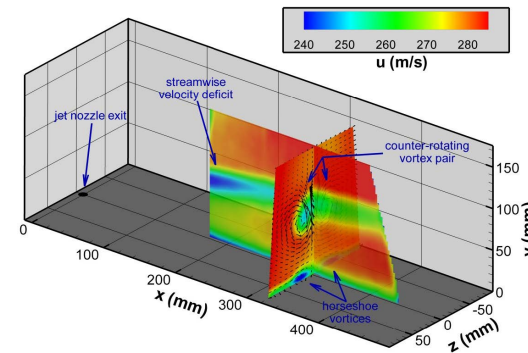
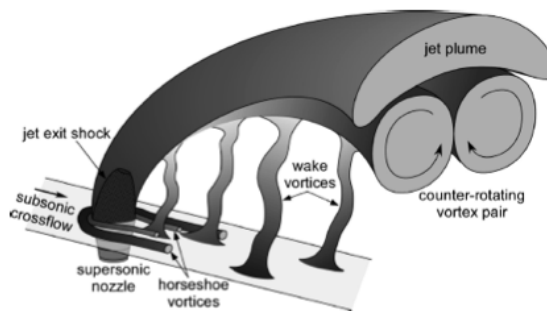


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Robust Bayesian calibration of a RANS model for jet-in-crossflow simulations

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Introduction

- **Aim:** Enable predictive RANS simulations of compressible jet-in-crossflow configurations (JIC)
- **Problem:** JIC simulations not very predictive; suffer from:
 - Model-form errors i.e., missing physics
 - Use of constants derived from incompressible canonical flows
- **Hypothesis:** Prediction errors are caused mostly by wrong constants
 - Calibration solves this problem (quantify estimation uncertainty!)
 - Fixing model-form error has a smaller effect
 - Approximate the new constant using an analytical model
 - i.e., show that the calibrated constants are physical, not just a “curve-fit”
 - Explore if there exists a calibration that works across a set of JIC configurations

The equations

- **The model**

- Devising a method to calibrate 3 k- ϵ parameters $\mathbf{C} = \{C_\mu, C_2, C_1\}$ from expt. data

$$\frac{\partial \rho k}{\partial t} + \frac{\partial}{\partial x_i} \left[\rho u_i k - \left(\mu + \frac{\mu_T}{\sigma_k} \right) \frac{\partial k}{\partial x_i} \right] = P_k - \rho \epsilon + S_k$$

$$\frac{\partial \rho \epsilon}{\partial t} + \frac{\partial}{\partial x_i} \left[\rho u_i \epsilon - \left(\mu + \frac{\mu_T}{\sigma_\epsilon} \right) \frac{\partial \epsilon}{\partial x_i} \right] = \frac{\epsilon}{k} (C_1 f_1 P_k - C_2 f_2 \rho \epsilon) + S_\epsilon$$

$$\mu_T = C_\mu f_\mu \rho \frac{k^2}{\epsilon}$$

- **Calibration parameters**

- $\mathbf{C} = \{C_\mu, C_1, C_2\}$; C_μ : affects turbulent viscosity; C_1 & C_2 : affects dissipation of TKE

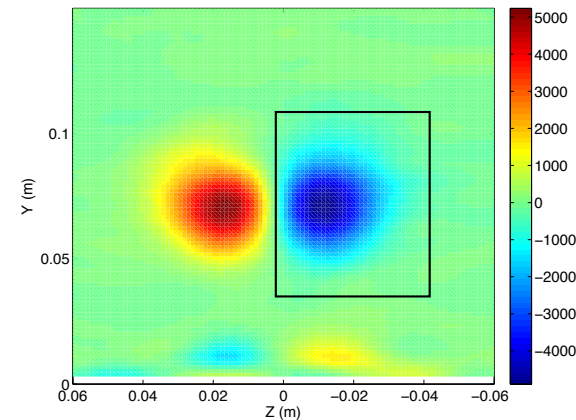
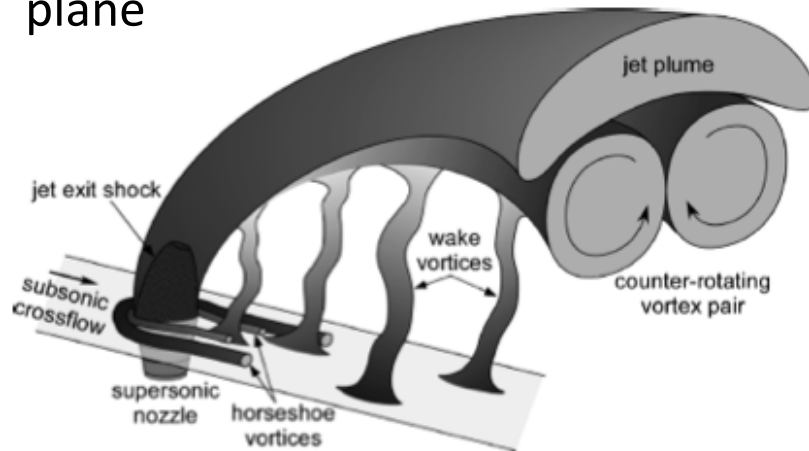
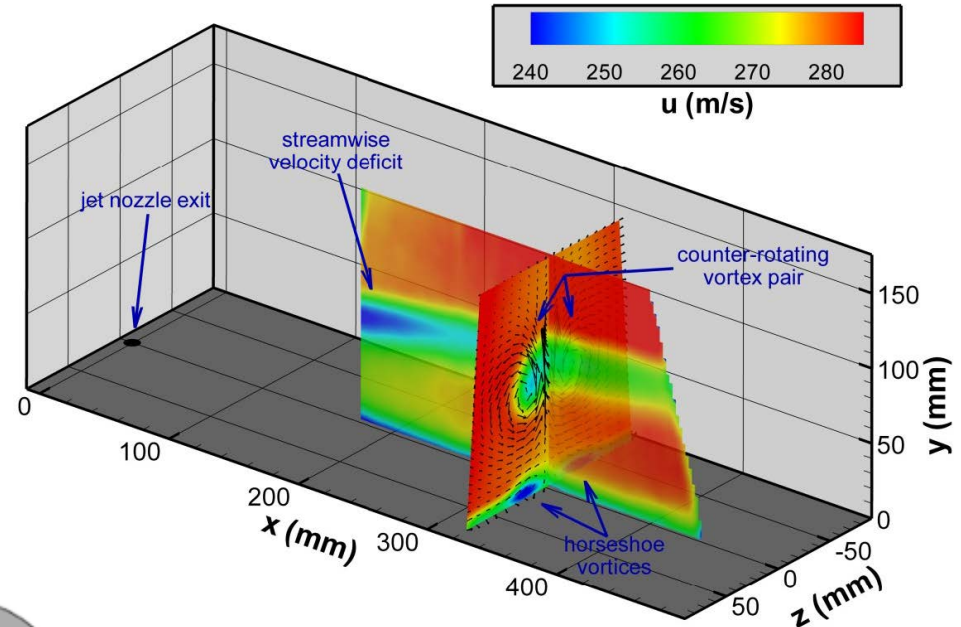
- **Model-form error**

- $-\tau_{ij} = -\overline{u'_i u'_j} = \frac{2}{3} k \delta_{ij} - \nu_T S_{ij} + \nu_T \frac{k}{\epsilon} \sum_{l=1}^3 c_l f_l(S, \omega) + \nu_T \left(\frac{k}{\epsilon} \right)^2 \sum_{l=4}^7 c_l f_l(S, \omega)$

