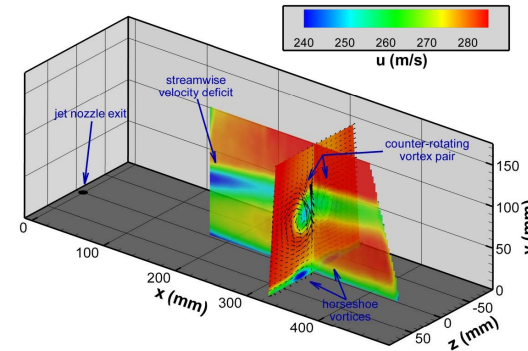
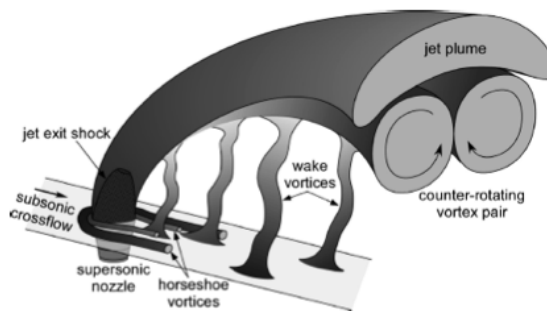


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# Tuning a RANS $k$ - $\epsilon$ model for jet-in-crossflow simulations

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# Introduction

- **Aim:** Develop a predictive RANS model for transonic jet-in-crossflow simulations
  - A strongly vortical flow, often with weak shocks
- **Drawback:** RANS simulations are simply not predictive
  - They have “model-form” error i.e., missing physics
  - The numerical constants/parameters in the k- $\epsilon$  model are usually derived from canonical flows – incompressible flow over plates, channel etc.
- **Hypothesis**
  - One can calibrate RANS on flow over a square cylinder (strongly vortical) to obtain better parameter estimates
  - Due to model-form error and limited square-cylinder experimental measurements, the parameter estimates will be approximate
    - We will estimate parameters as probability density functions (PDF)

# The problem

- **The model**

- Devising a method to calibrate 3 k- $\varepsilon$  parameters  $\mathbf{C} = \{C_\mu, C_2, C_1\}$  from expt. data

$$\frac{\partial \rho k}{\partial t} + \frac{\partial}{\partial x_i} \left[ \rho u_i k - \left( \mu + \frac{\mu_T}{\sigma_k} \right) \frac{\partial k}{\partial x_i} \right] = P_k - \rho \varepsilon + S_k$$

$$\frac{\partial \rho \varepsilon}{\partial t} + \frac{\partial}{\partial x_i} \left[ \rho u_i \varepsilon - \left( \mu + \frac{\mu_T}{\sigma_\varepsilon} \right) \frac{\partial \varepsilon}{\partial x_i} \right] = \frac{\varepsilon}{k} (C_1 f_1 P_k - C_2 f_2 \rho \varepsilon) + S_\varepsilon$$

