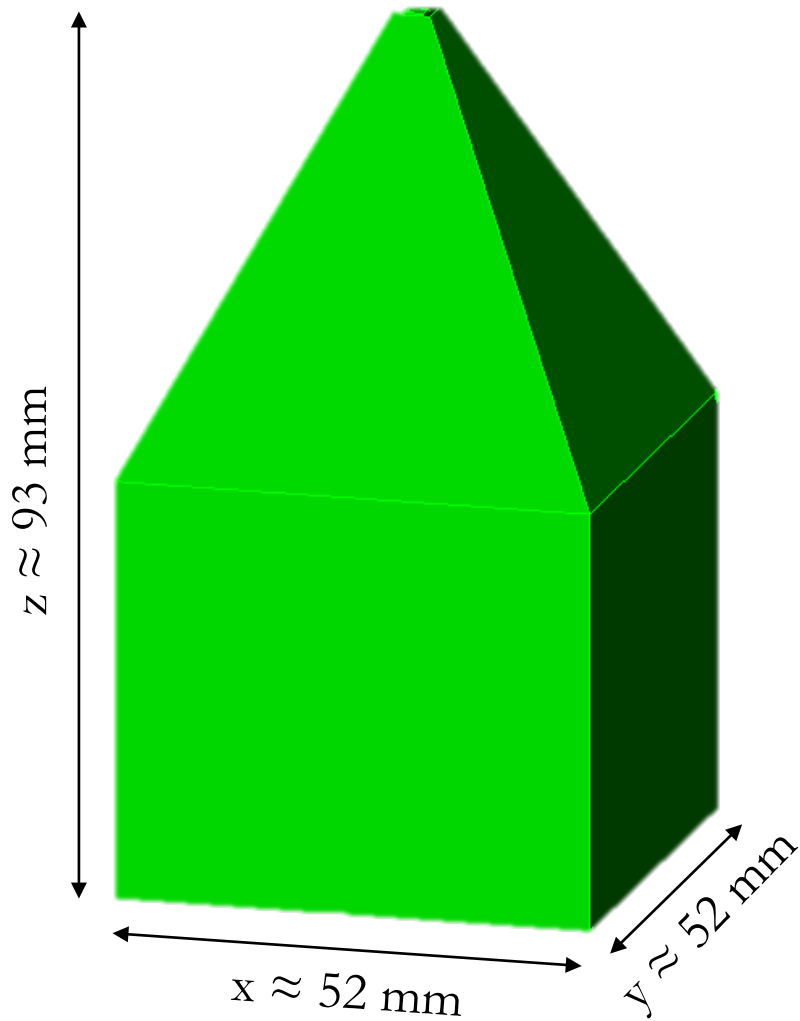
Optimization
Workflow

Algorithm
Workflow

Algorithm
Example

PROJECT RESULTS

Model & Mesh Overview



- Number of Layers: 93
- Element Type: HEX8
- Element Size: 0.50 mm
- Number of Elements: 257108



- Number of Layers: 185
- Element Type: HEX8
- Element Size: 0.25 mm
- Number of Elements: 1531176

Model & Mesh
Overview

Material
Models

Element
Birth Scheme

Distortion
Results

Algorithm
Statistics

Conclusions &
Future Work



- 300 series austenitic stainless steel (304L and 316L)
- Elastic model fit to widely established 304L data
 - Young's modulus: 200×10^9 Pa
 - Poisson's ratio: 0.25
- Elastic-Plastic model fit to 316L tensile data
 - Young's modulus: 200×10^9 Pa
 - Poisson's ratio: 0.3
 - Yield stress: 500×10^6 Pa
 - Hardening modulus: 500×10^6 Pa
 - Hardening exponent: 0.55

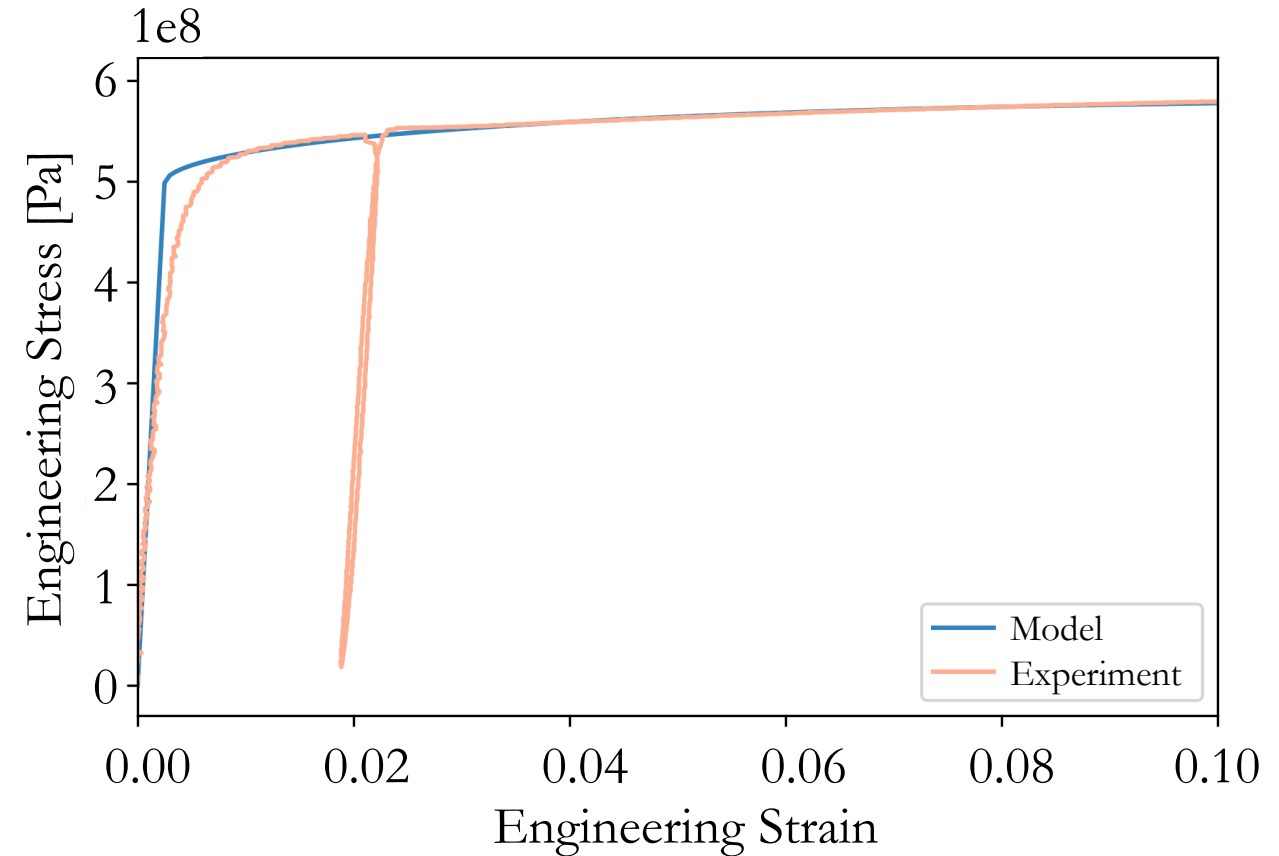


Fig. 8 Stress-strain curve for 316L stainless steel.

