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2 Motivation

Using a low fidelity model, can one predict failure seen in higher fidelity models?

Lower Fidelity

shell element models element death failure models Higher Fidelity



hexahedral element models XFEM failure models

3 Outline

- Introduction
- Material Models
- Hexahedral (Hex) Model
- Shell Model
- Comparison of Hexahedral and Shell Models

- Neural Network
- Conclusions

⁴ Problem Setup





Ball

- 5" diameter
- Made up of solid tetrahedral elements
- Mesh size of 0.5"
- 0.2" from plate in z-direction
- Initial velocity
- Plate
 - 25" x 25" x 0.12" square plate
 - Made up of either hexahedral (hex) or shell elements
 - Varying mesh sizes
 - Similar hex and shell models developed for comparison
 - Fixed on edges

Hexahedral and shell models developed at different levels of fidelity for comparison.

Neural Network -

Conclusions

Introduction → Material Models

Hex Model





Relating Hexahedral & Shell Elements

Relating hexahedral and shell elements will be achieved by comparing the following:

- Breakthrough velocity magnitude
 - How fast must the ball travel to break through the plate?
- Kinetic energy change
 - What is the change in energy of the projectile from the beginning time step to the end?

Shell Model

- Size of hole at ball speed of 5000 in/s
 - How much destruction is measured for each case?



Conclusions

Neural Network 🔶

Material Models

Plate: 6061-T651 Aluminum Alloy

Hex-Based Setup

J₂ Plasticity Model

Shell-Based Setup

Modular Plane Stress Plasticity Model

Ball: 304L Stainless Steel Alloy

<u>All Setups</u>

J₂ Plasticity Model

All components are set up with ductile failure models: J₂ plasticity for solid elements and modular plane stress plasticity for shell elements.

Neural Network -

Conclusions

Fixed Parameters

Aluminum

Parameter	ρ (blob/in³)	E (psi)	ν	c _p (in-lb/(blob °C))
Value	2.5 x 10 ⁻⁴	10.4×10^{6}	0.33	1.36 x 10 ⁶
Steel				
Parameter	ρ (blob/in³)	E (psi)	ν	c _p (in-lb/(blob °C))
Value	7.49 x 10 ⁻⁴	28 x 10 ⁶	0.27	0.776 x 10 ⁶

Fixed parameters do not vary with plastic deformation.

Hex Model

Shell Model



9 Modular Plane Stress Plasticity

- A J₂ plane-stress model with modified forms for hardening
- Uses the same values from the J₂ plasticity model
- Developed for use with shell elements

Only the plane stress state is allowed in shell elements.

Hex Model



Shell Model → Comparisons



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¹⁰ Death Criterion in Ductile Failure

Element death will be defined using the damage variable D

Factors of the damage variable

Material Models

• Calculated such that material failure occurs when damage ≥ 1

Hex Model

- Accumulates with plastic deformation
- Functional dependency chosen to be on the stress, equivalent plastic strain rate, and temperature histories

$$D = \frac{1}{d_{crit}} \int_{0}^{\epsilon^{p}} f(\sigma, T, \dot{\epsilon^{p}}) d\epsilon^{p}$$

Element death occurs when the variable damage \geq 1, which accumulates with plastic deformation.

Shell Model

Comparisons

Neural Network -

Conclusions

Introduction -

11 Hexahedral Model Development

Plate Mesh Sizes Considered

Case Number	Element Side Length Across Face (in)	Number of Elements Through Thickness	Total Number of Nodes	Aspect Ratio	Varied number of elements through
1	0.12	3	175,848	3	the thickness and
2	0.04	3	1,568,268	1	across faces of
3	0.02	6	10,956,131	1	place.



12 Hexahedral Fidelity Comparisons

Case 3 - Most Refined

Case 1 - Least Refined



13 Hexahedral Velocity Threshold

Case Number	Breakthrough Velocity (in/s)
1	1388
2	1363
3	1187-1250

Hex Model

Shell Model

Breakthrough velocity decreases with mesh refinement.