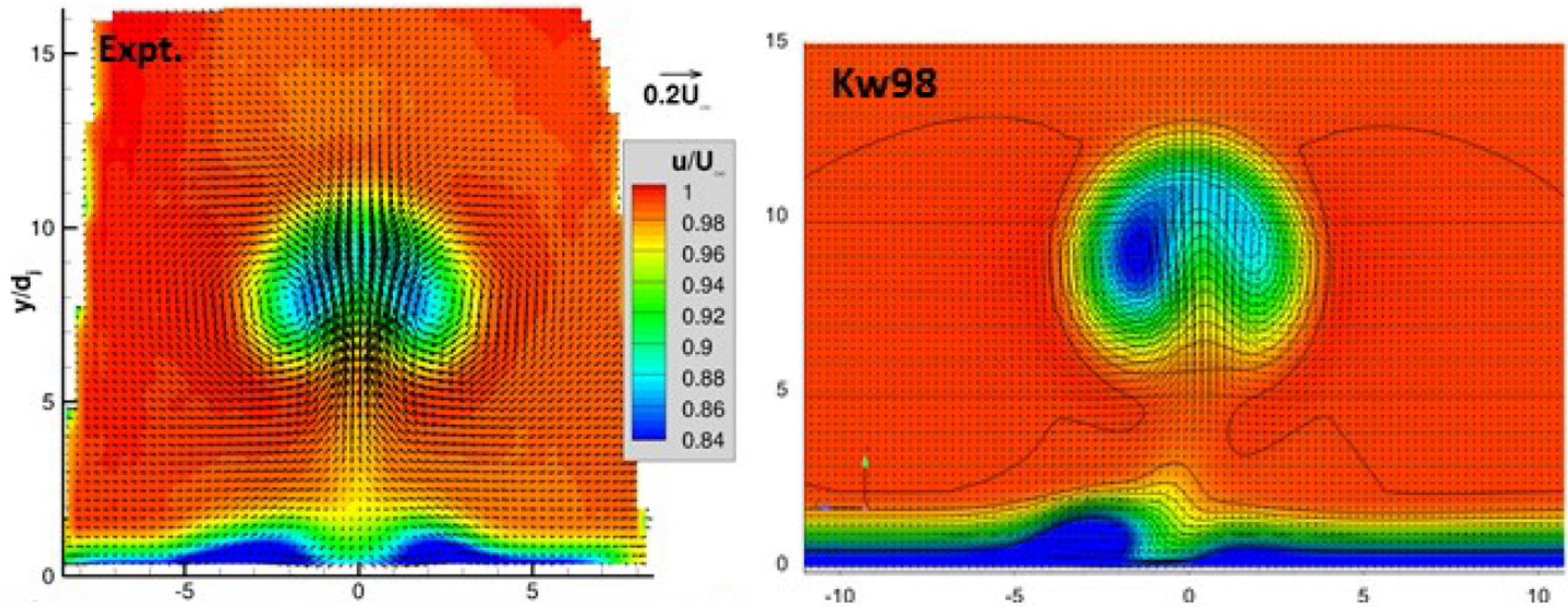
- Currently only linear terms are used (linear eddy viscosity model, LEVM); does adding more terms help in increasing prediction accuracy?

Target problem - jet-in-crossflow

- A canonical problem for spin-rocket maneuvering, fuel-air mixing etc.
- We have experimental data (PIV measurements) on the cross- and mid-plane
- Will calibrate to vorticity on the crossplane and test against mid-plane



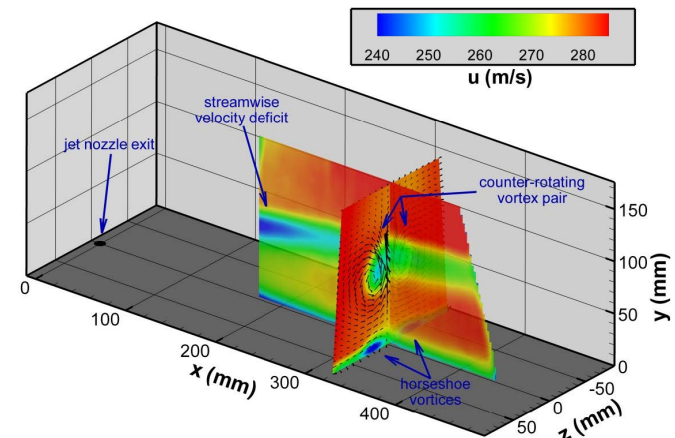
RANS (k- ω) simulations - crossplane results



- Crossplane results for stream
- Computational results (SST) are too round; Kw98 doesn't have the mushroom shape; non-symmetric!
- Less intense regions; boundary layer too weak

Calibration

- **Bayesian calibration – Develop a PDF for (C_μ, C_2, C_1)**
 - Captures the uncertainty in the estimation
 - Will be performed for 4 (Mach, J) combinations, to see how generalizable the calibration is
- **We pose the calibration as a statistical/Bayesian inverse problem**
 - Solve it using Markov chain Monte Carlo (MCMC)
 - Requires $O(10^4)$ samples/generations to give converged PDFs
 - Implies $O(10^4)$ invocations of the forward problem
 - Samples taken sequentially, not concurrently, so takes a long time
- **Observational data for calibration: velocity measurements (PIV) on the midplane**
 - 5 streamwise locations with 63 measurement points per location ~ 315 “probes”
- **Observational data for testing: vorticity measurements on the crossplane**



The Bayesian calibration problem

- Model experimental values at probe j as $v_{ex}^{(j)} = v^{(j)}(\mathbf{C}) + \varepsilon^{(j)}$, $\varepsilon^{(j)} \sim \mathcal{N}(0, \sigma^2)$

$$\Lambda(\mathbf{v}_{ex} | C) \propto \prod_{j \in P} \exp\left(-\frac{\left(v_{ex}^{(j)} - v^{(j)}(C)\right)^2}{2\sigma^2}\right)$$

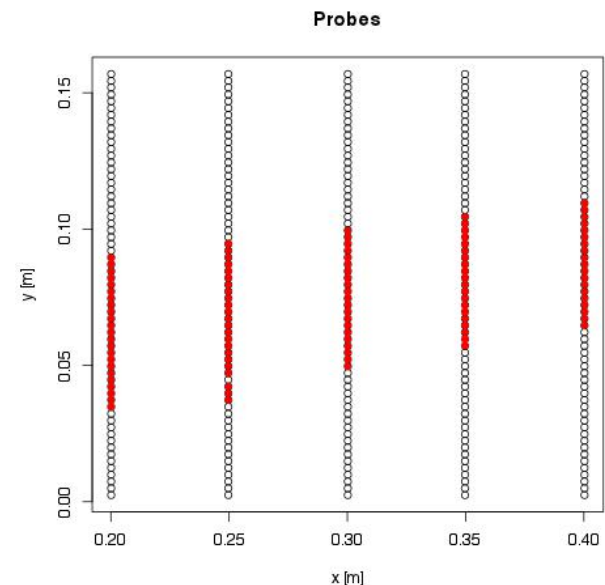
- Given prior beliefs π on \mathbf{C} , the posterior density ('the PDF') is

$$P(C, \sigma | \mathbf{v}_{ex}) \propto \Lambda(\mathbf{v}_{ex} | C) \pi(C, \sigma)$$

