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The *Albany/FELIX* First-Order Stokes Finite Element Ice Sheet Dynamical Core Built Using Trilinos Software Components: Performance, Next-Generation Capabilities and Validation

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PISCEES* Project for Land-Ice Modeling



Sandia's Role in the PISCEES Project: to develop and support a robust and scalable land ice solver based on the "First-Order" (FO) Stokes equations → Albany/FELIX**

Requirements for Albany/FELIX:

- Unstructured grid finite elements.
- Scalable, fast and robust
- Verified and validated.
- Portable to new/emerging architecture machines (multi-core, many-core, GPU)
- *Advanced analysis* capabilities: deterministic inversion, calibration, uncertainty quantification.

As part of **ACME DOE earth system model**, solver will provide actionable predictions of 21st century sea-level rise (including uncertainty).

**Finite Elements for Land Ice eXperiments



*PISCEES = Predicting Ice Sheet Climate Evolution at Extreme Scales.

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- 1. Ice Sheet Equations and Codes.
- 2. Mesh Adaptivity.
- 3. Scalability.
- 4. Performance Portability.
- 5. Validation.
- 6. Summary and Future Work.















Ice Sheet Equations and Codes



Momentum Balance: First-Order Stokes PDEs

$$\begin{cases} -\nabla \cdot (2\mu \dot{\boldsymbol{\epsilon}}_1) = -\rho g \frac{\partial s}{\partial x} \\ -\nabla \cdot (2\mu \dot{\boldsymbol{\epsilon}}_2) = -\rho g \frac{\partial s}{\partial y} \end{cases}, \quad \text{in } \Omega$$

with **Glen's law** viscosity $\mu = \frac{1}{2}A(T)^{-\frac{1}{3}} \left(\frac{1}{2}\sum_{ij} \dot{\epsilon}_{ij}^2\right)^{\left(-\frac{2}{3}\right)}$.

Conservation of Mass: thickness evolution PDE

$$\frac{\partial h}{\partial t} = -\nabla \cdot (\overline{\boldsymbol{u}}h) + \dot{b}$$

Energy Balance: temperature advection-diffusion PDE

$$\rho c \frac{\partial T}{\partial t} = \nabla \cdot (k \nabla T) - \rho c \boldsymbol{u} \cdot \nabla T + 2 \dot{\boldsymbol{\epsilon}} \boldsymbol{\sigma}$$

Ice Sheet Equations and Codes



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*https://github.com/gahansen/Albany. **FELIX = Finite Elements for Land Ice eXperiments.

(2)

Ice Sheet Equations and Codes





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Why?



Sandia National Laboratories

Why?

To *concentrate* computational power where it is needed.



How?





How?

PAALS = Parallel Albany Adaptive Loop with SCOREC









New capability for

land-ice solver!

How?

PAALS = Parallel Albany Adaptive Loop with SCOREC*

In collaboration with *Rensselaer Polytechnical Institute* (M. Shephard, C. Smith, D. Ibanez): added mesh adaptation capabilities (PAALS) to *Albany.*

**SCOREC* = Scientific Computation Research Center at RPI: https://github.com/SCOREC







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- Predictive dynamic load balancing via ParMetis/Zoltan + ParMA.
- SPR**-based generalized *error estimation* of *velocity gradient* drives adaptation.



**Super-convergent Patch Recovery: technique for estimating abla u using quadratic approximation within a patch of elements.

Parallel Adaptive Loop with SCOREC (PAALs) Sandia Laboratories



Dynamic Load Balancing

- Partition via Zoltan or ParMetis + ParMA.
- Libraries/Algorithms:
 - **ParMetis**: multi-level graph partitioning \rightarrow minimizes communication
 - **Zoltan**: Recursive Inertial Bisection (RIB) \rightarrow faster than graph partitioning
 - **ParMA**: Unstructured mesh-based diffusive improvement \rightarrow rebalances refined mesh



Left: Initial ParMetis/Zoltan partition Right: ParMA partition



PAALS = Parallel Albany Adaptive Loop with SCOREC

• <u>Step 1</u>: determine geometry and generate initial tetrahedral mesh (e.g., using *Triangle* or *Simmetrix*).

offline

online

- <u>Step 2</u>: 2D slice of initial mesh *adaptively refined in-memory* via *PAALS* based on gradient of velocity in *Albany*.
- <u>Step 3</u>: 3D mesh obtained by extruding 2D mesh vertically as prisms or tetrahedra in Albany.





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 PAALS adaptive loop driven by *homotopy continuation* using *LOCA* package in *Trilinos*.