Neural Network -

Conclusions



15 Shell Fidelity Comparisons





Hex Model 🔶

Shell Model ---- Comparisons -----





16 Shell Velocity Threshold

Mesh Size (in)	Breakthrough Velocity (in/s)
1	1083
.5	844
.25	795
.12	765
.04	516

Hex Model

Breakthrough Velocity

Disparity in Velocity Threshold is greater relative to Hex models, but all thresholds are underestimated relative to hex models

Conclusions

Shell Model ---

Comparisons → Neural Network →

17 Comparison of Shell and Hex

	Hex Model (.04)	Shell (.04)	Shell (0.5)
Computation Time (hour : minutes : seconds)	96:05:40	11:53:52	00:04:04
Projectile Kinetic Energy Loss (J)	7.02	7.80	12.67



Hex Model (.04)

Introduction -

Material Models



Shell Model (.04)

Shell Model

Hex Model



Shell Model (0.5)

Neural Network 🔶

Conclusions

18 Comparison of Shell and Hex



Velocity of the ball vs. time for different levels of fidelity.

Introduction ->

Material Models → Hex Model

Shell Model --- Comp



¹⁹ Shell – Varying Integration Point Thresholds

Number of Integration Points (IP) to Reach Death Criterion Before Element Killed







Neural Network 🔶

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Conclusions







Shell – Varying Integration Point Thresholds



Introduction ->





Neural Network -

Conclusions

Comparison of Hexahedral Element Death vs Shell XFEM

<u>Mass Lost</u>

Introduction

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- Shell with XFEM 0 lb
- Shell with Element Death 2.1x10⁻⁵ lb
- Hex with Element Death 2.076x10⁻⁵ lb (0.1% of starting mass)

Case 3 Hex Model (Most Refined)



Material Models



Shell Model

Hex Model

Case 2 Shell Model

Case 2 Shell Model XFEM



Neural Network →

Conclusions

²² Neural Network problem

- A fully connected neural network is used to determine if there is a break in a plate given the initial velocity of the projectile.
- To train the neural network, data was gathered from simulations where the initial velocities magnitude and directions varied. This simulation was then used to determine if there was a break in the plate or not.
- With this neural network, we can run lower fidelity simulations and predict if there was break in the plate or not.





Introduction -> Material Models -> Hex Model -> Shell Model -> Comparisons -> Neural Network -> Conclusions

²³ Fully Connected Neural Network

•For a fully connected neural network each connection between layers can be represented as

$\phi^i(A^ix^{i-1}+b^i)=x^i$

•Here **i=1,2,...,n**, where **n-1** is the number of hidden layers.

- The vectors **x**ⁱ⁻¹ are the inputs into the **i**th layer of the neural network.
- Aⁱ and bⁱ are the weight matrix and bias vectors respectively..
- The function ϕ^i is a an element wise function known as the activation function. This is used to add nonlinearity to the neural network.



Neural Network

Conclusions

Shell Model

Comparisons

²⁴ Neural Network Training

- Trained the network using 30 epochs.
- Use the adam optimization algorithm.
- •Total training time approximately 20 secs.

Prediction Accuracy ≈ 99%



Neural Network

Conclusions

²⁵ Impact Predictions

- Here, simulations are run to predict how large a tear there will be when there is element failure in the model.
- One fully connected neural network was used to make predictions on how wide the hole is and the total number of elements destroyed.



Hex Model

Shell Model

Comparisons



Neural Network

Conclusions

Impact Predictions on the Validation Set



Developed quantitative and qualitative comparison of shell and hex models

 Looked at the usefulness of XFEM in coarse shell models for crack propagation compared to a refined hex model

Quantified disparity in model behavior dependent on mesh resolution

 Able to accurately predict if there will be a tear in the plate given the projectiles velocity and give an estimate on how large the tear will be.



²⁸ Looking into the Future

- Predict shape of the hole
- Train neural networks with other inputs, such as stress, strain, contact force, etc.
- Train neural network with higher fidelity model
- Study the differences in kinetic energy of the plate loss in element death vs. XFEM



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