- $P(\mathbf{C} | \mathbf{v}_{ex})$ is a complicated distribution that has to be visualized by drawing samples from it
- This is done by MCMC
 - MCMC describes a random walk in the parameter space
 - Each step of the walk requires a model run to check out the new parameter combination

Forward model and surrogates

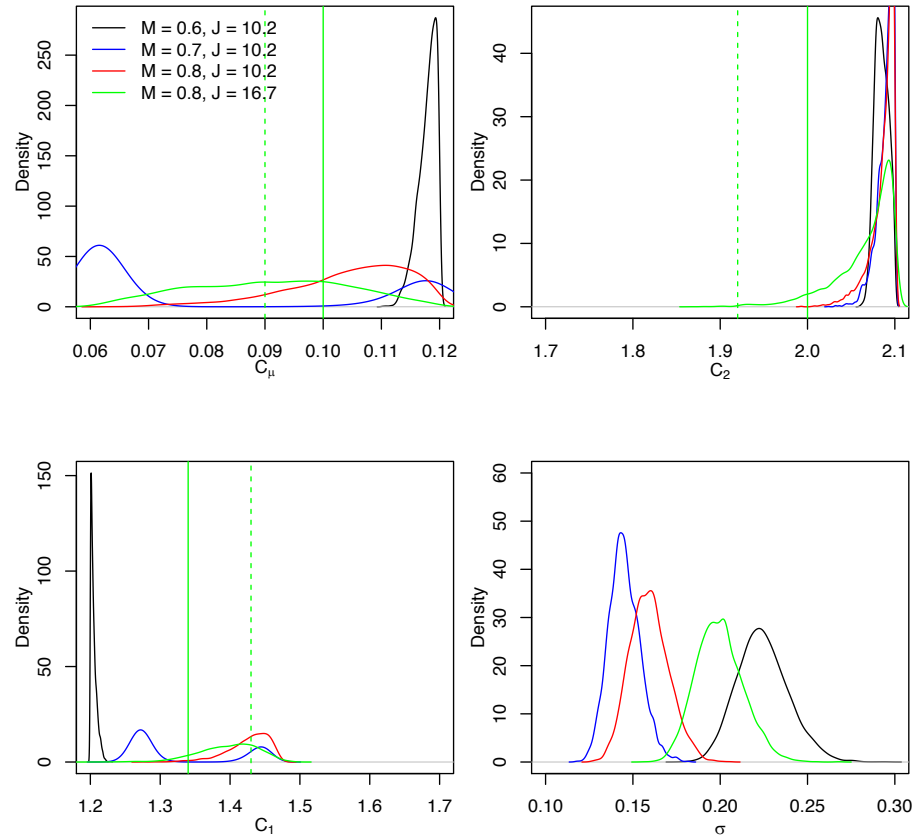
- 3D, finite volume, unsteady Roe solver
 - 10^7 mesh, 10^4 CPU hours to steady state. Can't be used in MCMC
- Surrogate models: A “curve-fit” replacement for aero solver
 - $v^{(j)} = a^{(j)}_0 + a^{(j)}_1 C_\mu + a^{(j)}_2 C_2 + a^{(j)}_3 C_1 + a^{(j)}_4 C_\mu C_2 + a^{(j)}_5 C_\mu C_1 + \dots$
- Making surrogates
 - Generate ~ 5000 (C_μ , C_2 , C_1) samples (bounds are known); run RANS
 - For the rest, OLS fitting for $a^{(j)}_i$
 - Simplify using AIC
 - If within 10% of RANS, accept surrogate as being “accurate enough”
- Usually left with ~ 50 / 315 probes where we can make sufficiently good surrogates



All probes. Those with surrogates are in red and track the jet

Solution of the inverse problem

- We estimated $\mathbf{C} = (C_\mu, C_2, C_1)$ for 4 (M, J) cases
 - $M = [0.6, 0.7], J = 10.2$
 - $M = 0.8, J = [10.2, 16.7]$
- A few commonalities
 - C_2 is higher than nominal
 - C_1 (nominal) is probably OK
 - C_μ ?? – probably does not affect mean flow much and is not constrained by it
- σ show that
 - $M = 0.7$ case probably best fit
 - $M = 0.6$ case worst fit

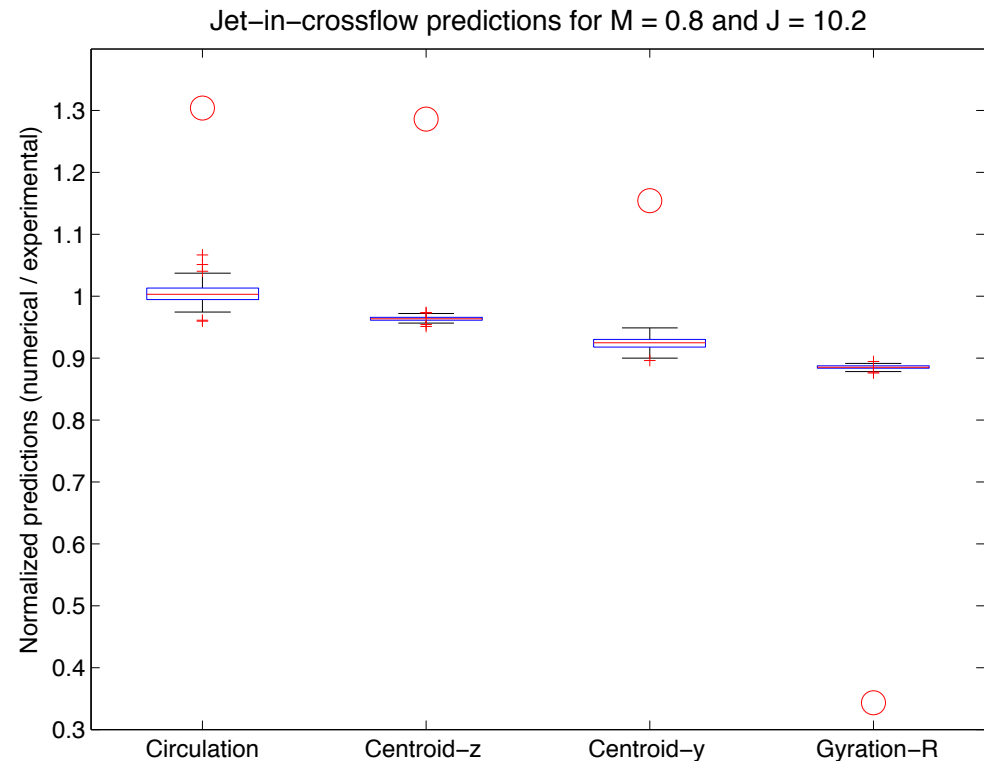


Vertical green lines:

- Dashed: nominal value
- Solid: Analytical model's estimate

Check # 1 – point vortex summary

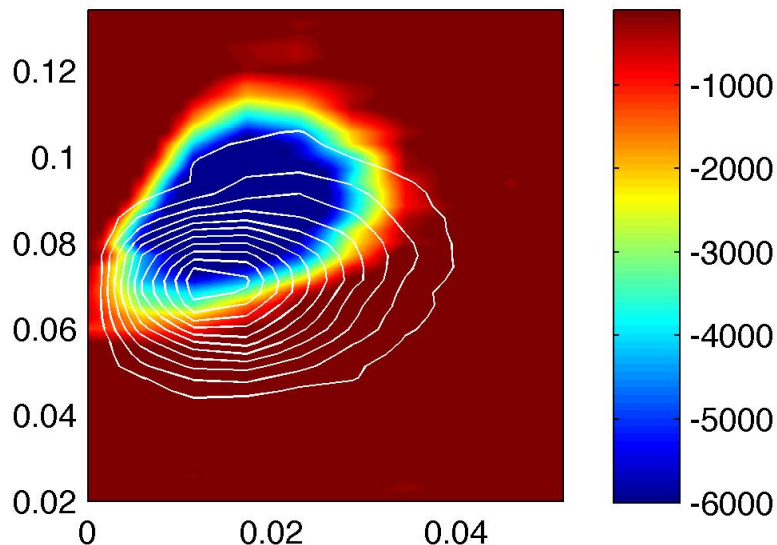
- Same 100 \mathbf{C} from the PDF, run them forward
- Use the crossplane vorticity fields from the ensemble to compute
 - Total circulation, centroid of vorticity field, radius of gyration of vorticity field
 - Normalize each by their experimental counterpart
- We expect to get an ensemble of values for each metric around 1
 - We also find a $\mathbf{C}_{opt} = \{0.1025, 2.09, 1.42\}$ that provides the best predictions



The spread of point vortex summaries are tightly distributed around 1. The red circles are the predictions from the nominal values of \mathbf{C}