Model & Mesh
Overview

Material
Models

Element
Birth Scheme

Distortion
Results

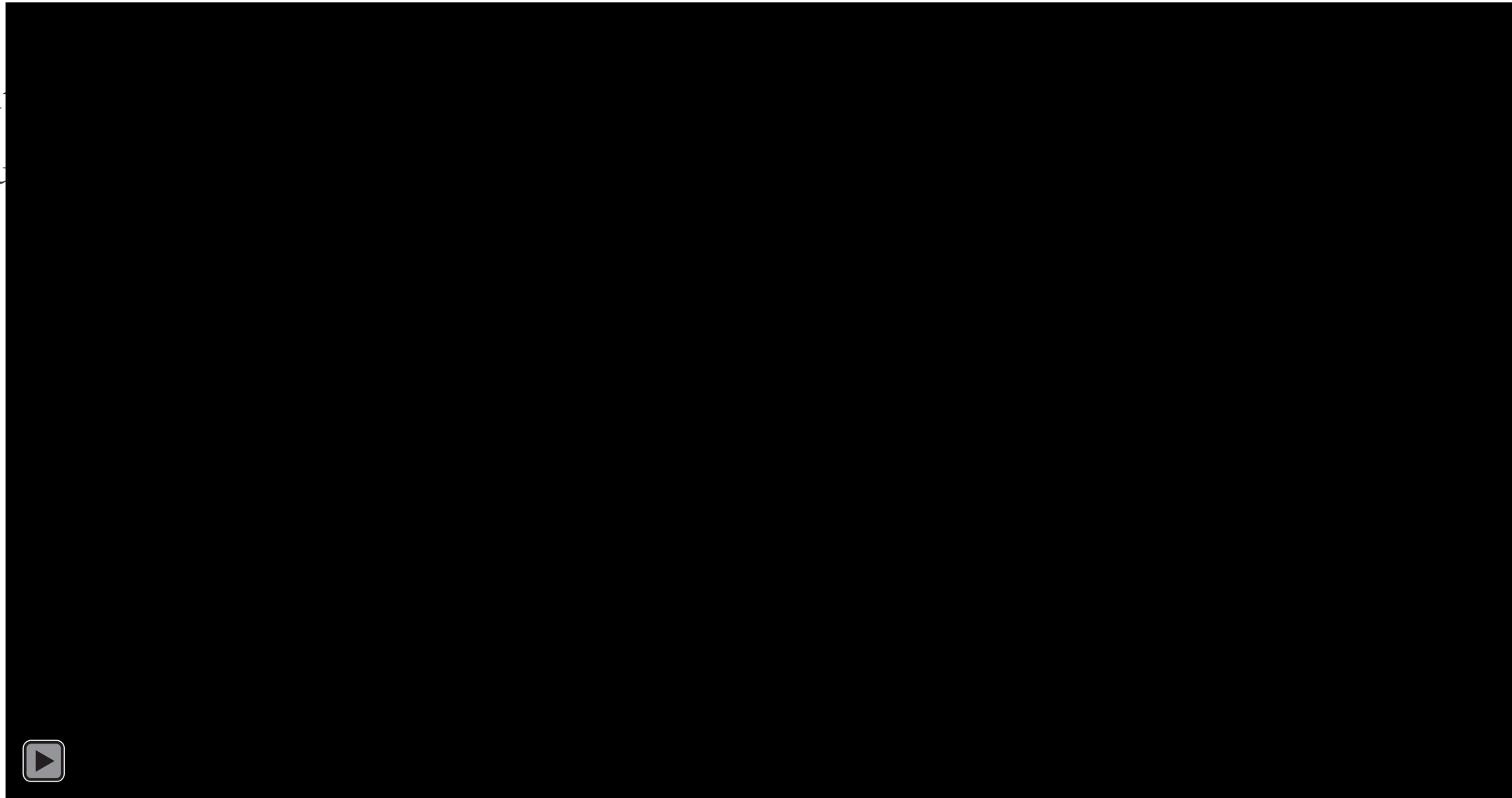
Algorithm
Statistics

Conclusions &
Future Work

Element Birth Scheme



- Layer-by-layer element
- Inactive elements accu



Model & Mesh
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Birth Scheme

Distortion
Results

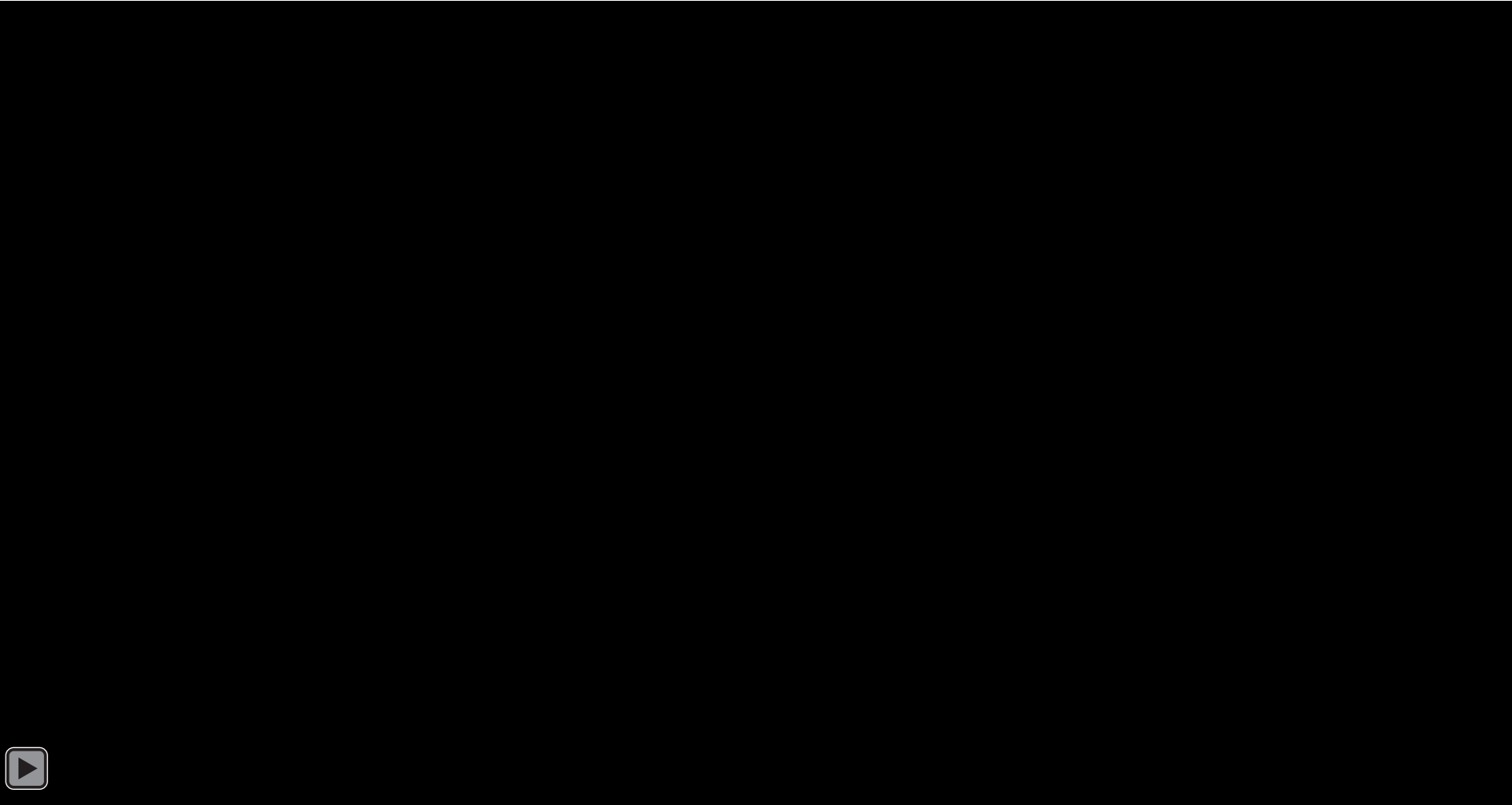
Algorithm
Statistics

Conclusions &
Future Work

Distortion Results: Elastic-Plastic Model



- Number of Processors
- Inherent Strain Values
 - Strain in $x \approx -2\%$
