Feature Importance with Deep Echo State Models for Long-Term

Introduction

Long term forecasting Recent work has proposed the use of deep ensemble echo-state network (D-EESN) models for long term forecasting with spatiotemporal data [1][2]. D-EESN models are more computationally efficient than other current statistical methods for spatio-temporal forecasting. D-EESN models use reservoir computing, where parameters are fixed or sampled from a random distribution instead of estimated.

Disadvantage D-EESN models possess a common disadvantage of machine learning models: model parameters are not interpretable in the context of the application.

Explanability We are interested in developing "explainability" methods to understand the relationships in the data used by D-EESN models for prediction.

Climate Application

Climate Security Motivation Climate change is considered a serious national and global threat and measures such as solar climate interventions are becoming a real possibility. The development of algorithmic methods for understanding the impact of such events on climate change will help to inform decision makers.

Mount Pinatubo 1991 eruption of Mount Pinatubo used as an example climate event to develop algorithmic approaches for characterizing climate impacts. Figure below shows impact of eruption on surface temperature leading to a decrease for several years after eruption (ERA5 reanalysis data [3]).



Change in average surface temperature



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Background

Permutation feature importance (PFI) **PFI for** X_i is average change in model performance when X_i is randomly permuted:

$$\mathscr{I}_{j} = m - rac{1}{K} \sum_{k=1}^{K} m_{j,k}$$

where *m* is model performance on observed data and $m_{i,k}$ is model performance when X_i is randomly permuted for repetition $k \in \{1, ..., K\}$ (Quadratic) Echo State Network Single layer version of D-EESN model for a spatio-temporal data Z_t (only V_1 and V_2 are estimated):

Data stage: $\mathbf{Z}_t \approx \mathbf{\Phi} \boldsymbol{\alpha}_t$ (empirical orthogonal function decomposition) Output stage: $\alpha_t = V_1 h_t + V_2 h_t^2 + \epsilon_t$; $\epsilon_t \sim Gaussian(\mathbf{0}, \sigma_{\epsilon}^2 \mathbf{I})$ Hidden stage: $\mathbf{h}_t = g_h \left(\frac{\nu}{|\lambda_u|} \mathbf{W} \mathbf{h}_{t-1} + \mathbf{U} \mathbf{\tilde{x}}_t \right)$

where $\tilde{\mathbf{x}}_t = \left[\mathbf{x}'_t, \mathbf{x}'_{t-\tau^*}, ..., \mathbf{x}'_{t-m\tau^*}\right]'$ is the embedding vector (τ^* is embedding vector lag and *m* embedding vector length) and

> $\mathbf{W} = [\mathbf{w}_{i,l}]_{i,l} : \mathbf{w}_{i,l} = \gamma_{i,l}^{w} Unif(-a_{w}, a_{w}) + (1 - \gamma_{i,l}^{w})\delta_{0}$ $\mathbf{U} = [u_{i,j}]_{i,j} : u_{i,j} = \gamma_{i,j}^u Unif(-a_u, a_u) + (1 - \gamma_{i,j}^u)\delta_0$ $\gamma_{i,l}^{w} \sim Bern(\pi_{w}); \gamma_{i,i}^{u} \sim Bern(\pi_{u})$

Feature Importance with ESN

Objective Determine importance of time t on forecast at time t + c (c > 0) Current implementation Apply concept of PFI by permuting input observations at time t and comparing model performance for forecasts at time t + c

Models

- Quadratic echo state network for initial development
- Response Variable: Temperature at given pressue level
- Predictor Variables: Lagged temperatures at given pressure level
- Training Data: Monthly observations in 1979-1990
- Testing Data: Monthly observations in 1991-1992
- \blacktriangleright Preprocessing: For a given pressure level, let $y_{loc, year, month}$ be temperature at a spatial location, year, and month:
- ► None: *y*_{loc,year,month}
- ► Centered: $y_{loc, year, month} \bar{y}_{loc}$ where \bar{y}_{loc} is average temperature at a spatial location over all times (years and months)
- ► Climatology: $y_{loc, year, month} \bar{y}_{loc, month}$ where $\bar{y}_{loc, month}$ is average temperature at a spatial location and month over all years

Climate Forecasting





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