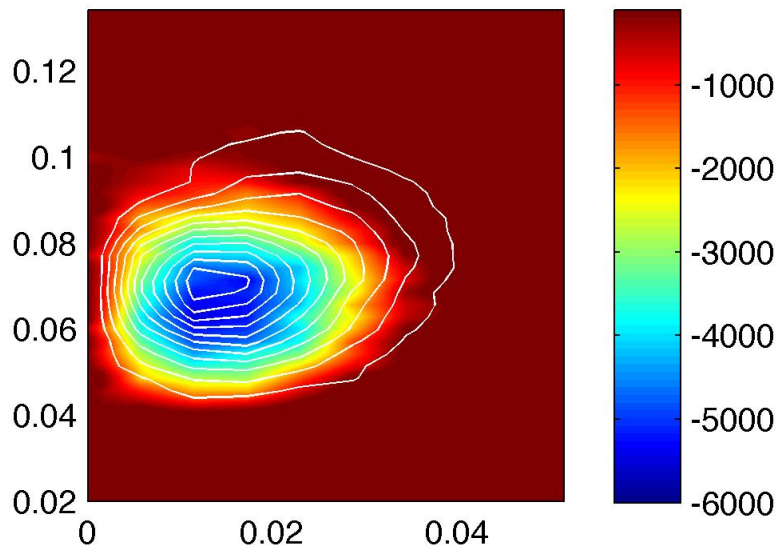
Check # 2 – the vorticity field

Vorticity (nominal case); $J = 10.2$



RANS predictions with C_{nom}

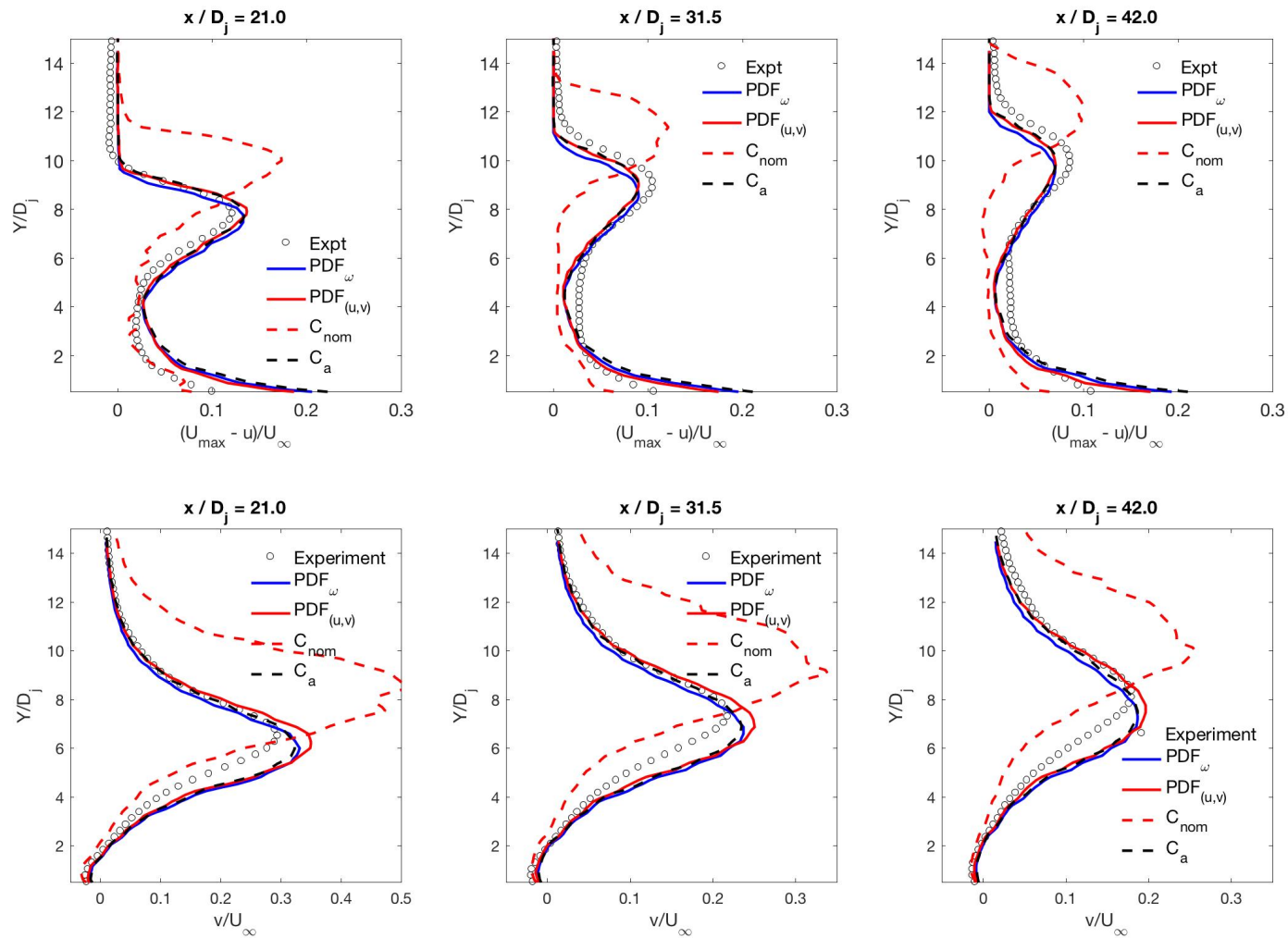
Vorticity (best case); $J = 10.2$



RANS predictions with C_{opt}

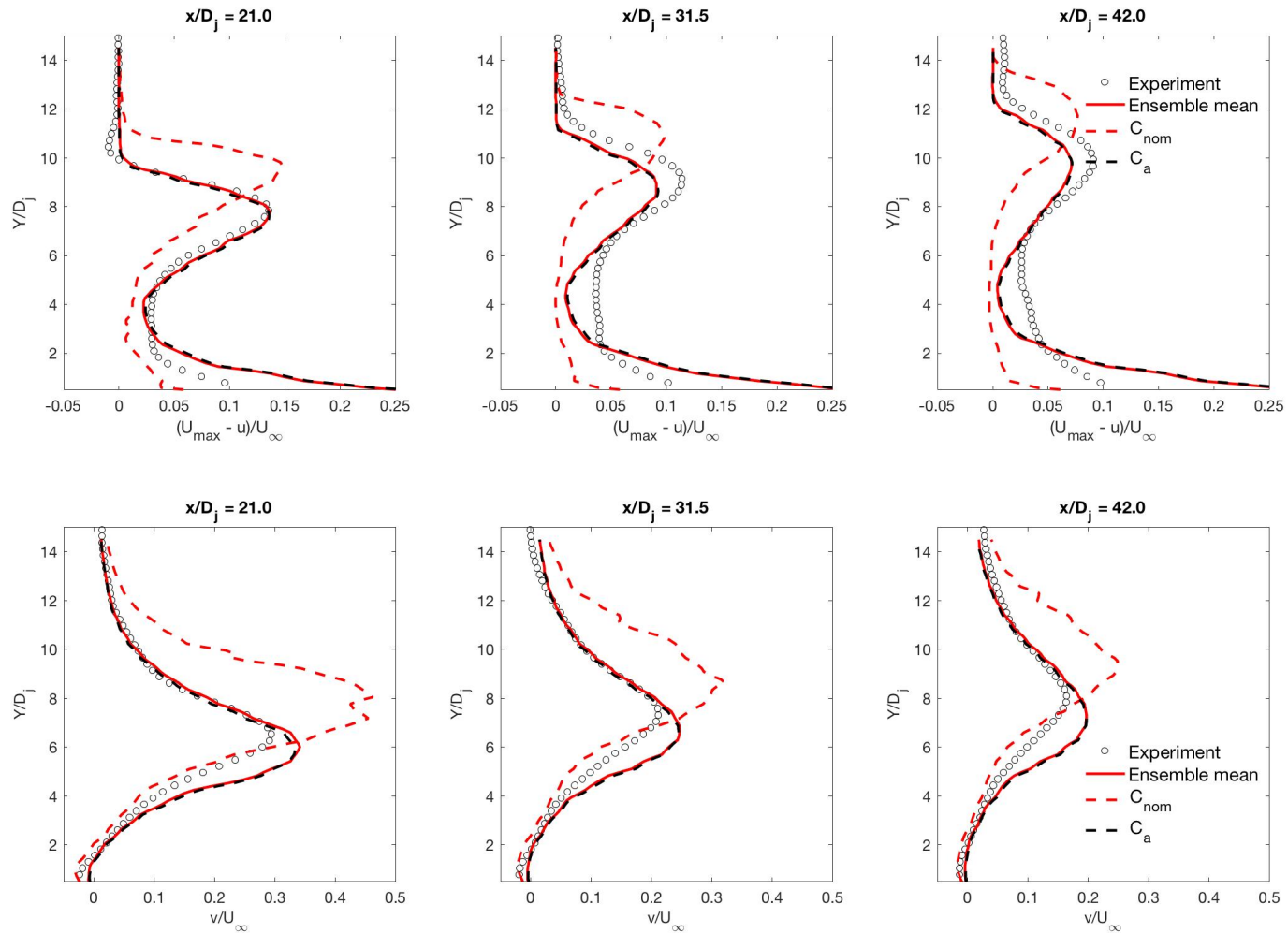
- Contours are plotted using the experimental measurements
- The improvement is significant

Check # 3 – mid-plane comparisons



- $M = 0.8, J = 10.2$, case

Check # 4 – $M = 0.7$ case



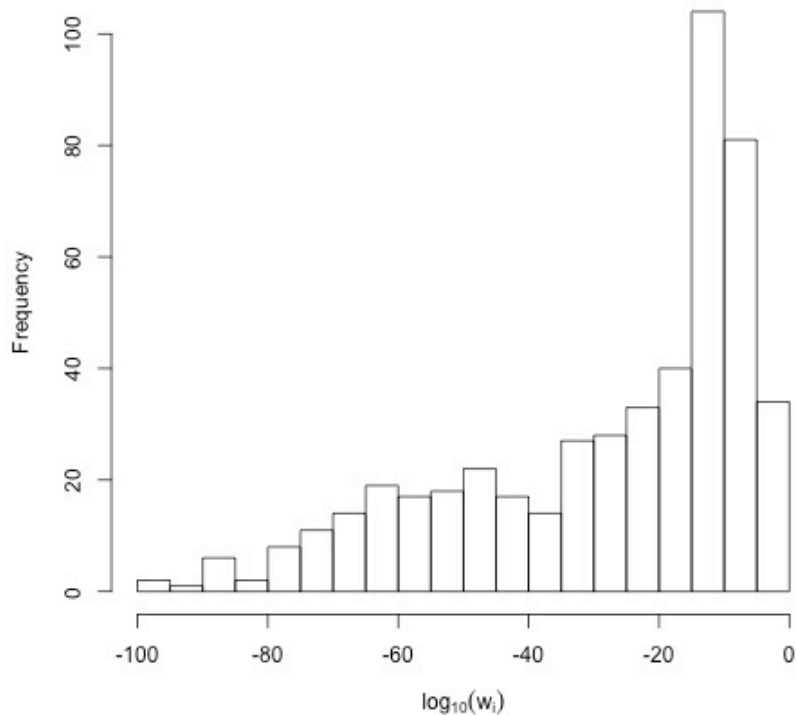
- $M = 0.7, J = 10.2$

Combining PDFs

- The 4 PDFs have overlaps
 - Could (C_μ, C_2, C_1) samples from the overlap region be predictive for all 4 cases?
- Take 100 samples each from the 4 PDFs; simulate all 4 cases with them
 - Call each RANS run, seeded with a (C_μ, C_2, C_1) sample, a separate “model”
 - We have an ensemble of 400 models
- Could a weighted average of 400 models reproduce experimental velocities for all 4 cases? BMA!
 - If yes, then the weights of each model i.e., (C_μ, C_2, C_1) combination, could be used to make a PDF over them
 - That becomes a PDF that’s useable for all 4 cases
 - But only if they cluster in a region, to make a unimodal PDF