 - Strain in $y \approx -2\%$
 - Strain in $z \approx 2\%$



Model & Mesh
Overview

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Birth Scheme

Distortion
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Future Work

Distortion Results: As-Built Distortion Significantly Reduced

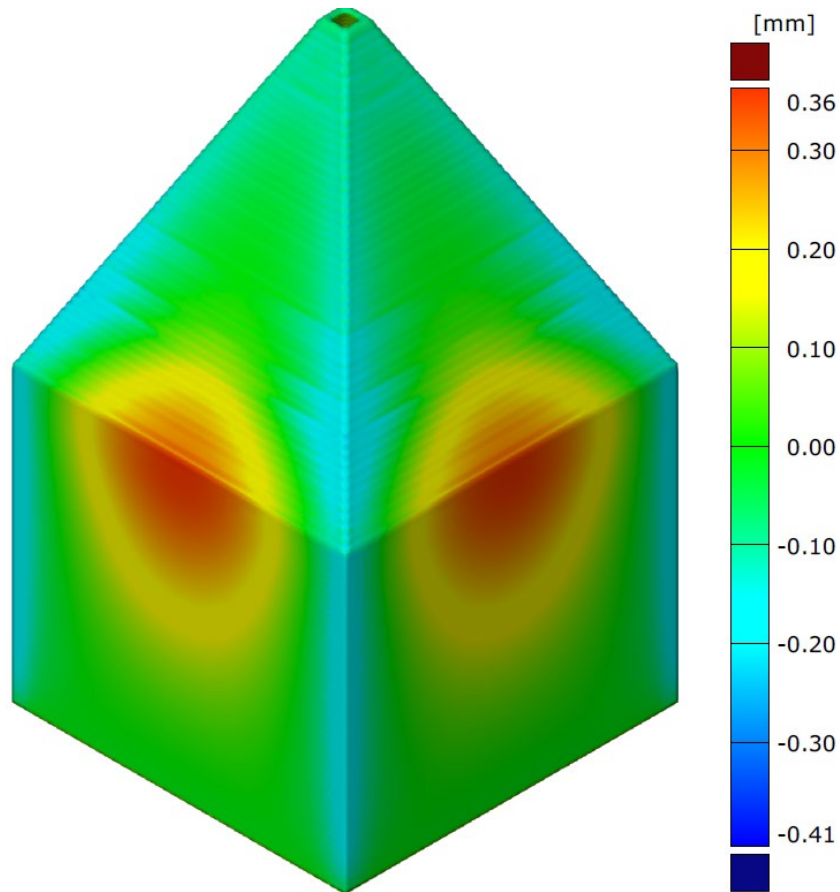


Fig. 9 Simulated deformation of elastic-plastic model without distortion compensation.

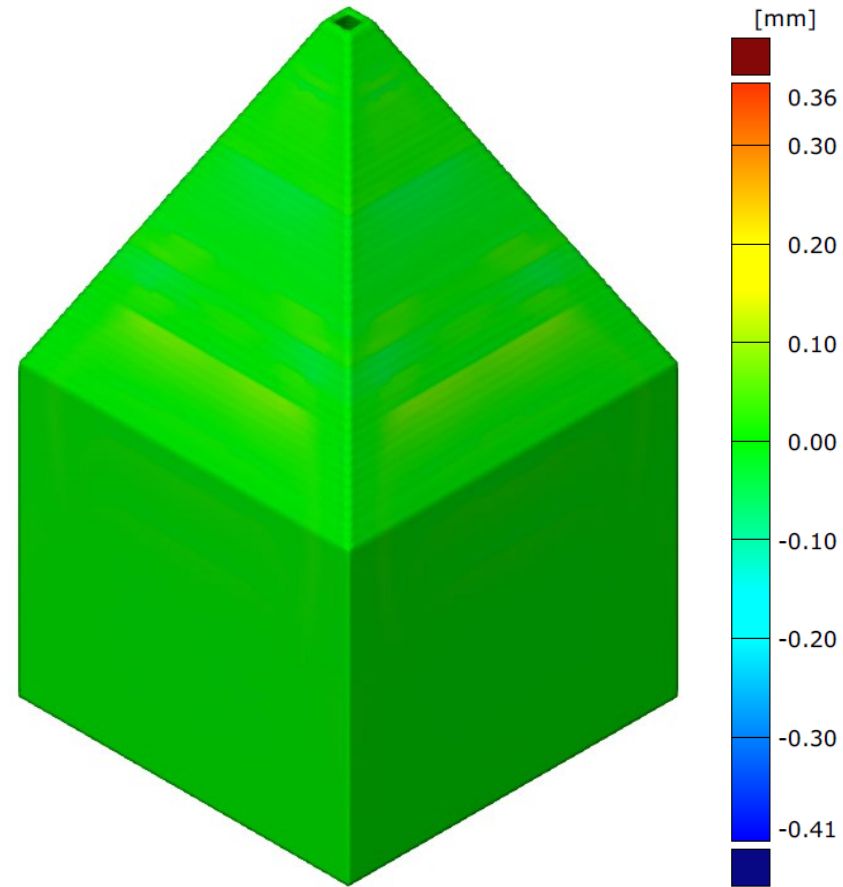


Fig. 10 Simulation deformation of elastic-plastic model with optimized distortion compensation.

