

An Update on the Albany/FELIX First-Order Stokes Finite Element Solver & Its Coupling to Land Ice Dycores

Irina Kalashnikova, Andy Salinger, Mauro Perego, Ray Tuminaro, Steve Price

In collaboration with Matt Hoffman, Doug Ranken, Kate Evans, Pat Worley, Matt Norman, Mike Eldred, John Jakeman and Irina Demeshko.

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PISCEES Project & the Albany/FELIX First-Order Stokes Dycore

To **develop** and **support** a robust and scalable unstructured grid finite element land ice dycore based on the "first-order" (FO) Stokes physics →*Albany/FELIX dycore*

- Finite element method.
- Parallel, unstructured grid with *partitioning*.
- Automatic differentiation for (exact) Jacobians.
- Globalized Newton's method nonlinear solver.
- Preconditioned (ILU or algebraic multigrid) iterative Krylov linear solvers.
- *Performance-portable kernels* to run on new architecture machines / GPUs (in progress).
- Analysis tools: UQ, sensitivity analysis, optimization.
- *Software tools*: git / cmake / ctest / jenkins.







First Order Stokes Model $\begin{cases}
-\nabla \cdot (2\mu\dot{\epsilon}_1) = -\rho g \frac{\partial s}{\partial x} \\
-\nabla \cdot (2\mu\dot{\epsilon}_2) = -\rho g \frac{\partial s}{\partial y}
\end{cases}$





Code Verification and Performance

 Implementation of PDEs + BCs (no-slip, stress-free, basal sliding, open-ocean) has been *verified* through MMS tests (right) and code-to-code comparisons (confined-shelf, below).



Robust nonlinear solves (Newton converges out-of-the-box!) with homotopy continuation of γ in Glen's law viscosity:

$$\mu = \frac{1}{2} A^{-\frac{1}{n}} \left(\frac{1}{2} \sum_{ij} \dot{\epsilon}_{ij}^{2} + \gamma \right)^{\left(\frac{1}{2n} - \frac{1}{2}\right)}$$



Dycore Interfaces and Meshes



We support several full *mesh/data* (geometry, topography, surface height, basal traction, temperature, etc.) import methods: ***.exo**, **ASCII** (stand-alone Albany), ***.nc** (Dycore-Albany);

Steady Runs Using Dycore Interfaces



Regional Refinement (work-inprogress using MPAS LI)



Mesh Details Min *h*: 4 km Max *h*: 15 km 32K nodes



- Step 1: determine geometry boundaries and possible holes (MATLAB).
- <u>Step 2:</u> generate uniform triangular mesh and refine based on *gradient of measured surface velocity (Triangle – a 2D meshing software).*
- <u>Step 3:</u> obtain 3D mesh by extruding the 2D mesh in the vertical direction as *prism*, then splitting each prism into 3 *tetrahedra (Albany)*.

Courtesy of: M. Perego (SNL)



Dynamic Runs Using Dycore Interfaces (work-in-progress)



Greenland Mesh Convergence Study

Full 3D Mesh-Convergence Study

Are the GIS problems resolved? Is theoretical convergence rate achieved?



 Full 3D mesh convergence study (uniform refinement, fixed data w.r.t. reference solution) for GIS gives theoretical convergence rate of 2 in L² norm.

z Mesh-Convergence Study

How many vertical layers are needed?

# z layers/ # cores	# dofs	Total Time – Mesh Import	Solution Average	Error
5/128	21.0M	519.4 sec	2.827	3.17e-2
10/256	38.5M	525.4 sec	2.896	8.04e-3
20/512	73.5M	499.8 sec	2.924	2.01e-3
40/1024	143M	1282 sec	2.937	4.96e-4
80/2048	283M	1294 sec	2.943	1.20e-4
160/4096	563M	1727 sec	2.945	2.76e-5

- z mesh-convergence study for 1 km GIS.
- Important to do partition of 2D mesh for parallel refined mesh (center).
- QOI (solution average) does change with *z*-refinement.