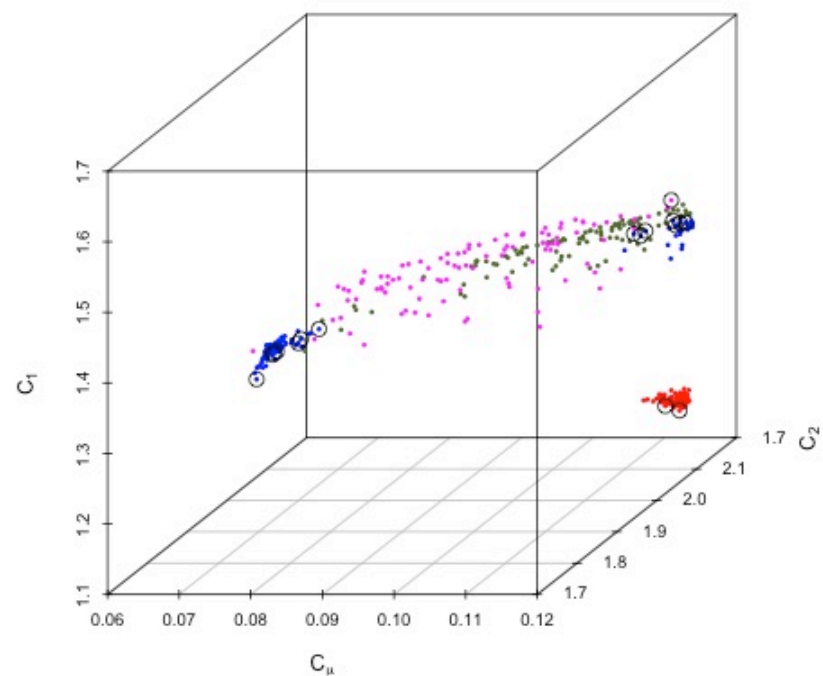
Combining PDFs - results

Histogram of $\log_{10}(w)$



Histogram of model weights

BMA training samples and selected models



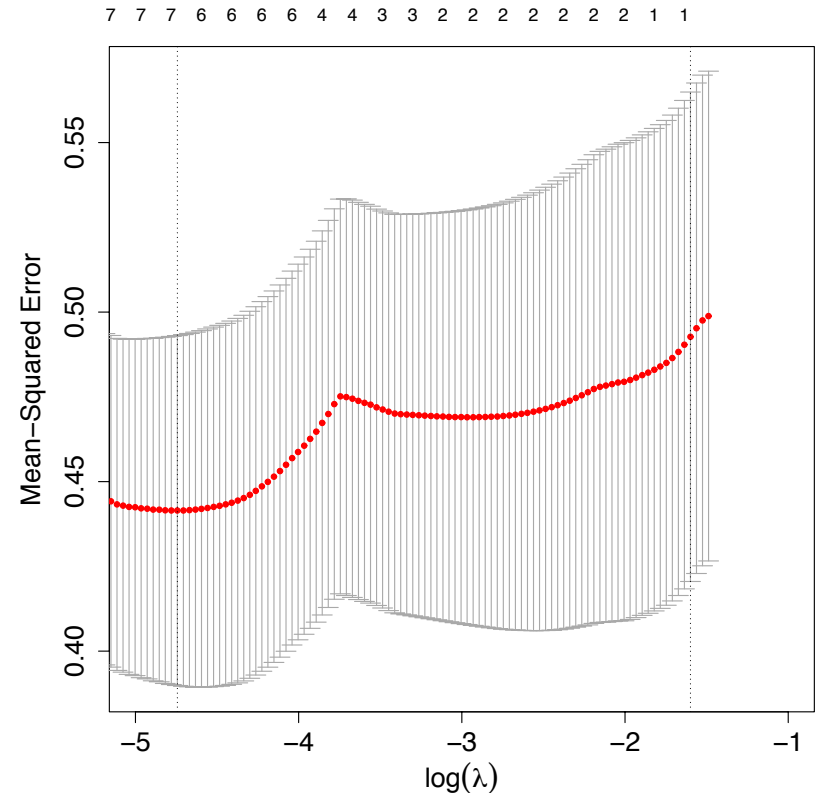
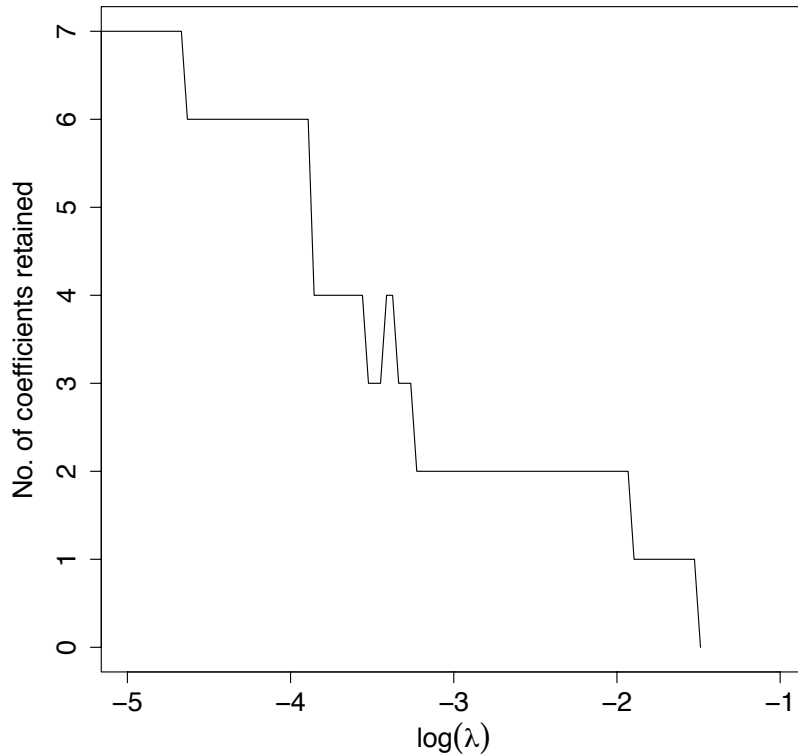
400 \mathbf{C} samples, colored by the PDF they were drawn from

- 22/400 account for 99.9% of the probability mass
- They don't cluster. **Failed!**

Model-form error

- Hypothesis: The simple form of the EVM is responsible for lack of predictive skill
 - Can enriching it fix the problem?
 - $-\tau_{ij} = -\overline{u'_i u'_j} = \frac{2}{3}k\delta_{ij} - \nu_T S_{ij} + \nu_T \frac{k}{\epsilon} \sum_{l=1}^3 c_l f_l(S, \omega) + \nu_T \left(\frac{k}{\epsilon}\right)^2 \sum_{l=4}^7 c_l f_l(S, \omega)$
 - We do have estimates of c_l from incompressible canonical flow
 - Which terms do we include? We don't have enough expt data to estimate all 7 terms
- Pose a shrinkage problem
 - We have measurements of k, S, ω and τ_{ij} on the midplane; no ϵ
 - Approximate ϵ as Production = destruction
 - $\min_{\mathbf{c}} \|\tau_{ij} - \mathbf{A}(k, \epsilon, S, \omega)\mathbf{c}\|_2^2 + \lambda \|\mathbf{c}\|_1$
 - This will retain only those c_l that are supported by observations
- Note that the values of c_l so obtained are not trustworthy