Model & Mesh
Overview

Material
Models

Element
Birth Scheme

Distortion
Results

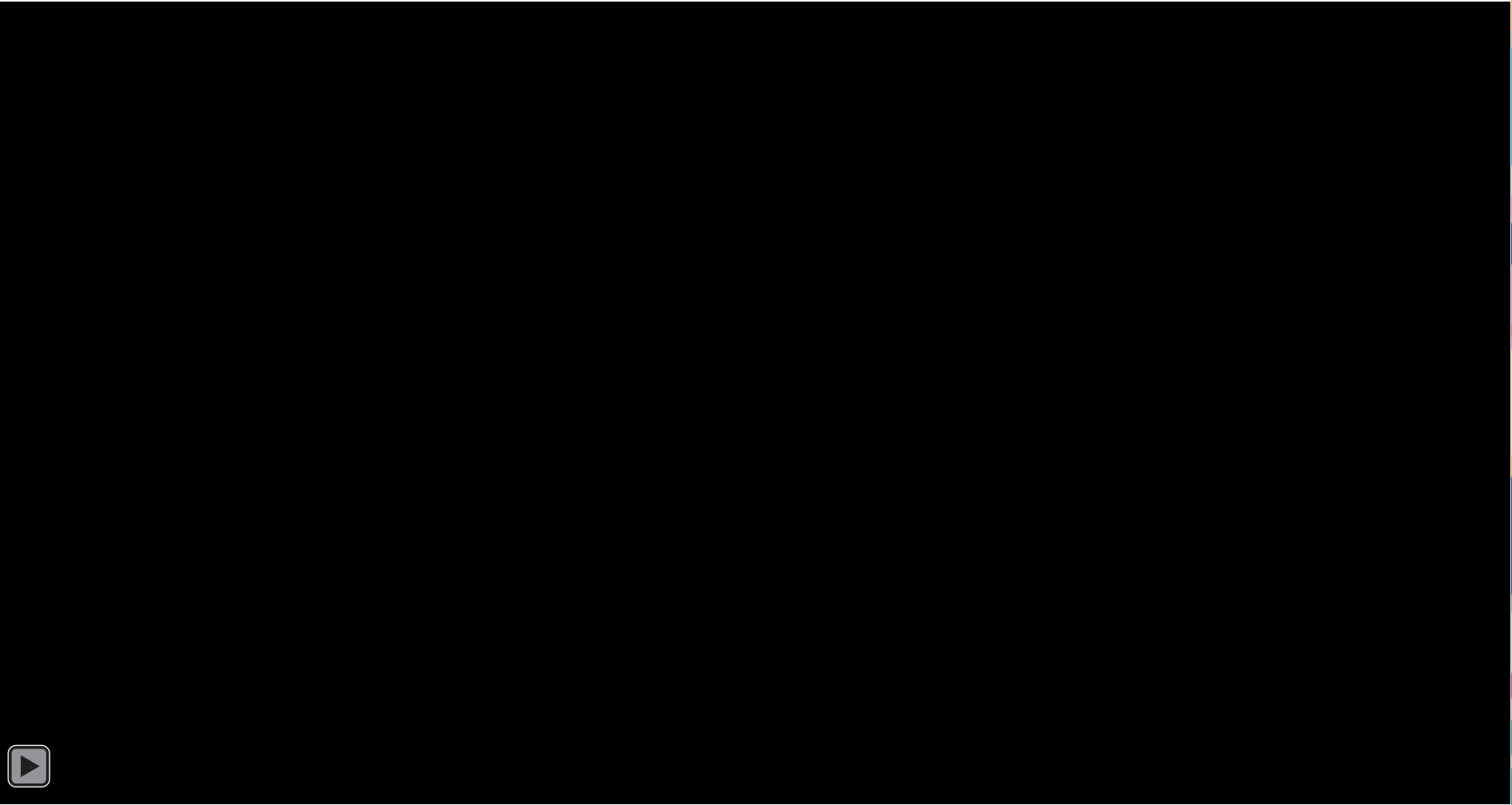
Algorithm
Statistics

Conclusions &
Future Work

Distortion Results: Elastic Model



- Number of Processor
- Inherent Strain Values
 - Strain in $x = -0.2\%$
 - Strain in $y = -0.2\%$
 - Strain in $z = 0.2\%$



Model & Mesh
Overview

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Models

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Birth Scheme

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Conclusions &
Future Work

Distortion Results: As-Built Distortion Significantly Reduced

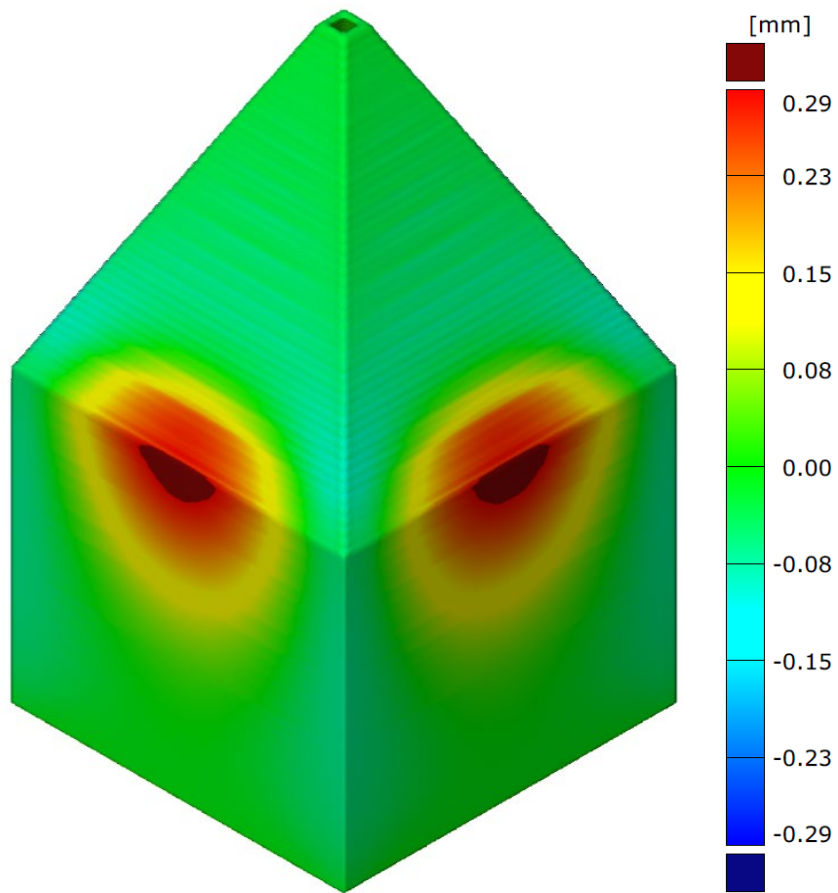


Fig. 11 Simulated deformation of elastic model without distortion compensation.