$$\mu_T = C_\mu f_\mu \rho \frac{k^2}{\varepsilon}$$

- **Calibration parameters**

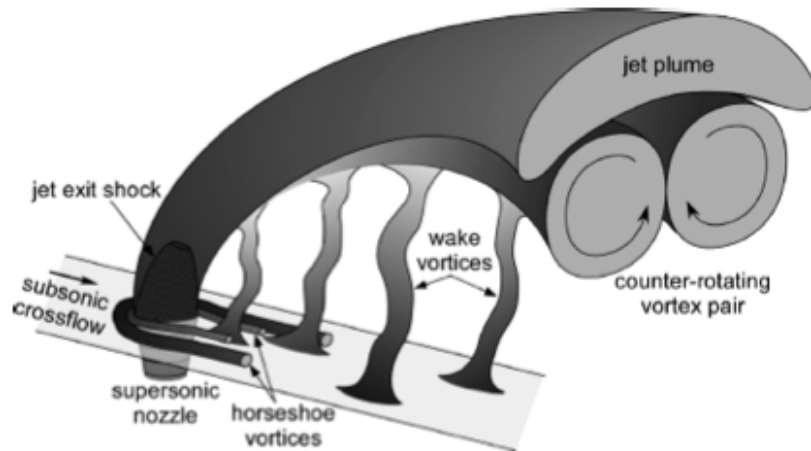
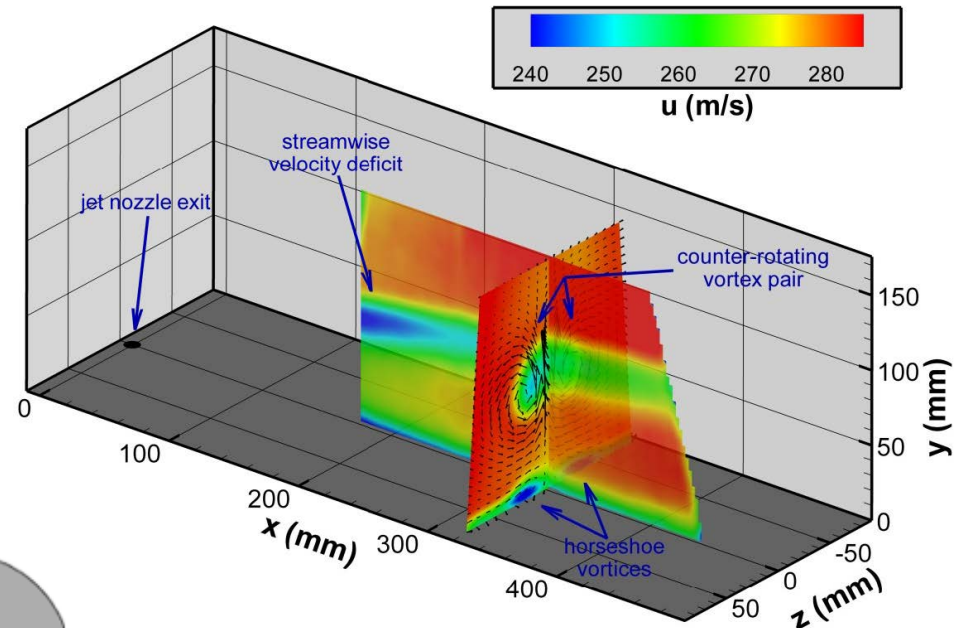
- $C_\mu$ : affects turbulent viscosity;  $C_1$  &  $C_2$ : affects dissipation of TKE

- **Calibration method**

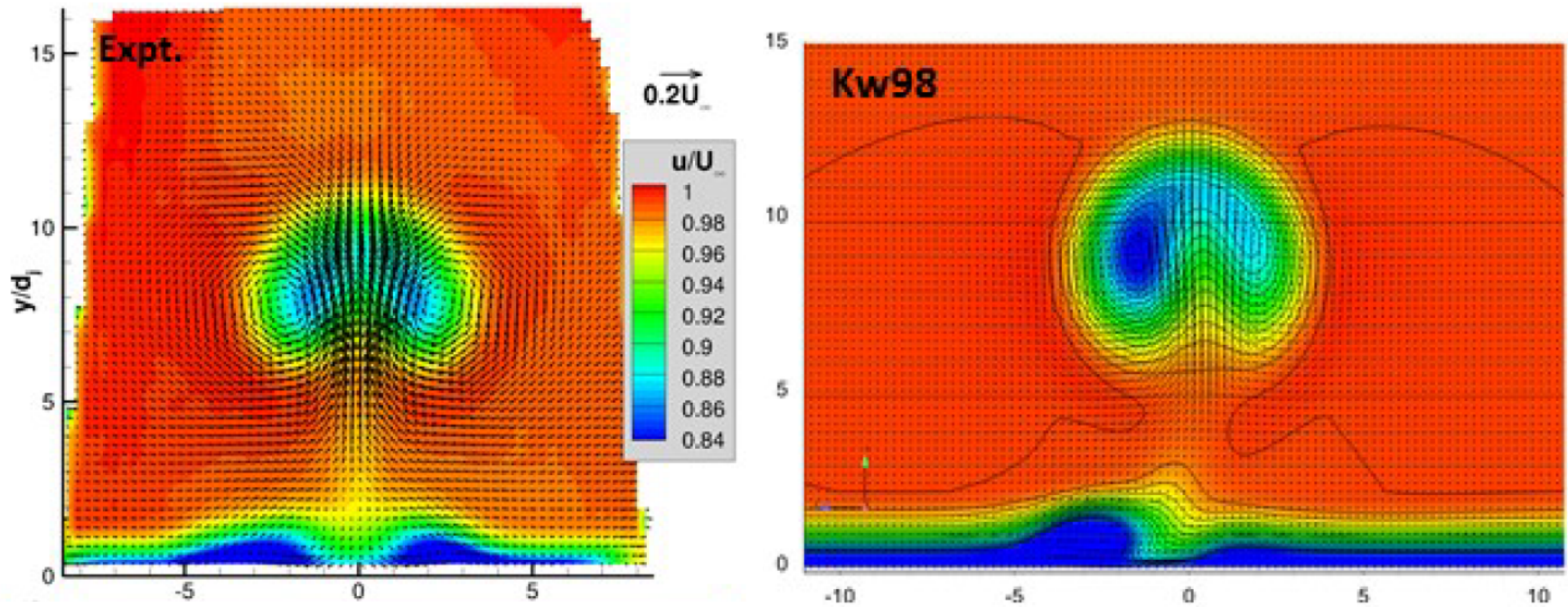
- Pose a statistical inverse problem using experimental data for flow-over-a-square-cylinder
  - Estimate parameters using Markov chain Monte Carlo
  - Construct a polynomial surrogate for square-cylinder RANS simulations