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- PAALS adaptive loop driven by *homotopy continuation* using *LOCA* package in *Trilinos*.
- Currently adaptation is done in *stand-alone* Albany.
- <u>Future work</u>: integrating adaptation into *dynamical cores* (*MPAS- Albany*).







Rensselaer



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Why is scalability so **bad** for out-of-the-box preconditioners?

- 1. Ice sheet geometries have **bad aspect ratios** $(dx \gg dz)$.
- 2. Ice shelves give rise to severely ill-conditioned matrices.
- 3. Islands and hinged peninsulas lead to solver failures.





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<u>Why is scalability so **bad** for out-of-the-box preconditioners?</u> 1. Ice sheet geometries have **bad aspect ratios** $(dx \gg dz)$.

- 2. *Ice shelves* give rise to *severely ill-conditioned* matrices.
- 3. Islands and hinged peninsulas lead to solver failures.

We **<u>mitigate</u>** these difficulties through the development of:

- New AMG preconditioner based on semi-coarsening.
- Island/hinge removal algorithm.

Scalability via Algebraic Multi-Grid Preconditioning with Semi-Coarsening



Bad aspect ratios $(dx \gg dz)$ ruin classical AMG convergence rates!

- relatively small horizontal coupling terms, hard to smooth horizontal errors
- \Rightarrow Solvers (AMG and ILU) must take aspect ratios into account

We developed a **new AMG solver** based on aggressive **semi-coarsening** (available in *ML/MueLu* packages of *Trilinos*)





See (Tezaur *et al.,* 2015), (Tuminaro *et al.,* 2016). Scaling studies (next slides): New AMG preconditioner vs. ILU

Greenland Controlled Weak Scalability Study



- Weak scaling study with fixed dataset, 4 mesh bisections.
- ~70-80K dofs/core.
- Conjugate Gradient (CG) iterative method for linear solves (faster convergence than GMRES).
- New AMG preconditioner developed by R. Tuminaro based on *semi-coarsening* (coarsening in *z*-direction only).
- *Significant improvement* in scalability with new AMG preconditioner over ILU preconditioner!

Greenland Controlled Weak Scalability Study



Moderate Resolution Antarctica Weak Scaling Study

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Antarctica is fundamentally different than Greenland: AIS contains large ice shelves (floating extensions of land ice).

- Along ice shelf front: open-ocean BC (Neumann).
- Along ice shelf base: zero traction BC (Neumann).

⇒ For vertical grid lines that lie within ice shelves, top and bottom BCs resemble Neumann BCs so sub-matrix associated with one of these lines is almost* singular.



⇒ Ice shelves give rise to severe illconditioning of linear systems!





*Completely singular in the presence of islands and some ice tongues.

Moderate Resolution Antarctica Weak Scaling Study

- Weak scaling study on Antarctic problem (8km w/ 5 layers \rightarrow 2km w/ 20 layers).
- Initialized with realistic basal friction (from deterministic inversion) and temperature field from BEDMAP2.
- Iterative linear solver: GMRES.
- **Preconditioner**: ILU vs. new AMG based on aggressive semi-coarsening.





Improved Linear Solver Performance through Removal of Hinged Peninsulas



Islands and certain hinged peninsulas lead to **solver failures**



- We have developed an algorithm to detect/remove problematic hinged peninsulas & islands based on coloring and repeated use of connected component algorithms (Tuminaro et al., 2016).
- Solves are ~2x faster with hinges removed.
- Current implementation is MATLAB, but working on C++ implementation for integration into dycores.



Resolu-	ILU –	ILU – no	ML –	ML – no	
tion	hinges	hinges	hinges	hinges	
8km/5	878 sec,	693 sec,	254 sec,	220 sec,	
layers	84 iter/solve	71 iter/solve	11 iter/solve	9 iter/solve	
4km/10	1953 sec,	1969 sec,	285 sec,	245 sec,	
layers	160 iter/solve	160 iter/solve	13 iter/solve	12 iter/solve	
2km/20	10942 sec,	5576 sec,	482 sec,	294 sec,	
layers	710 iter/solve	426 iter/solve	24 iter/solve	15 iter/solve	
1km/40 layers		15716 sec, 881 iter/solve	668 sec, 34 iter/solve		







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MPI (task parallelism) + X* (thread + data-level parallelism)

- Kokkos: open-source library that provides performance portability across diverse devises with different memory models.
 - A *programming model* as much as a software library.
 - Provides automatic access to OpenMP, CUDA, Pthreads, ...
 - Templated meta-programming: parallel_for, parallel_reduce (templated on an *execution space*).
 - Memory layout abstraction ("array of structs" vs. "struct of arrays", locality).