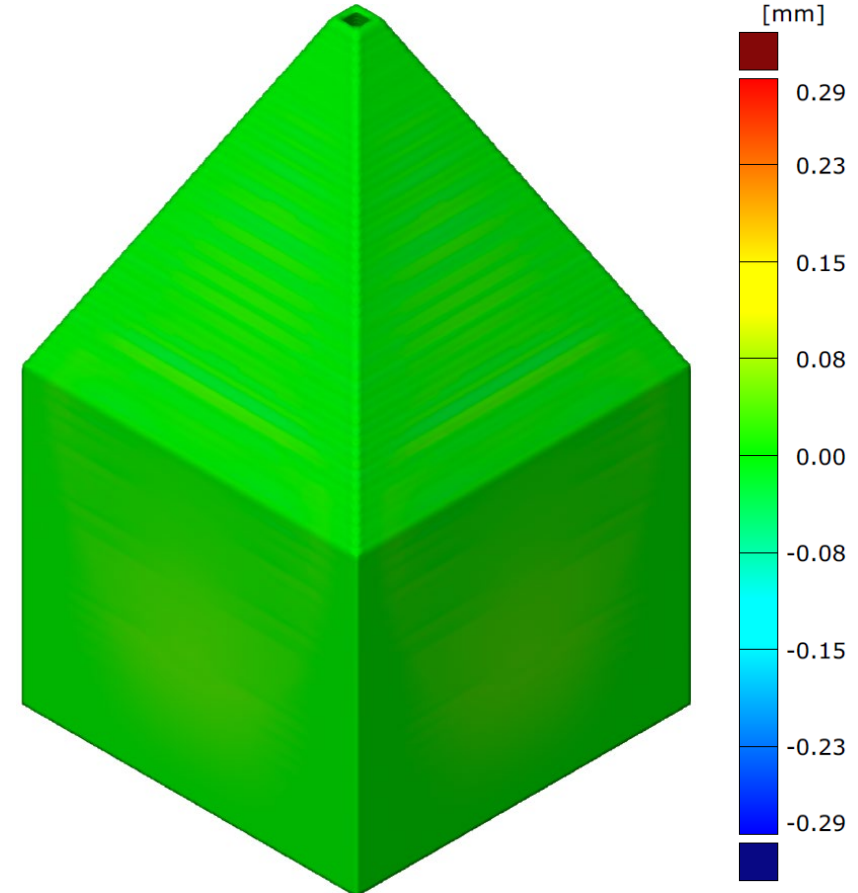


Fig. 12 Simulation deformation of elastic model with optimized distortion compensation.

Model & Mesh
Overview

Material
Models

Element
Birth Scheme

Distortion
Results

Algorithm
Statistics

Conclusions &
Future Work

Algorithm Statistics: Errors

Model	Iteration	Iteration Avg 2-Norm Error	Minimized Avg 2-Norm Error
Elastic-Plastic	1	2.45E-7	2.45E-7
	2	4.30E-8	4.17E-8
	3	3.32E-8	2.58E-8
	4	2.45E-8	2.58E-8
Elastic	1	1.70E-7	1.70E-7
	2	3.49E-8	3.39E-8
	3	2.46E-8	2.06E-8
	4	1.96E-8	1.65E-8

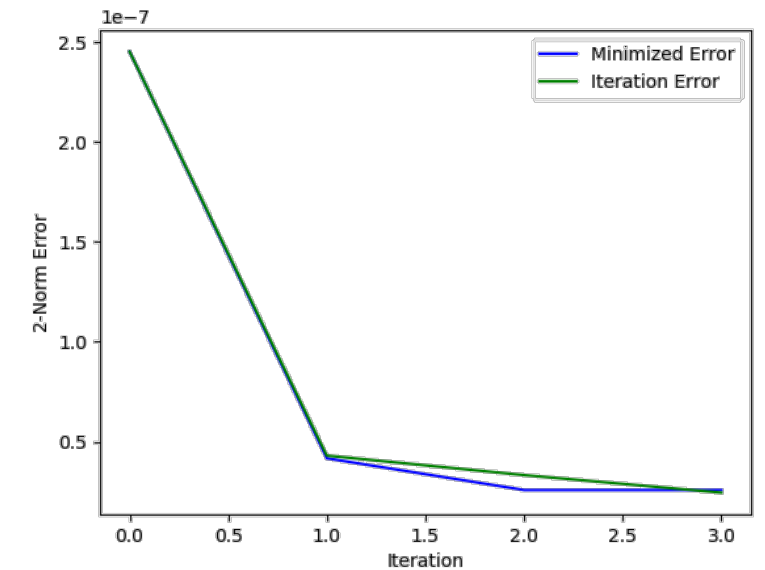


Fig. 13 Elastic-plastic model error per iteration.

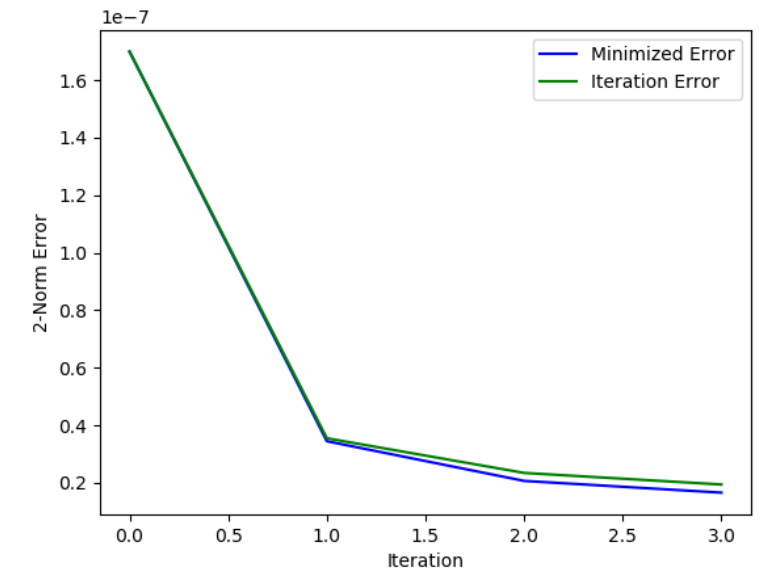


Fig. 14 Elastic model error per iteration.