# Target problem - jet-in-crossflow

- A canonical problem for spin-rocket maneuvering, fuel-air mixing etc.
- We have experimental data (PIV measurements) and corresponding RANS simulations
- The RANS simulations have stability problems



# RANS (k- $\omega$ ) simulations - crossplane results



- Crossplane results for stream
- Computational results (SST) are too round; Kw98 doesn't have the mushroom shape; non-symmetric!
- Less intense regions; boundary layer too weak

# Flow over a square cylinder

## ■ Experimental data

- Water tunnel, 39 cm X 56 cm cross-section
  - Square-cylinder 4 cm per side
- 96 probes in the wake where  $\eta = u'v'$  are measured

## ■ Making the RANS training set

- Take 2744 ( $14^3$ ) samples from the  $(C_w, C_2, C_1)$  space
- Save  $\eta = u'v'$  at the 96 probes for each run

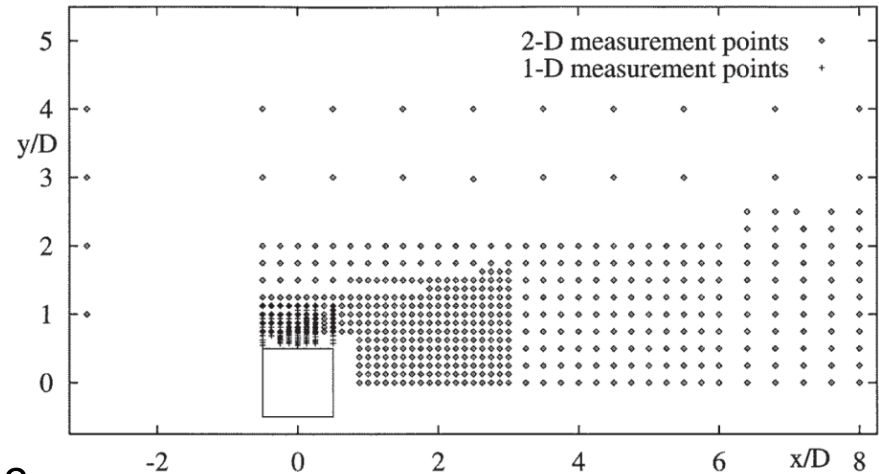


Figure 1: Coordinate system and location of measurement points.