With *Kokkos*, you write an algorithm **once**, and just change a template parameter to get the optimal data layout for your hardware (e.g., (i,j,k) vs. (k,i,j).





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- Finite element assembly in Albany has recently been rewritten using Kokkos functors.
- Linear solvers in *Belos* package of *Trilinos* can run on next-generation platforms with simple preconditioners (Jacobi, Gauss-Seidel, Chebyshev, ILU).





Kokkos-ification of Finite Element Assembly

```
typedef Kokkos::OpenMP ExecutionSpace;
//typedef Kokkos::CUDA ExecutionSpace;
//typedef Kokkos::Serial ExecutionSpace;
template<typename ScalarT>
vectorGrad<ScalarT>::vectorGrad()
Kokkos::View<ScalarT****, ExecutionSpace> vecGrad("vecGrad", numCells, numOP, numVec, numDim);
3
              *******
template<typename ScalarT>
void vectorGrad<ScalarT>::evaluateFields()
{
  Kokkos::parallel for<ExecutionSpace> (numCells, *this);
template<typename ScalarT>
KOKKOS INLINE FUNCTION
                                                                ExecutionSpace parameter
void vectorGrad<ScalarT>:: operator() (const int cell) const
                                                               tailors code for device (e.g.,
  for (int cell = 0; cell < numCells; cell++)
                                                                  OpenMP, CUDA, etc.)
  for (int qp = 0; qp < numQP; qp++) {
   for (int dim = 0; dim < numVec; dim++) {</pre>
      for (int i = 0; i < numDim; i++) {
       for (int nd = 0; nd < numNode; nd++) {
         vecGrad(cell, qp, dim, i) += val(cell, nd, dim) * basisGrad(nd, qp, i);
```

Results on *Shannon*: 4km Greenland & 8km Antarctica Problems





Results on *Titan*: Weak Scalability for Greenland (8km, 4km, 2km, 1km)





- CUDA implementation is *slower* than MPI-only for total time but *faster* for compute time (due to communication costs).
- Filling the matrix requires use of *atomics*, which are difficult to optimize (work in progress by *Kokkos* team).
- Work is *distributed more thinly* on *Titan* than on *Shannon* → worse for GPU (less work, more communications).

Titan: 18,688 AMD Opteron nodes

- 16 cores per node
- 1 K20X Kepler GPUs per node
- 32GB + 6GB memory per node

3. Scalability.

5. Validation.







Validation*: how well does our model represent the real ice sheet?

*vs. verification: is our code bug free? (some of my past SIAM talks on PISCEES)



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• There are currently (up to) 2 decades of large-scale *satellite* observations of Greenland ice sheet geometry change:

ICESat1	2003 – 2009
GRACE	2002 – 201? (ongoing)





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ICESat1	2017-20??
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GRACE2	2020s-?



Validation Workflow:

- Run ice sheet model over period where ICESat/GRACE observations exist.
- Process model output for comparison to these observations.
- Process observations for comparison to model output.
- Evaluate model performance relative to observations.
 - ICESat: ice sheet surface elevation [state comparison]
 - **GRACE**: rate of mass change [trend comparison]

*vs. verification: is our code bug free? (some of my past SIAM talks on PISCEES)

Validation: Observations & Forcing

Validation time period:

- ICESat: 2003-2009
- GRACE: 2003-2011 (CSR Release-05)
- Model forcing: the following datasets taken as "truth"
 - Monthly *surface mass balance* (SMB) from RACMO2¹ anomalies applied (1960-present)
 - Well-validated over Greenland
 - Mean-annual outlet glacier flux² applied at grounding line (1990-present)
 - Figure below: outlet glacier *flux forcing (FF)* time series



<u>Code</u>: CISM-Albany (CISM2.0 + Albany/FELIX)

¹ van Angelen et al. (*Surv. Geophys.*, 2013) ² Enderlin et al. (*GRL*, 2014)



Validation: 1km GIS initial condition*



*Initial condition obtained through *deterministic inversion*; see talk by M. Perego.



Validation: Surface Elevation Observations



- Model evaluated: CISM-Albany with SMB + FF in October 2007.
- Surface elevation predictions (states) agree pretty well with *GLAS* (*Geoscience Laser Altimeter System aboard ICESat*): *mean differences* are <1 m



Validation: Whole Ice Sheet Mass Trends





- Overall mass trends from the CISM-Albany simulations look fairly realistic (left figure, red & blue)
- **CISM-Albany** trends look **more realistic** (closer to observations; right figure) than the "idealized" simulations (left figure, pink & black).
- There is *more mass loss* from the simulation when we account for changes in outlet glacier flux (i.e., the evolution of the ice sheet is not only forced by surface mass balance changes, but also be changes in outlet glacier dynamics).