Model & Mesh
Overview

Material
Models

Element
Birth Scheme

Distortion
Results

Algorithm
Statistics

Conclusions &
Future Work

Algorithm Statistics: Runtimes



Model	Average SIERRA Time per Iteration	Average EPU Time per Iteration	Average Algorithm Time per Iteration	Average Total Time per Iteration	Number of Iterations	Total Time for all Iterations
Elastic-Plastic	21.5 min	4.3 min	7.1 sec	25.9 min	4	1.73 hrs
Elastic	20.4 min	5.8 min	9.8 sec	26.9 min	4	1.76 hrs

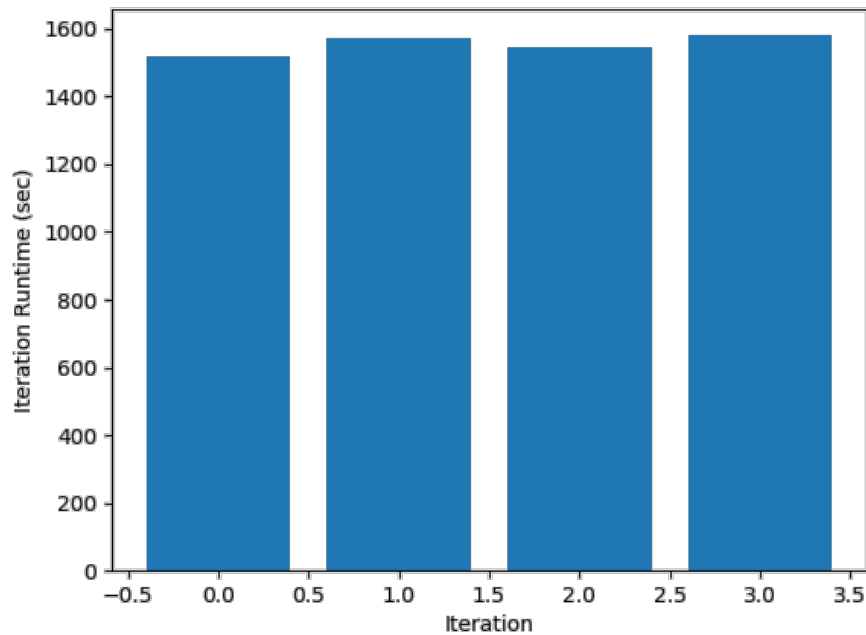


Fig. 15 Elastic-plastic model runtime per iteration.

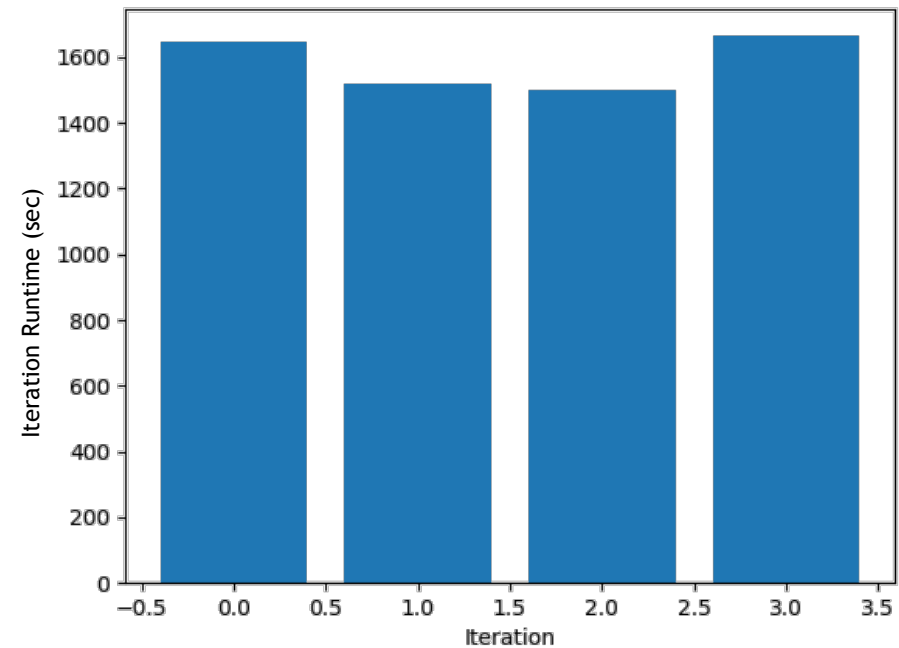


Fig. 16 Elastic model runtime per iteration.





- Conclusions:
 - The distortion of metal builds with SLS is an impediment to the reliability and widespread adoption of additive manufacturing.
 - We developed an efficient numerical distortion compensation optimization workflow which outputs a CAD file that will distort into the desired geometry when printed.
 - We developed a comprehensive tool to obtain a geometrically compensated stereolithography file from a mesh input
 - We tested this algorithm on a thin house geometry, and it works!
- Future work:
 - Integrate coupled thermomechanical modeling techniques into the workflow
 - Validate the algorithm with a printed proof-of-concept



Acknowledgements



- The authors would like to acknowledge the support of our mentors, Kyle Johnson, Michael Stender, Carl Herriott, Richard Deering, and Ellen Wagman.
- Further appreciation is extended to the NOMAD team—Deborah Fowler, Robert Kuether, Joseph Bishop, Jill Blecke, and Brooke Allensworth—for their organization and guidance.
- Sandia National Laboratories is a multimission laboratory managed and operated by National Technology & Engineering Solutions of Sandia, LLC, a wholly owned subsidiary of Honeywell International Inc., for the U.S. Department of Energy's National Nuclear Security Administration under contract DE-NA0003525.

THANK YOU!

We will take your questions at this time.



X. Liang, Q. Chen, L. Cheng, Q. Yang, A. To, A modified inherent strain method for fast prediction of residual deformation in additive manufacturing of metal parts, in: 2017 International Solid Freeform Fabrication Symposium, University of Texas at Austin, 2017. doi: <http://dx.doi.org/10.26153/tsw/16972>.

BACKUP SLIDES



$$\epsilon_{to} = \epsilon_e + \epsilon_p + \epsilon_{th} + \epsilon_{pt} + \epsilon_{cr}$$

$$\epsilon^* = \epsilon_{to} - \epsilon_e = \epsilon_p + \epsilon_{th} + \epsilon_{pt} + \epsilon_{cr}$$