# Surrogate models

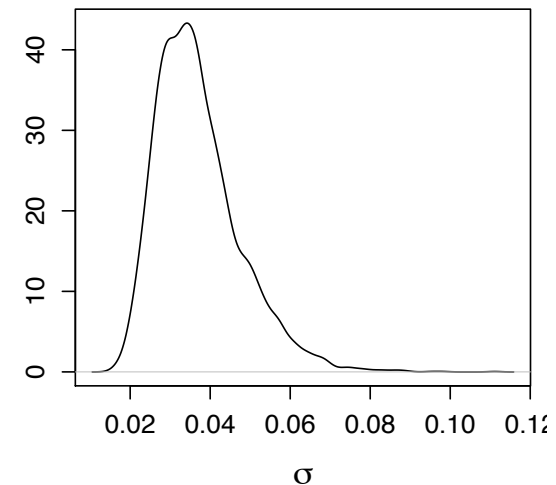
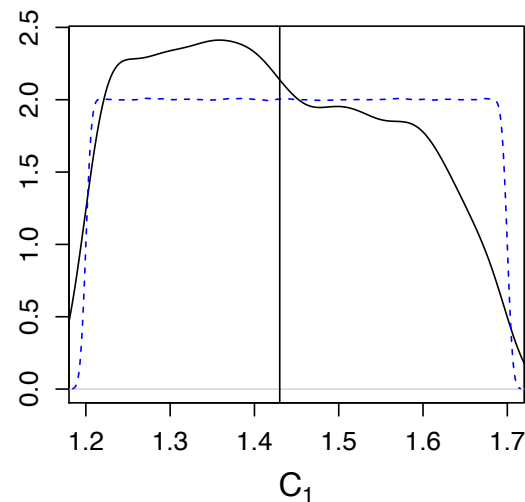
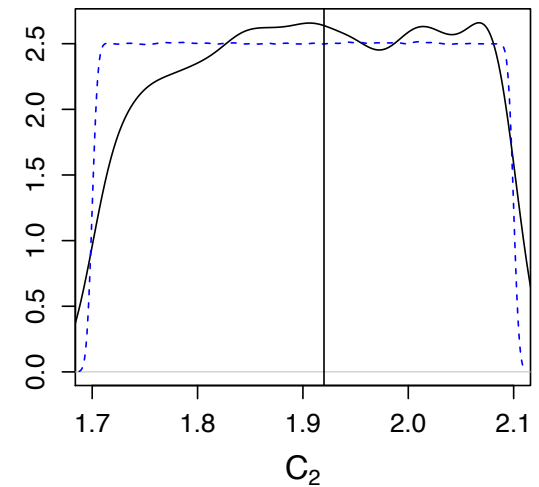
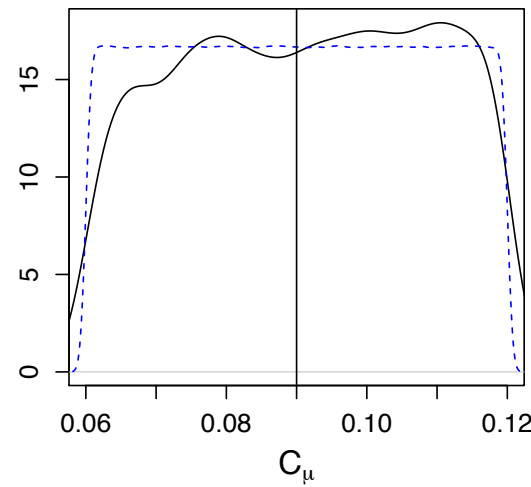
- Model  $\eta$  as a function of  $\mathbf{C}$  i.e.  $\eta = \eta(\mathbf{C})$ 
  - Approximate this dependence with a polynomial

$$\eta \cong \eta_{trend} = a_0 + a_1 C_\mu + a_2 C_2 + a_3 C_1 + a_4 C_\mu C_2 + a_5 C_\mu C_1 + a_6 C_2 C_1 + \dots$$

- Given  $\eta_{exp}$  at a bunch of probe locations, it should be possible to estimate  $\{C_\mu, C_2, C_1\}$  by fitting the polynomial model to data
- But how to get  $(a_0, a_1, \dots)$  for each of the probe locations to complete the surrogate model for each probe?
  - Divide training data in a Learning Set and Testing Set
  - Fit a full quadratic model for  $\eta$  to the Learning Set via least-squares regression; sparsify using AIC
  - Estimate prediction RMSE for Learning & Testing sets; should be equal
- Final model tested using 100-fold cross-validation