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Greenland Controlled Weak Scalability Study



- Weak scaling study with fixed dataset, 4 mesh bisections.
- ~70-80K dofs/core.
- Conjugate Gradient (CG) iterative method for linear solves (faster convergence than GMRES).
- New algebraic multigrid preconditioner (ML) developed by R. Tuminaro based on semicoarsening (coarsening in zdirection only).
- *Significant improvement* in scalability with new ML preconditioner over ILU preconditioner!



Greenland Controlled Weak Scalability Study

In collaboration with: R. Tuminaro (SNL)



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Deterministic Inversion: Estimation of Ice Sheet Initial State

First-Order Stokes PDE Constrained Optimization Problem:

$$J(\beta, H) = \frac{1}{2}\alpha \int_{\Gamma} |div(\boldsymbol{U}H) - SMB|^2 ds + \frac{1}{2}\alpha_v \int_{\Gamma top} |\boldsymbol{u} - \boldsymbol{u}^{obs}|^2 ds + \frac{1}{2}\alpha_H \int_{\Gamma top} |H - H^{obs}|^2 ds + \mathcal{R}(\beta) + \mathcal{R}(H)$$

- Minimize difference between:
 - Computed divergence flux and measured *surface mass balance (SMB)*.
 - Computed and measured surface velocity (u^{obs}).
 - Computed and *reference thickness (H^{obs})*.
- Control variables:

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- Basal friction (β).
- Thickness (H).
- Software tools: *LifeV* (assembly), *Trilinos* (linear/nonlinear solvers), *ROL* (gradient-based optimization).

Courtesy of: M. Perego (SNL); S. Price (LANL); G. Stadler (UT) Estimated divergence (left) vs. reference SMB (right)





Estimated (left) vs. reference surface velocity (right)



Bayesian Inversion/Uncertainty Quantification (work-in-progress)

With:

J. Jakeman,

Difficulty in UQ: "Curse of Dimensionality" The β -field inversion problem has O(20,000) dimensions!

Step 1: Model reduction (from O(20,000) parameters to O(5) parameters) using **Karhunen-Loeve Expansion** (or *eigenvectors of Hessian*, in future) of basal sliding field:

$$log(\beta(\omega)) = \bar{\beta} + \sum_{k=1}^{K} \sqrt{\lambda_k} \boldsymbol{\phi}_k \xi_k(\omega)$$

- Step 2: Polynomial Chaos Expansion (PCE) emulator for mismatch over surface velocity discrepancy.
- Step 3: Markov Chain Monte Carlo (MCMC) calibration using PCE emulator.











Conversion to Performance-Portable Kernels (work-in-progress)

We need to be able to run Albany/FELIX on *new architecture machines* (hybrid systems) and *manycore devices* (multi-core CPU, NVIDIA GPU, Intel Xeon Phi, etc.).

- *Kokkos*: Trilinos C++ library that provides performance portability across diverse devises with different memory models.
- With Kokkos, you write an algorithm once, and just change a template parameter to get the optimal data layout for your hardware.
- Albany/FELIX *finite element* assembly has been converted to Kokkos functors in Albany/FELIX MiniDriver (I. Demeshko).

Albany/FELIX MiniDriver, 20 km GIS





Summary and Future Work

Summary:

- Albany/FELIX first-order Stokes dycore can be run on Greenland/Antarctica problems discretized by several kinds of meshes and is nearly ready for science.
- The Albany/FELIX dycore has been hooked up to the CISM and MPAS codes.
- Convergence, scalability and robustness of the Albany/FELIX code has been verified.

Verification, Greenland/Antarctica runs, scalability, robustness, UQ, advanced analysis, performance-portability: all attained in **~2 FTE of effort**!

Ongoing/future work:

- Mature dynamic evolution capabilities.
- Perform deterministic and stochastic initialization runs.
- Finish conversion to performance-portable kernels.
- Journal article on Albany/FELIX (I. Kalashnikova, A. Salinger, M. Perego, R. Tuminaro, S. Price, M. Hoffman).
- Delivering code to users in climate community.
- Coupling to an earth system model (ESM).



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Trilinos/Dakota collaborators: E. Phipps, M. Eldred, J. Jakeman, L. Swiler.







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