Original inherent strain method

$$\epsilon^* = \epsilon_p$$

Contribution of the plastic deformation to the IS of the AM process

$$\epsilon_p^* = \epsilon_p^I$$

Contribution to the IS in the AM process

$$\epsilon_{th} = \epsilon_e^I - \epsilon_e^S$$

Modified inherent strain model

$$\epsilon^* = \epsilon_p^* + \epsilon_{th}^*$$

ϵ_{to} total strain

ϵ_e elastic strain

ϵ_p plastic strain

ϵ_{th} thermal strain

ϵ_{pt} phase transformation

ϵ_{cr} creep strain

ϵ^* inherent strain

ϵ_p^I largest compressive plastic strain at intermediate state

ϵ_e^I elastic strain at the intermediate state

ϵ_e^S elastic strain at the steady state

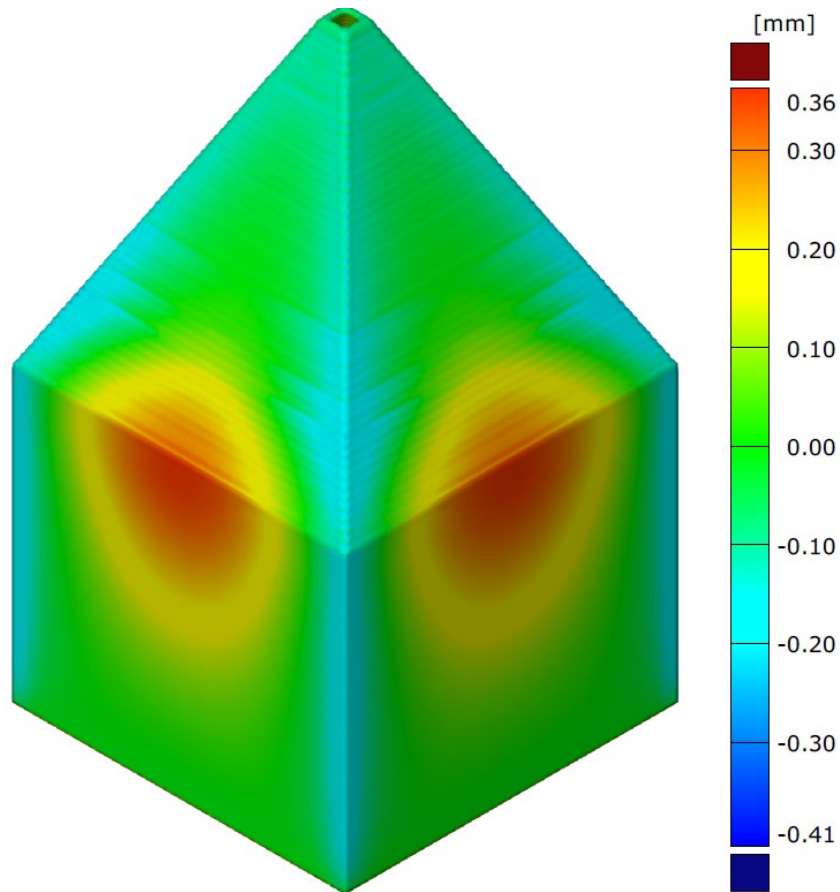


Fig. 17 Simulated deformation without distortion compensation.

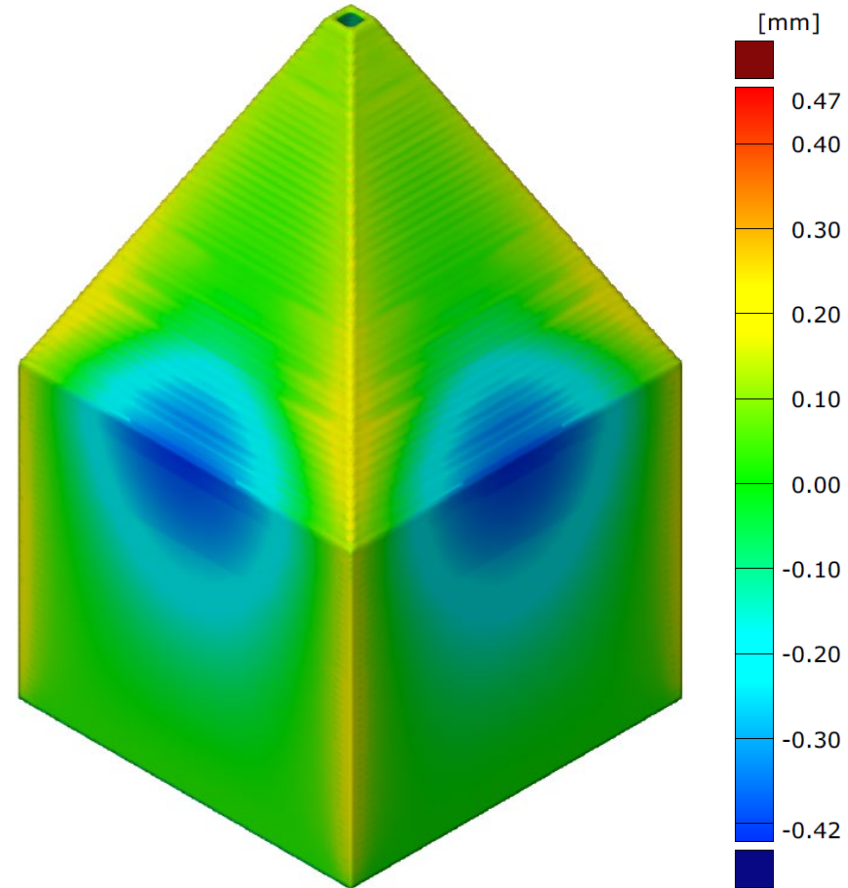


Fig. 18 Distortion compensated file (final geometry to be printed).

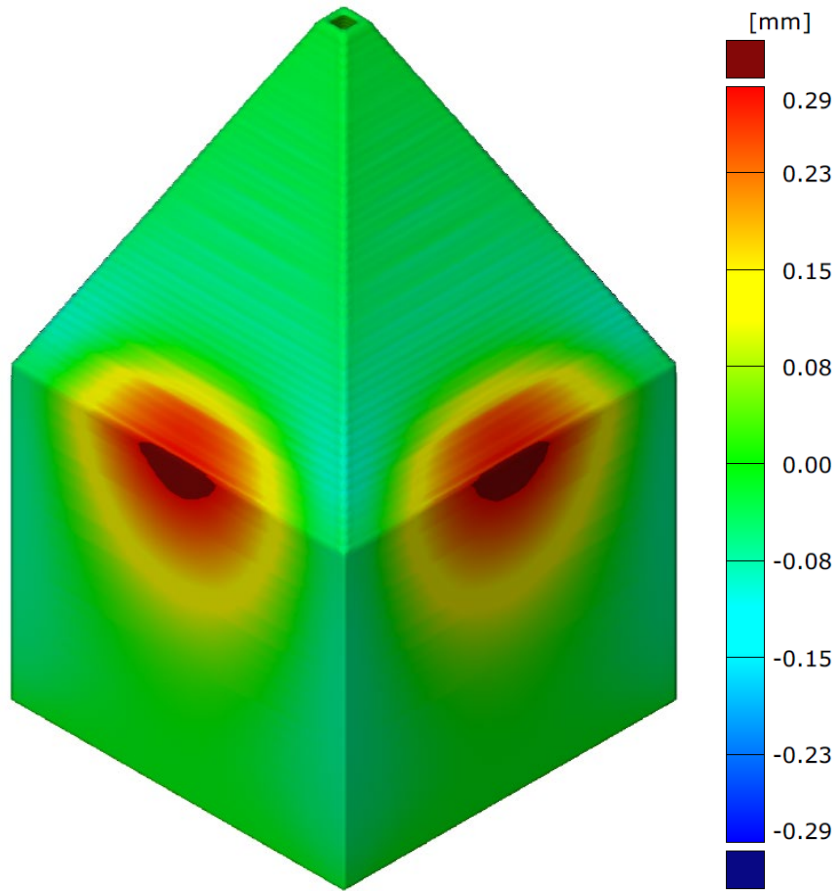


Fig. 19 Simulated deformation without distortion compensation.