# MCMC solution for $(C_\mu, C_2, C_1)$

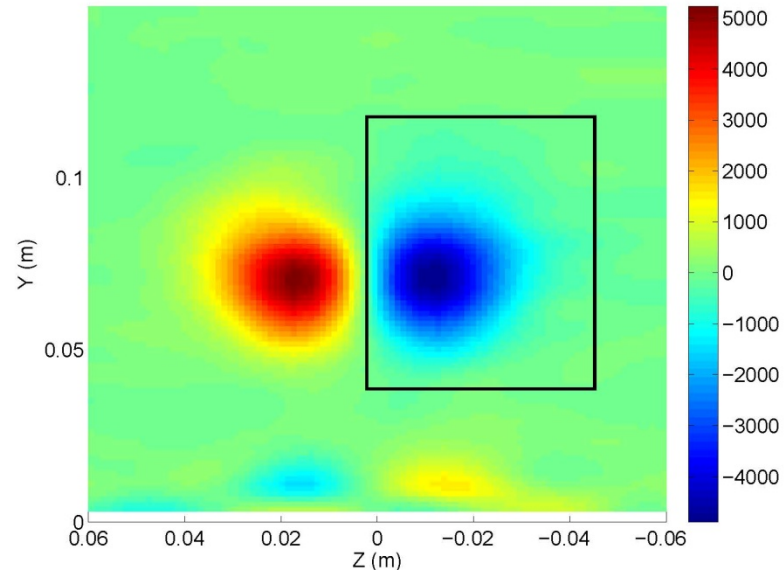
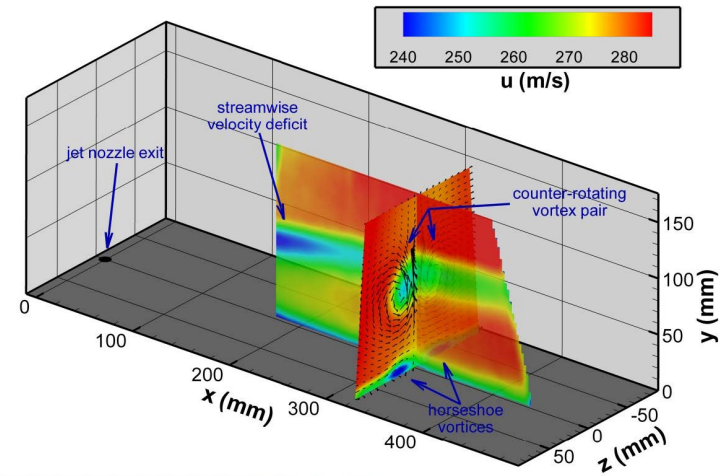
- Computed using an adaptive MCMC method (DRAM)
- These are marginals – the distribution is 4D
- Nominal values are vertical lines
- Blue dashed lines are prior beliefs
- The model error  $\sigma$  is large