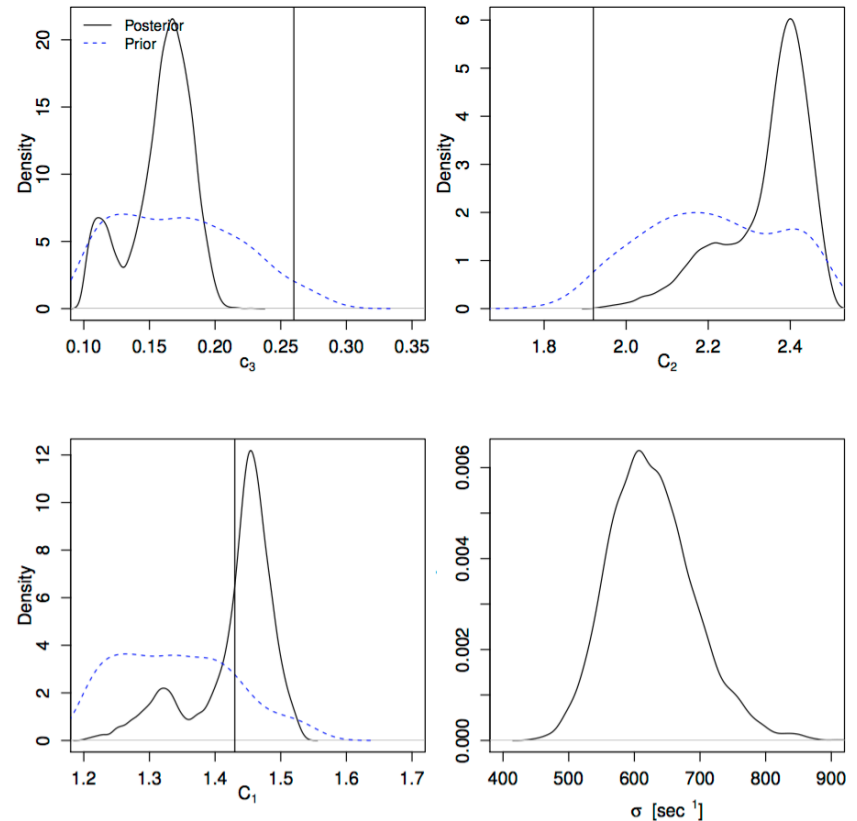
Model-form error results



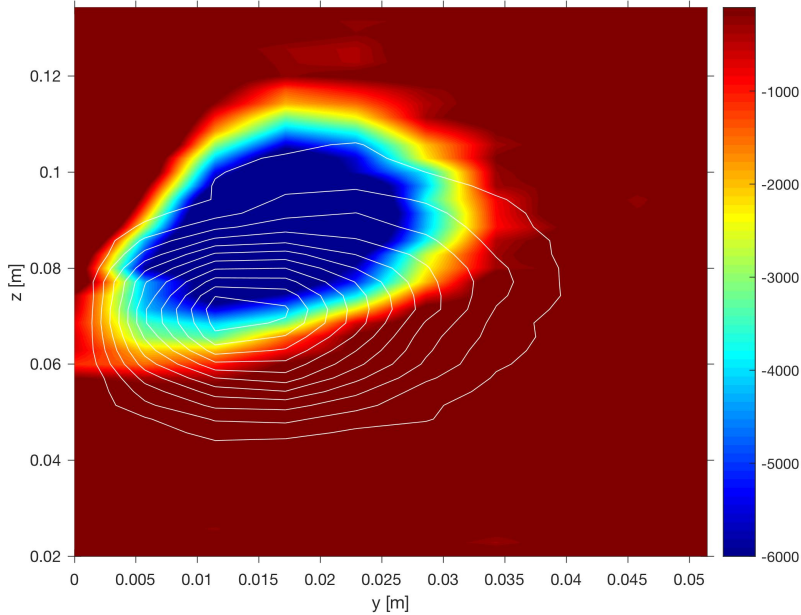
- Good value of λ obtained via 7-fold cross-validation
- Final chosen value of λ retains one extra quadratic term (ω^2) in the EVM

Calibrating QEVM

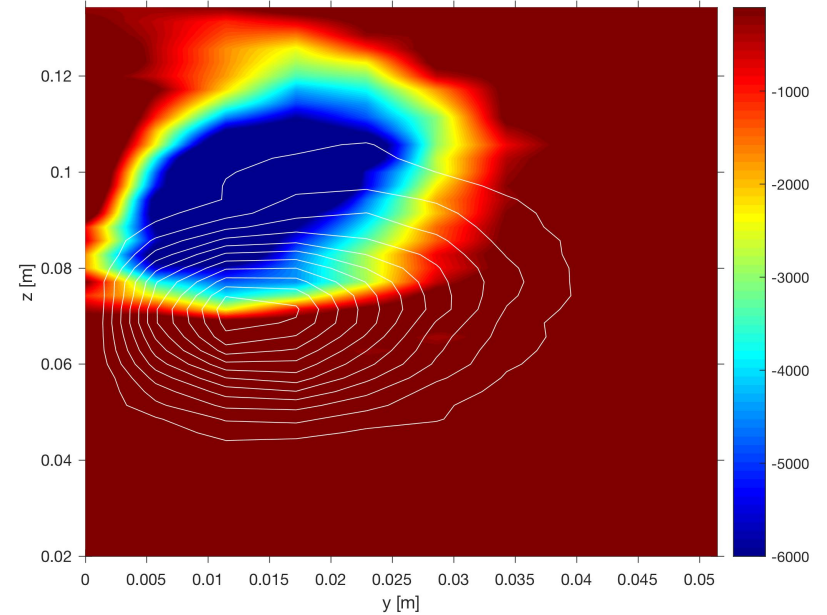
- While we have an enriched EVM, we still have a problem values of constants
- Calibration shows (again) that appropriate values of C_2 are different from nominal
 - And C_1 is close to OK
- We'll check the calibration via a "pushed-forward posterior"