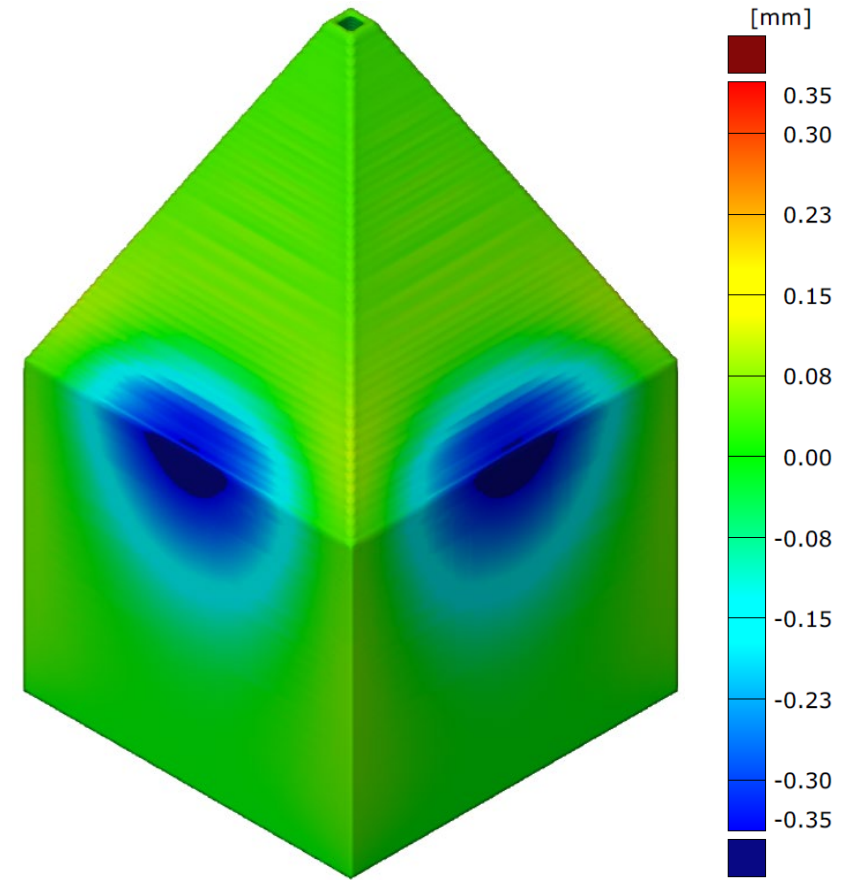


Fig. 20 Distortion compensated file (final geometry to be printed).

Comparing Experimental Data vs Simulated Data for Uncompensated Build

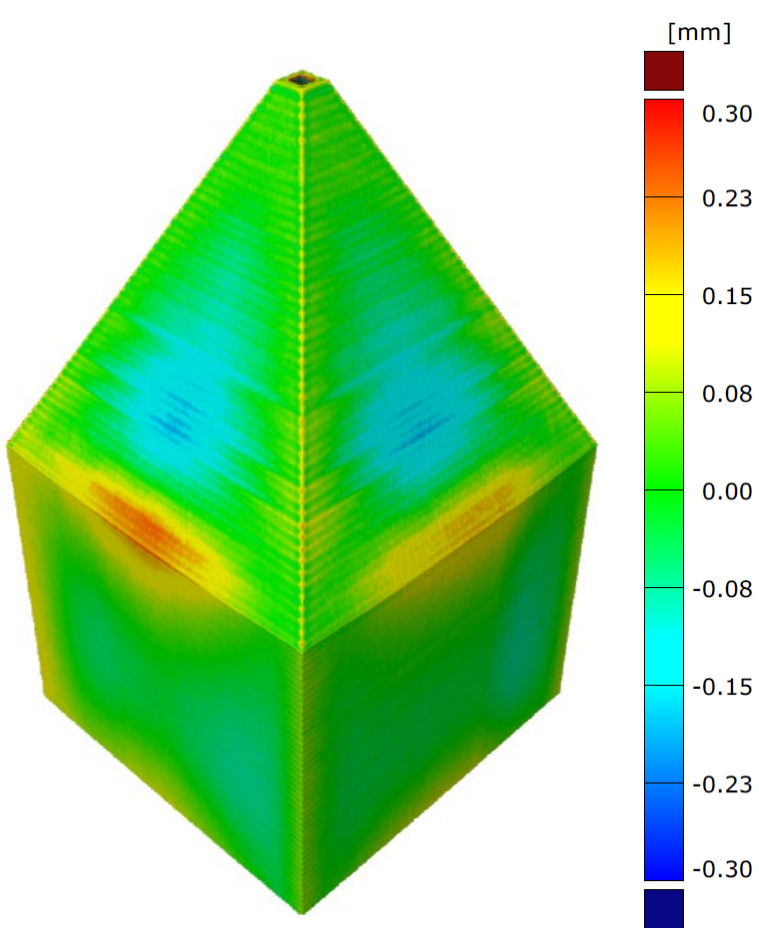


Fig. 21 Elastic-plastic model.

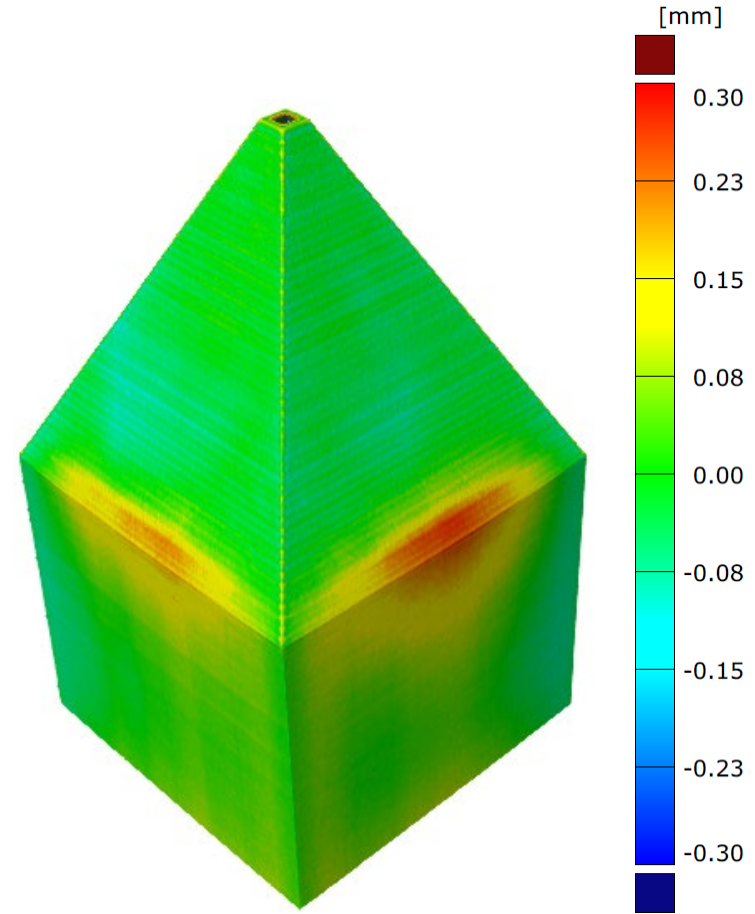


Fig. 22 Elastic model.