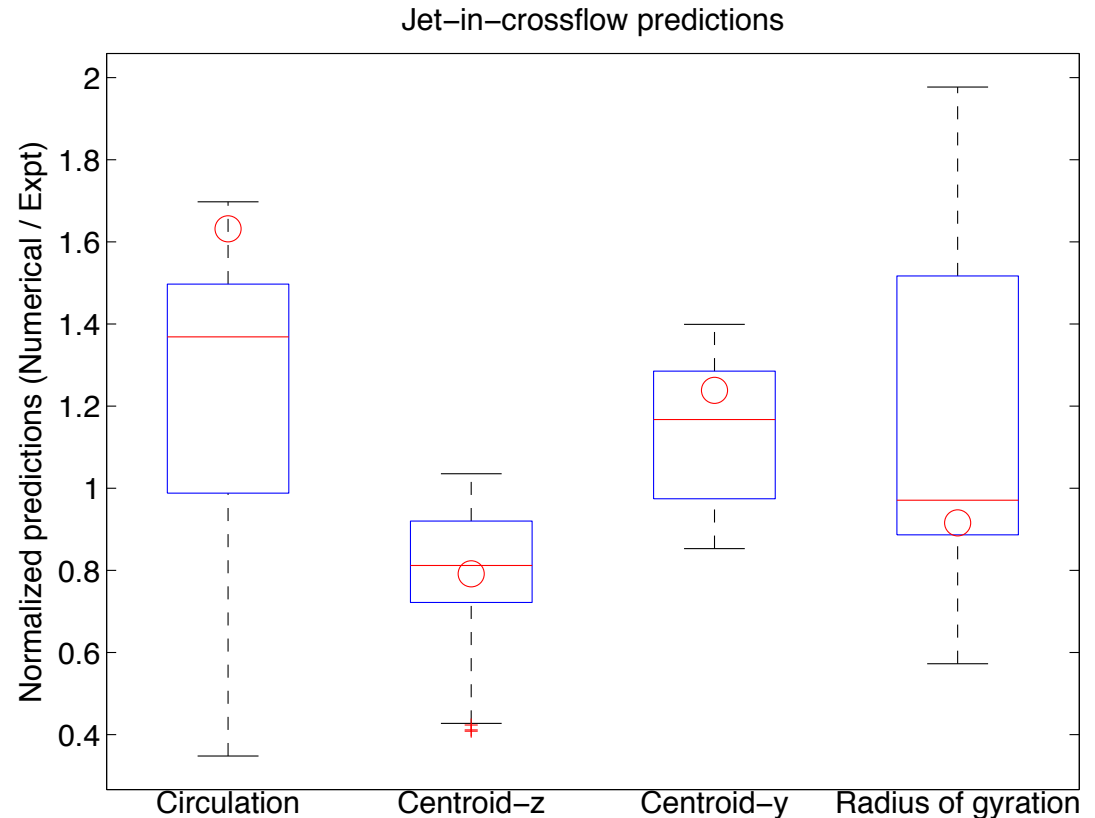
# Is the PDF predictive for jet-in-crossflow?

- Pick 100 C samples from the PDF
- Simulate jet-in-crossflow
- In the crossplane, quantify
  - Circulation
  - Centroid of vorticity
  - Radius of gyration
- From the ensemble, calculate median, quartiles etc
- Compare with experimental values