Vorticity, crossplane



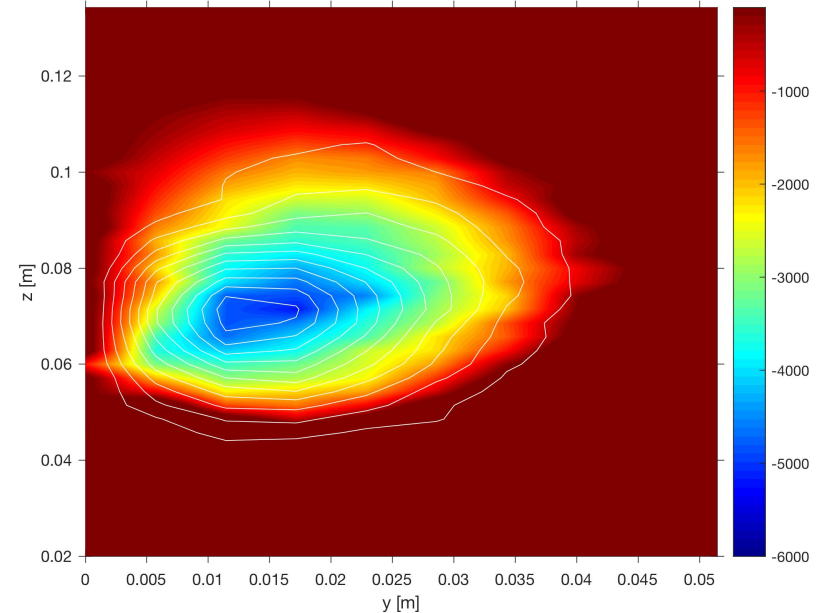
Uncalibrated, CEVM



Uncalibrated, LEVM

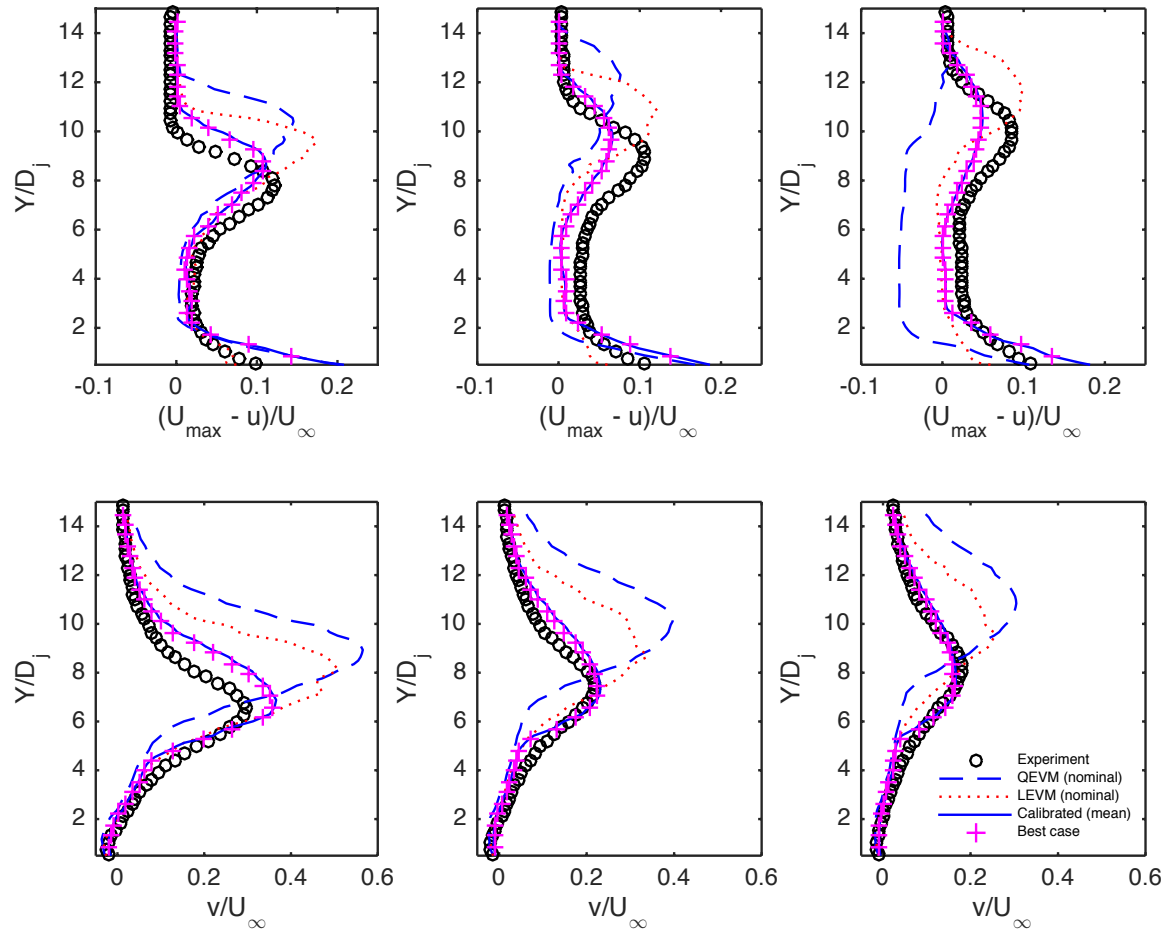
Calibrated, QEVM

- Experiments: Contours
- Significant improvement



Velocities, midplane

- Velocities on the mid plane match experiments, after calibration
- Neither QEVM and LEVM, before calibration, are predictive



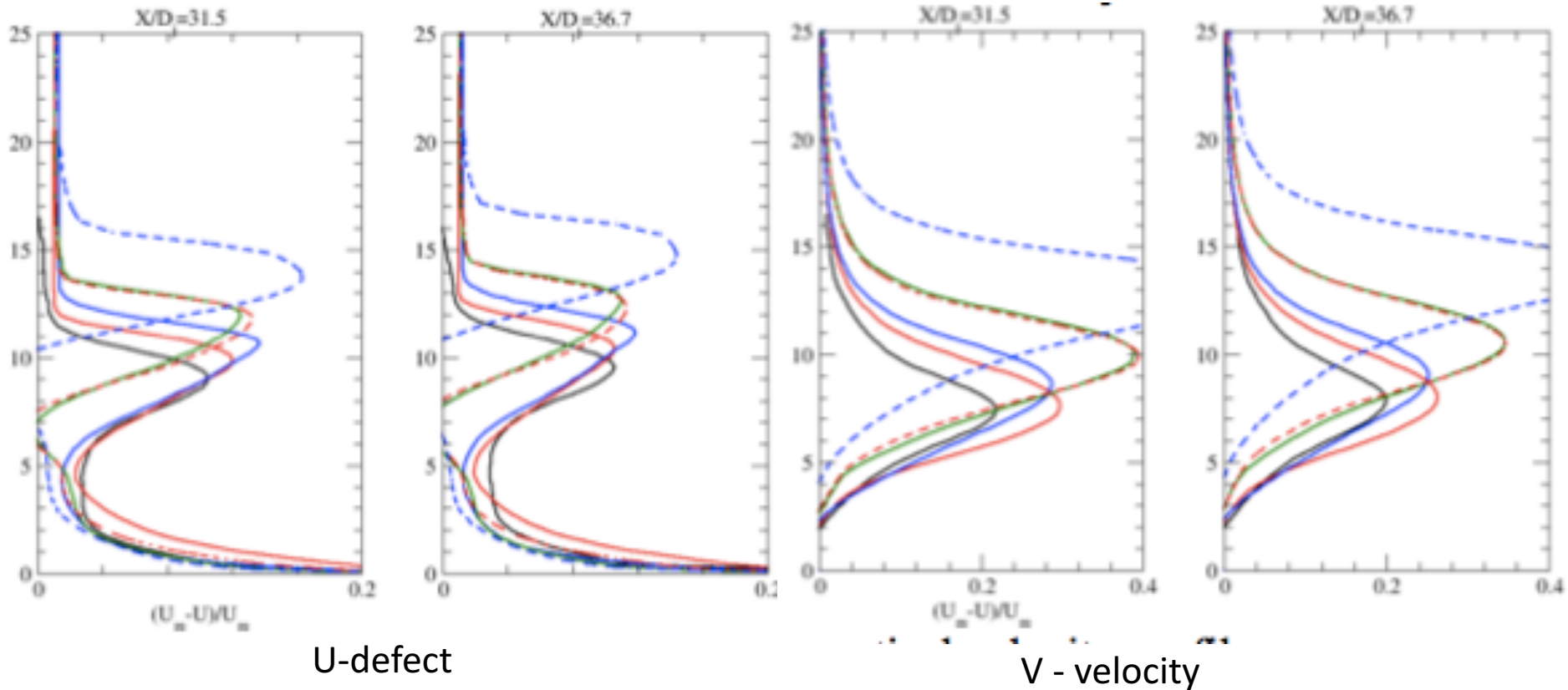
- We have shown how Bayesian calibration improves predictive skill
 - New (C_{μ} , C_2 , C_1) could be a mere artefact to fitting to data; may have no physical significance
 - But analytical model predictions very close to predictions with C_{opt}
 - Next talk: $C_{\text{opt}} \sim C_{\text{analytical}}$
 - Our calibration *does* yield physically realistic constants
- We've also explored enriching the LEVM, but no great improvements
 - For this particular configuration, it does not seem to be about model-form errors, but inappropriate constants
 - Dechant (next talk) will show how and why the calibrated constants are the good ones

Conclusions

- We have explored the causes behind non-predictive JIC RANS computations
 - We think we should be using very different constants
 - We inferred the “good” values of the constants via Bayesian calibration
 - Calibrated PDFs more accurate than the nominal values
 - Also, calibration supported via analytical verification
- We addressed model-form error too
 - In this case, the inappropriate constants overwhelmed model-form error
 - Regardless, the model-form error exists, and manifests itself in the turbulent stresses
 - They don’t match measurements

BACKGROUND

RANS (k- ω) simulations – midplane results



- Experimental results in black
- All models are pretty inaccurate (blue and red lines are the non-symmetric results)