¹Geometry held constant in time. ²RACMO2 SMB time series applied to dh/dt; includes SS "discharge" using 1960-1990 mean SMB.

Validation: Whole Ice Sheet Mass Trends





- *Apples-to-apples* comparison between models and GRACE:
 - Information is all on the *same plot*.
 - Model output and observations were both *processed in the same way.*

Validation Takeaways



Current generation ice sheet models, *when appropriately forced*, show *skill* at mimicking ice sheet observations

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Current generation ice sheet models, <u>when appropriately</u> <u>forced</u>, show skill at mimicking ice sheet observations

• **Clear improvement over a decade ago:** SLR projections from ice sheet models were not included in the IPCC's AR4 b/c models could not explain observed ice dynamical behaviors.

Validation Takeaways



Current generation ice sheet models, *when appropriately forced*, show *skill* at mimicking ice sheet observations

- *Clear improvement over a decade ago:* SLR projections from ice sheet models were not included in the IPCC's AR4 b/c models could not explain observed ice dynamical behaviors.
- For more details on validation study, see our *GMD paper*, currently under review.

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Cryospheric Model Comparison Tool (CmC

 Validation work involved development of new ice sheet model validation framework – the Cryospheric Model Comparison Tool (CmCt) – which includes proposed qualitative and quantitative metrics for use in comparing models to observations.



CmCt is **online** and ready for testing by community

https://ggsghpcc.sgtinc.com/cmct/





Summary and Future Work



Summary:

- We have developed a land-ice solver known as **Albany/FELIX** using **Trilinos** libraries.
- This solver is:
 - Equipped with in-memory parallel *unstructured mesh adaption*.
 - Scalable, fast, robust.
 - Coupled to CISM and MPAS codes for **dynamic** runs and integration into ESMs.
 - Verified and validated.
 - *Portable* to new and emerging architecture machines.
 - Equipped with *advanced analysis capabilities* (deterministic inversion, UQ).

Ongoing/future work:

- Mesh adaptivity for transient runs.
- Integration of *hinge removal algorithm* into *transient* runs.
- Science runs using CISM-Albany and MPAS-Albany.
- Code optimizations for *new architecture machines* (GPUs, multi-core, many-core).
- Uncertainty quantification (not covered in this talk).
- Delivering code to climate community and *coupling to ESMs*.





Thank you! Questions?





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 Computing resources: NERSC, OLCF.

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PISCEES Project for Land-Ice Modeling





Unstructured Mesh Generation & Adaptiv

Original approach:

offline

online

offline

online

Parallel Unstructured Mesh Infrastru

- **<u>Step 1</u>**: geometry boundary and possible holes determined in **MATLAB**
- <u>Step 2</u>: uniform triangular mesh is generated and refined based on surface velocity gradient in Triangle (2D meshing software)
- <u>Step 3</u>: 3D mesh obtained by extruding 2D mesh vertically as *prisms*, then splitting each prism into 3 *tetrahedra (Albany)*.

New approach: Parallel Albany Adaptive Loop with SCOREC* (PAALS)

- **<u>Step 1</u>**: geometry determined from *.nc file using *scripts*.
- <u>Step 2</u>: uniform tetrahedral mesh generated (using *Triangle* or *Simmetrix*).
 - <u>Step 3</u>: 2D slice of initial mesh adaptively refined via *in-memory Parallel Albany Adaptive Loop with SCOREC* (*PAALS*).
 - <u>Step 4</u>: 3D mesh obtained by extruding 2D mesh vertically as *prisms* in *Albany*.





*Scientific Computation Research Center at Rensselaer Polytechnic Institute (RPI); https://github.com/SCOREC

Fine-Resolution Greenland Strong Scaling

- Strong scaling on 1km Greenland with 40 vertical layers (143M dofs, hex elements).
- Initialized with realistic basal friction (from deterministic inversion) and temperature fields → interpolated from coarser to fine mesh.
- Iterative linear solver: CG.
- **Preconditioner**: ILU vs. new AMG (based on aggressive semi-coarsening).





beta

150

10

0.1

0.01

ILU solver scales better than AMG but ILU solve is slightly slower: AMG solver becomes inefficient when # unknowns/core small (expensive setup; a lot of communications).

Validation - Total Mass Change 2003-2012