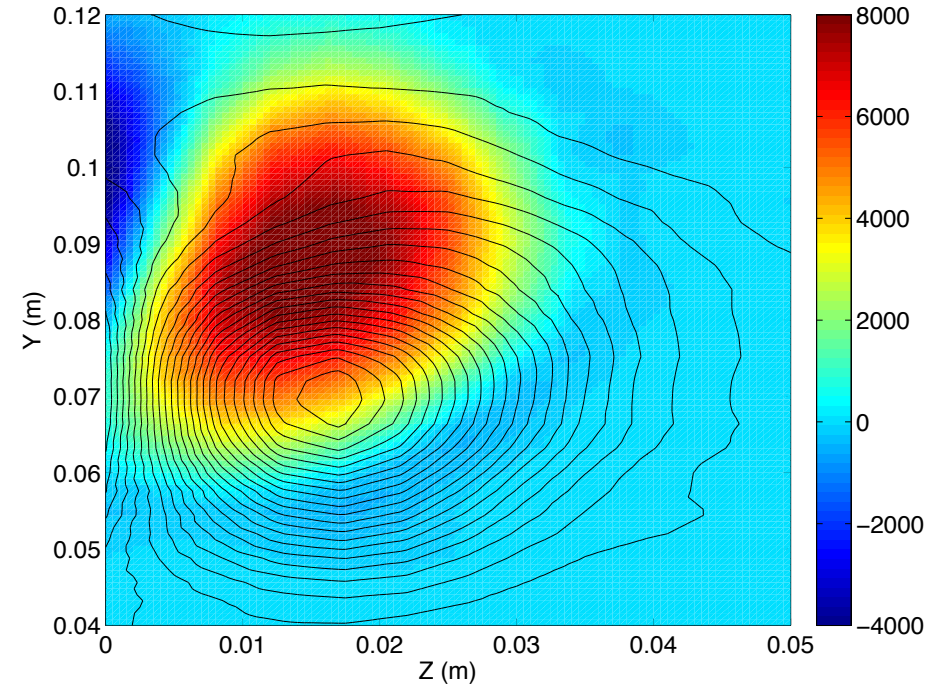


# Comparison of predictions and experiments

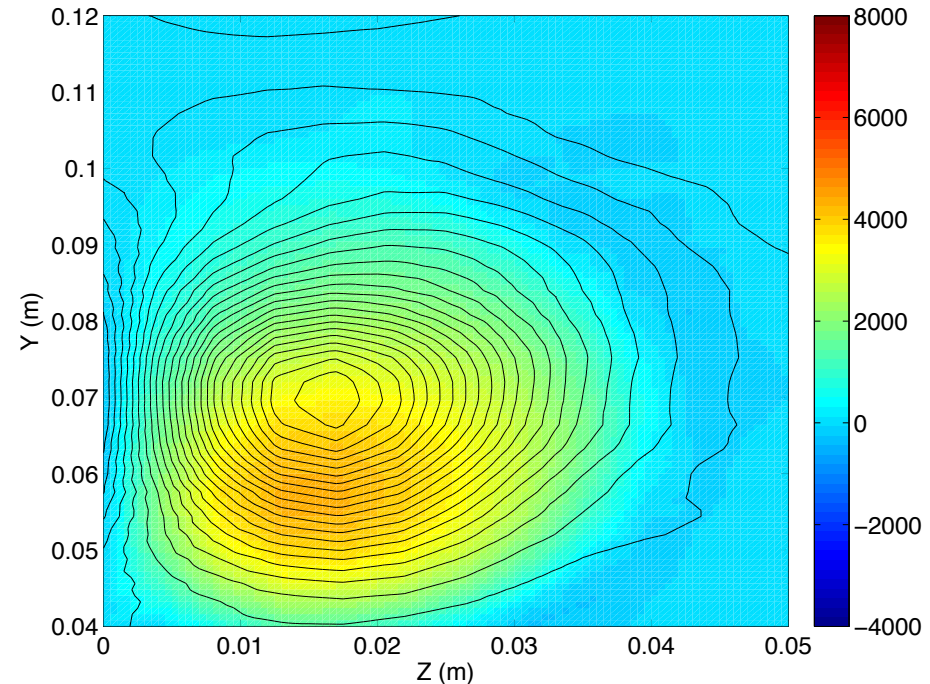
- Plotting Predictions / Experimental values
- We overpredict circulation
- Location is somewhat off
- Size is somewhat larger
- Big improvements over nominal value
- Also search the 100 ensemble members for best prediction
  - “Optimal” ensemble member



# Optimal ensemble member – vorticity



With nominal **C**

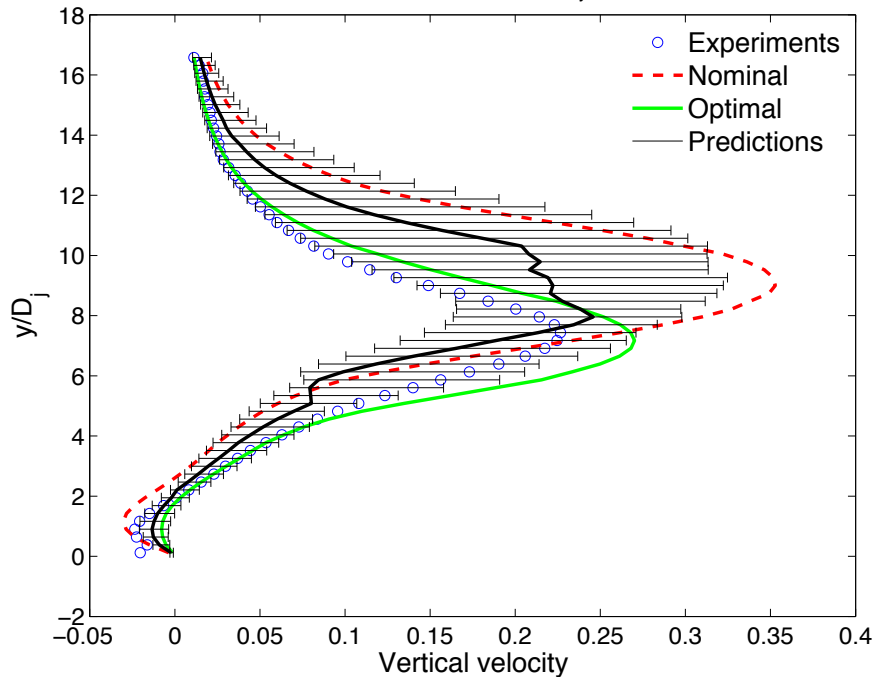


With best **C**

- Experimental vorticity as contours
- Calibration positions the vortex better; also gets its strength right
- The circulation, position and size are +/- 15% from experiments

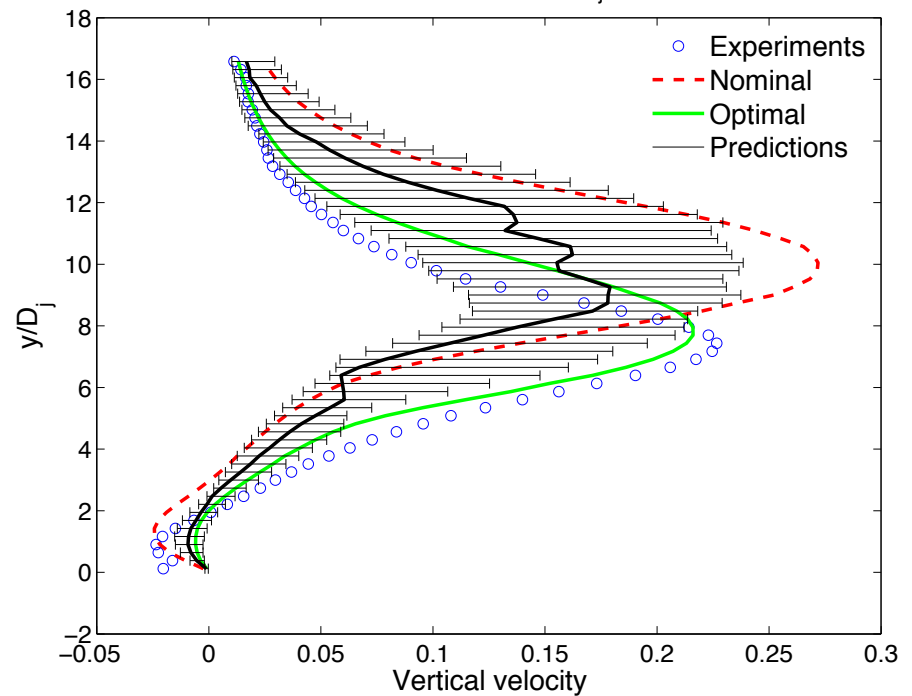
# Optimal ensemble member: w velocity

Predictions with IQR;  $x/D_j = 31.5$



$x/D = 31.6$

Predictions with IQR;  $x/D_j = 42.0$



$x/D = 42.0$

- Improvement over  $C_{\text{nominal}}$
- Nearly nailed the experiment

# Conclusions

- Our hypothesis of calibrating to a simple vortical flow for predictive jet-in-crossflow proved correct
- Even simple, polynomial surrogates were sufficiently accurate to allow us to calibrate RANS models
  - More elaborate models, with the deficit would probably do somewhat better
  - With surrogates come Bayesian calibration and PDFs of calibrated parameters
- Being able to get a PDF for  $(C_{\mu}, C_2, C_1)$  proved to be very convenient
  - Ensemble predictions provide error bars on predictions
  - They allow us to test various  $(C_{\mu}, C_2, C_1)$  combinations for predictive power
- *Details: S. Lefantzi, J. Ray, S. Arunajatesan and L. Dechant, "Tuning a RANS  $k-\varepsilon$  model for jet-in-crossflow simulations", Sandia Technical Report, SAND2013-8158*